

# Min-max theory for noncompact manifolds and three-spheres with unbounded widths

Rafael Montezuma

July 11, 2016



Advisor: Fernando Codá Marques

# Min-max constructions: Background

# Min-max constructions: Background

- Birkhoff (1917): closed geodesics in  $(S^2, g)$ .

# Min-max constructions: Background

- Birkhoff (1917): closed geodesics in  $(S^2, g)$ .
- Lusternik-Schnirelmann (1940s): 3 closed geodesics.

# Min-max constructions: Background

- Birkhoff (1917): closed geodesics in  $(S^2, g)$ .
- Lusternik-Schnirelmann (1940s): 3 closed geodesics.
- Almgren (1960s): general theory, uses G.M.T.

# Min-max constructions: Background

- Birkhoff (1917): closed geodesics in  $(S^2, g)$ .
- Lusternik-Schnirelmann (1940s): 3 closed geodesics.
- Almgren (1960s): general theory, uses G.M.T.
- Pitts (1970-80s): hypersurfaces in lower dimensions ( $n \leq 6$ ).

# Min-max constructions: Background

- Birkhoff (1917): closed geodesics in  $(S^2, g)$ .
- Lusternik-Schnirelmann (1940s): 3 closed geodesics.
- Almgren (1960s): general theory, uses G.M.T.
- Pitts (1970-80s): hypersurfaces in lower dimensions ( $n \leq 6$ ).
- Schoen-Simon (1981): hypersurfaces in arbitrary dimension, curvature estimates for stable minimal hypersurfaces.

# Min-max constructions: Background

- Birkhoff (1917): closed geodesics in  $(S^2, g)$ .
- Lusternik-Schnirelmann (1940s): 3 closed geodesics.
- Almgren (1960s): general theory, uses G.M.T.
- Pitts (1970-80s): hypersurfaces in lower dimensions ( $n \leq 6$ ).
- Schoen-Simon (1981): hypersurfaces in arbitrary dimension, curvature estimates for stable minimal hypersurfaces.
- Simon-Smith (1982): continuous setting and topological bounds. Every  $(S^3, g)$  contains embedded minimal  $S^2$ .



# Min-max constructions: Background

- Birkhoff (1917): closed geodesics in  $(S^2, g)$ .
- Lusternik-Schnirelmann (1940s): 3 closed geodesics.
- Almgren (1960s): general theory, uses G.M.T.
- Pitts (1970-80s): hypersurfaces in lower dimensions ( $n \leq 6$ ).
- Schoen-Simon (1981): hypersurfaces in arbitrary dimension, curvature estimates for stable minimal hypersurfaces.
- Simon-Smith (1982): continuous setting and topological bounds. Every  $(S^3, g)$  contains embedded minimal  $S^2$ .
- Colding-de Lellis (2003): survey on min-max constructions.

# Min-max constructions: Background

- Birkhoff (1917): closed geodesics in  $(S^2, g)$ .
- Lusternik-Schnirelmann (1940s): 3 closed geodesics.
- Almgren (1960s): general theory, uses G.M.T.
- Pitts (1970-80s): hypersurfaces in lower dimensions ( $n \leq 6$ ).
- Schoen-Simon (1981): hypersurfaces in arbitrary dimension, curvature estimates for stable minimal hypersurfaces.
- Simon-Smith (1982): continuous setting and topological bounds. Every  $(S^3, g)$  contains embedded minimal  $S^2$ .
- Colding-de Lellis (2003): survey on min-max constructions.
- Colding-Minicozzi (2000s): finite time extinction of RF.

# Min-max constructions: Background

- Birkhoff (1917): closed geodesics in  $(S^2, g)$ .
- Lusternik-Schnirelmann (1940s): 3 closed geodesics.
- Almgren (1960s): general theory, uses G.M.T.
- Pitts (1970-80s): hypersurfaces in lower dimensions ( $n \leq 6$ ).
- Schoen-Simon (1981): hypersurfaces in arbitrary dimension, curvature estimates for stable minimal hypersurfaces.
- Simon-Smith (1982): continuous setting and topological bounds. Every  $(S^3, g)$  contains embedded minimal  $S^2$ .
- Colding-de Lellis (2003): survey on min-max constructions.
- Colding-Minicozzi (2000s): finite time extinction of RF.
- Marques-Neves: rigidity of min-max spheres in 3-manifolds, Willmore Problem and infinitely many closed, embedded, minimal hypersurfaces in manifolds with  $Ric > 0$ .

# Min-max constructions: Background

- Birkhoff (1917): closed geodesics in  $(S^2, g)$ .
- Lusternik-Schnirelmann (1940s): 3 closed geodesics.
- Almgren (1960s): general theory, uses G.M.T.
- Pitts (1970-80s): hypersurfaces in lower dimensions ( $n \leq 6$ ).
- Schoen-Simon (1981): hypersurfaces in arbitrary dimension, curvature estimates for stable minimal hypersurfaces.
- Simon-Smith (1982): continuous setting and topological bounds. Every  $(S^3, g)$  contains embedded minimal  $S^2$ .
- Colding-de Lellis (2003): survey on min-max constructions.
- Colding-Minicozzi (2000s): finite time extinction of RF.
- Marques-Neves: rigidity of min-max spheres in 3-manifolds, Willmore Problem and infinitely many closed, embedded, minimal hypersurfaces in manifolds with  $Ric > 0$ .
- Many others: Ketover, Pellandini, Tasnady, Li, Zhou, ...

# Part 1: Minimal hypersurfaces in noncompact manifolds

There is no closed minimal hypersurface in  $\mathbb{R}^n$ .

# Part 1: Minimal hypersurfaces in noncompact manifolds

There is no closed minimal hypersurface in  $\mathbb{R}^n$ .

Need extra assumptions!

- Every **complete Riemannian surface of finite area** and homeomorphic to either the plane, or the cylinder or the Möbius band admits infinitely many closed geodesics.

(Bangert, 1980)

# Part 1: Minimal hypersurfaces in noncompact manifolds

There is no closed minimal hypersurface in  $\mathbb{R}^n$ .

Need extra assumptions!

- Every **complete Riemannian surface of finite area** and homeomorphic to either the plane, or the cylinder or the Möbius band admits infinitely many closed geodesics.

(Bangert, 1980)

**Our assumptions:** Let  $(N^n, g)$  be a complete non-compact Riemannian manifold.

- Bangert's condition: complete Riemannian surfaces of finite area have **bounded, mean-concave subsets**.
- We say that  $N$  has the  $\star_k$ -**condition** if there exist  $p \in N$  and  $R_0 > 0$ , such that, for every  $R \geq R_0$ ,

$$\sup_{q \in B(p, R)} |\text{Sec}_N|(q) \leq R^k \quad \text{and} \quad \inf_{q \in B(p, R)} \text{inj}_N(q) \geq R^{-\frac{k}{2}}.$$

## Theorem A (—)

Let  $(N^n, g)$  be a complete non-compact Riemannian manifold of dimension  $n \leq 7$ . Suppose:

- $N$  has a bounded and strictly mean-concave open subset  $\Omega$ ;
- $N$  satisfies the  $\star_k$ -condition, for some  $k \leq \frac{2}{n-2}$ .

Then, there exists a closed embedded minimal hypersurface  $\Sigma^{n-1} \subset N$  that intersects  $\Omega$ .



## Theorem A (—)

Let  $(N^n, g)$  be a complete non-compact Riemannian manifold of dimension  $n \leq 7$ . Suppose:

- $N$  has a bounded and strictly mean-concave open subset  $\Omega$ ;
- $N$  satisfies the  $\star_k$ -condition, for some  $k \leq \frac{2}{n-2}$ .

Then, there exists a closed embedded minimal hypersurface  $\Sigma^{n-1} \subset N$  that intersects  $\Omega$ .

## Remarks:

- $\Sigma^{n-1}$  is a min-max minimal hypersurface.

## Theorem A (—)

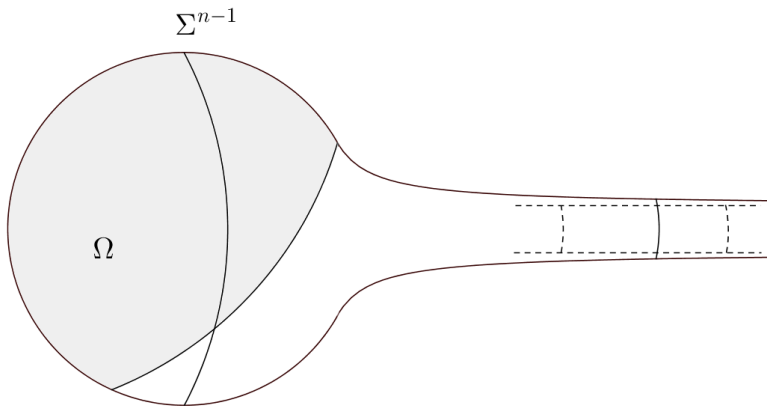
Let  $(N^n, g)$  be a complete non-compact Riemannian manifold of dimension  $n \leq 7$ . Suppose:

- $N$  has a bounded and strictly mean-concave open subset  $\Omega$ ;
- $N$  satisfies the  $\star_k$ -condition, for some  $k \leq \frac{2}{n-2}$ .

Then, there exists a closed embedded minimal hypersurface  $\Sigma^{n-1} \subset N$  that intersects  $\Omega$ .

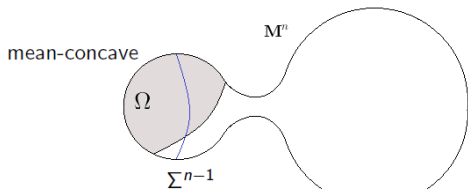
## Remarks:

- $\Sigma^{n-1}$  is a min-max minimal hypersurface.
- Collin, Hauswirth, Mazet and Rosenberg proved that any complete non-compact hyperbolic three-dimensional manifold of finite volume admits a closed, embedded minimal surface.



**Figure:** A non-compact Riemannian manifold, asymptotic to a cylinder and containing a mean-concave open set  $\Omega$ . In this case, the theorem could be applied.

## Theorem B (—)



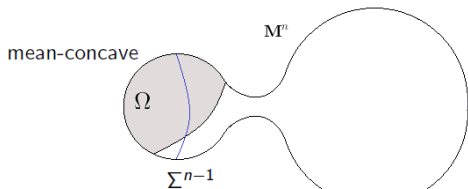
(minimal hypersurface)

(possibly disconnected and with multiplicities)

$$\|\Sigma\|(M) = \mathbf{L}(\Pi, \Omega)$$

MIN-MAX HYPERSURFACE

## Theorem B (—)



(minimal hypersurface)

(possibly disconnected and with multiplicities)

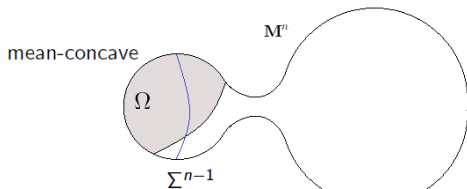
$$\|\Sigma\|(M) = \mathbf{L}(\Pi, \Omega)$$

MIN-MAX HYPERSURFACE

### Remarks:

- $\mathbf{L}(\Pi, \Omega)$  is the new min-max invariant.

## Theorem B (—)



(minimal hypersurface)

(possibly disconnected and with multiplicities)

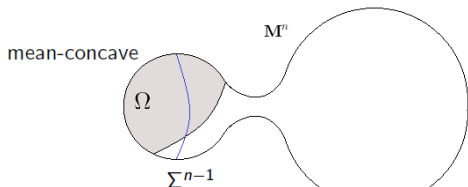
$$\|\Sigma\|(M) = \mathbf{L}(\Pi, \Omega)$$

MIN-MAX HYPERSURFACE

### Remarks:

- $\mathbf{L}(\Pi, \Omega)$  is the new min-max invariant.
- $\mathbf{L}(\Pi, M) = \mathbf{L}(\Pi)$ .

## Theorem B (—)



(minimal hypersurface)

(possibly disconnected and with multiplicities)

$$\|\Sigma\|(M) = \mathbf{L}(\Pi, \Omega)$$

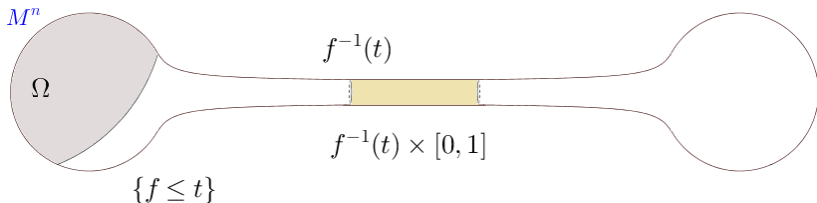
MIN-MAX HYPERSURFACE

### Remarks:

- $\mathbf{L}(\Pi, \Omega)$  is the new min-max invariant.
- $\mathbf{L}(\Pi, M) = \mathbf{L}(\Pi)$ .
- Optimal with respect to the intersecting property.

# Proof of Theorem A

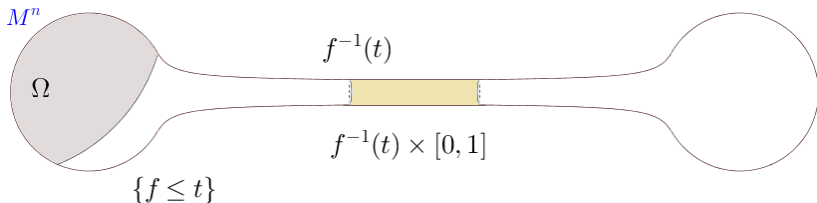
- (1) Let  $f : N \rightarrow [0, \infty]$  be a Morse function and  $t > 0$  such that  $\Omega \subset \{f \leq t\}$ . Let  $M^n$  be a closed manifold containing an isometric copy of  $\{f \leq t\}$ .





# Proof of Theorem A

- (1) Let  $f : N \rightarrow [0, \infty]$  be a Morse function and  $t > 0$  such that  $\Omega \subset \{f \leq t\}$ . Let  $M^n$  be a closed manifold containing an isometric copy of  $\{f \leq t\}$ .



- (2) Apply **Theorem B** to obtain a closed, embedded, minimal hypersurface  $\Sigma^{n-1} \subset M$ , that intersects  $\Omega$  and with

$$\mathcal{H}^{n-1}(\Sigma) \leq \mathbf{L}(\Pi, \Omega).$$

Moreover,  $\mathbf{L}(\Pi, \Omega)$  has an upper bound which does not depend on  $t$ .

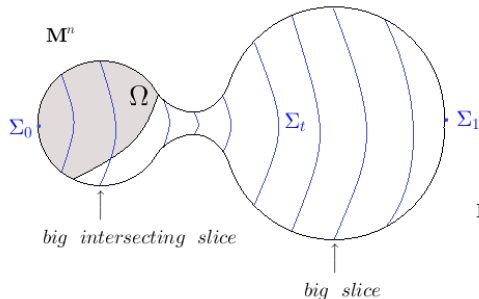
- (3) If  $t$  is large, the **polynomial decay of the geometry at infinity** implies that

$$\Sigma \subset \{f \leq t\}.$$

In particular,  $\Sigma$  is a minimal hypersurface in the original manifold  $N$ .

# Min-max theory for intersecting slices

**Sweepout:** Continuous one-parameter family of closed, oriented hypersurfaces (possibly with finitely many singularities).



$$S = \{\Sigma_t\}_{t \in [0,1]}$$

(sweepout)

$$\mathbf{L}(S, \Omega) = \max\{\mathcal{H}^{n-1}(\Sigma_t) : \Sigma_t \cap \bar{\Omega} \neq \emptyset\}$$

**Width with respect to  $\Omega$ :** Let  $\Pi$  be a homotopy class of sweepouts of  $M$ . Define:

$$\mathbf{L}(\Pi, \Omega) = \inf\{\mathbf{L}(S, \Omega) : S \in \Pi\}.$$

# Proof of Theorem B

## 1. (Existence of critical sequences)

We can find  $\mathfrak{S} = \{S^k\}_{k \in \mathbb{N}} \subset \Pi$  such that

$$\lim_{k \rightarrow \infty} \mathbf{L}(S^k, \Omega) = \mathbf{L}(\Pi, \Omega)$$

and

$$\sup\{\mathcal{H}^{n-1}(\Sigma) : \Sigma \text{ is a slice of } S^k, \text{ for some } k \in \mathbb{N}\} < \infty.$$

# Proof of Theorem B

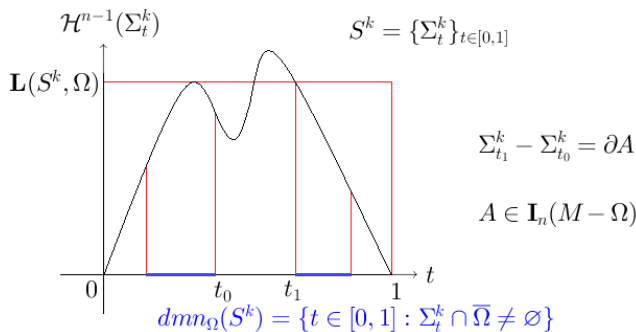
## 1. (Existence of critical sequences)

We can find  $\mathfrak{S} = \{S^k\}_{k \in \mathbb{N}} \subset \Pi$  such that

$$\lim_{k \rightarrow \infty} \mathbf{L}(S^k, \Omega) = \mathbf{L}(\Pi, \Omega)$$

and

$$\sup\{\mathcal{H}^{n-1}(\Sigma) : \Sigma \text{ is a slice of } S^k, \text{ for some } k \in \mathbb{N}\} < \infty.$$



## Lemma

We can find a continuous path

$$\phi : [0, 1] \rightarrow \mathcal{Z}_{n-1}(M - \Omega)$$

such that

- (i)  $\phi(0) = \partial A$  and  $\phi(1) = 0$ ;
  - (ii)  $\mathcal{H}^{n-1}(\phi(t)) \leq C \cdot \mathcal{H}^{n-1}(\partial A)$ , for every  $t \in [0, 1]$ ,
- where  $C > 0$  is a uniform constant.

## Lemma

We can find a continuous path

$$\phi : [0, 1] \rightarrow \mathcal{Z}_{n-1}(M - \Omega)$$

such that

(i)  $\phi(0) = \partial A$  and  $\phi(1) = 0$ ;

(ii)  $\mathcal{H}^{n-1}(\phi(t)) \leq C \cdot \mathcal{H}^{n-1}(\partial A)$ , for every  $t \in [0, 1]$ ,

where  $C > 0$  is a uniform constant.

**Idea:** In  $M - \Omega$ , we use the gradient flow of a Morse function without interior local maxima.

## Min-max sequences and Critical sets

Let  $\mathfrak{S} = \{S^k\}_{k \in \mathbb{N}} \subset \Pi$  be a critical sequence.

**Min-max sequence:** sequence of intersecting slices  $\Sigma_{t_j}^{k_j}$  of  $S^{k_j}$  satisfying

$$\lim_{j \rightarrow \infty} \mathcal{H}^{n-1}(\Sigma_{t_j}^{k_j}) = \mathbf{L}(\Pi, \Omega).$$

$$\mathcal{C}(\mathfrak{S}, \Omega) = \{\text{limits (as varifolds) of min-max sequences}\}.$$



## Min-max sequences and Critical sets

Let  $\mathfrak{S} = \{S^k\}_{k \in \mathbb{N}} \subset \Pi$  be a critical sequence.

**Min-max sequence:** sequence of intersecting slices  $\Sigma_{t_j}^{k_j}$  of  $S^{k_j}$  satisfying

$$\lim_{j \rightarrow \infty} \mathcal{H}^{n-1}(\Sigma_{t_j}^{k_j}) = \mathbf{L}(\Pi, \Omega).$$

$$\mathcal{C}(\mathfrak{S}, \Omega) = \{\text{limits (as varifolds) of min-max sequences}\}.$$

2. Can find  $\mathfrak{S} \in \Pi$  critical and such that

$$V \in \mathcal{C}(\mathfrak{S}, \Omega) \Rightarrow V \text{ stationary in } M \text{ or } \text{spt}(V) \cap \Omega = \emptyset.$$

## Min-max sequences and Critical sets

Let  $\mathfrak{S} = \{S^k\}_{k \in \mathbb{N}} \subset \Pi$  be a critical sequence.

**Min-max sequence:** sequence of intersecting slices  $\Sigma_{t_j}^{k_j}$  of  $S^{k_j}$  satisfying

$$\lim_{j \rightarrow \infty} \mathcal{H}^{n-1}(\Sigma_{t_j}^{k_j}) = \mathbf{L}(\Pi, \Omega).$$

$$\mathcal{C}(\mathfrak{S}, \Omega) = \{\text{limits (as varifolds) of min-max sequences}\}.$$

2. Can find  $\mathfrak{S} \in \Pi$  critical and such that

$$V \in \mathcal{C}(\mathfrak{S}, \Omega) \Rightarrow V \text{ stationary in } M \text{ or } \text{spt}(V) \cap \Omega = \emptyset.$$

3. Given  $\mathfrak{S} \in \Pi$  as in the previous item, we can find  $\Sigma \in \mathcal{C}(\mathfrak{S}, \Omega)$  such that

$$\text{spt}(\Sigma) \cap \Omega \neq \emptyset$$

and

$\Sigma$  is *almost minimizing in small annuli*.

#### 4. Apply *Pitts' Regularity Theorem*

(stationary) + (a.m. in small annuli)  $\Rightarrow$  smooth.

# Existence of intersecting a.m. varifolds

- Suppose that no  $V \in \mathcal{C}(\mathfrak{S}, \Omega)$  satisfies our assumption. Then, big intersecting slices of  $\mathfrak{S}$  are close either
  - (1) to intersecting non-almost minimizing varifolds
  - (2) or to non-intersecting varifolds.
- We deform  $S^k$  to obtain better competitors  $\tilde{S}^k \in \Pi$  such that

$$\mathbf{L}(\tilde{S}^k, \Omega) < \mathbf{L}(S^k, \Omega) - \rho,$$

for some uniform  $\rho > 0$ .

- Therefore,  $\mathbf{L}(\tilde{S}^k, \Omega) < \mathbf{L}(\Pi, \Omega)$  for large  $k$ . Contradiction!

The deformation from  $S^k$  to  $\tilde{S}^k$  is done in two steps.

If  $V$  is type (1), there exist

small annuli  $a(V)$  and  $\varepsilon(V) > 0$  such that:

**Given:**  $\Sigma_t^k \in S^k$  close to  $V$  and  $\eta > 0$ ,

**Can find:**  $\{\Sigma_t^k(s)\}_{s \in [0,1]}$  with the following properties:

- continuous
- $\Sigma_t^k(0) = \Sigma_t^k$
- $\Sigma_t^k(s) \cap (M - a(V)) = \Sigma_t^k \cap (M - a(V))$
- $\mathcal{H}^{n-1}(\Sigma_t^k(s)) \leq \mathcal{H}^{n-1}(\Sigma_t^k) + \eta$
- $\mathcal{H}^{n-1}(\Sigma_t^k(1)) < \mathcal{H}^{n-1}(\Sigma_t^k) - \varepsilon(V)$ .

If  $V$  is type (1), there exist

small annuli  $a(V)$  and  $\varepsilon(V) > 0$  such that:

**Given:**  $\Sigma_t^k \in S^k$  close to  $V$  and  $\eta > 0$ ,

**Can find:**  $\{\Sigma_t^k(s)\}_{s \in [0,1]}$  with the following properties:

- continuous
- $\Sigma_t^k(0) = \Sigma_t^k$
- $\Sigma_t^k(s) \cap (M - a(V)) = \Sigma_t^k \cap (M - a(V))$
- $\mathcal{H}^{n-1}(\Sigma_t^k(s)) \leq \mathcal{H}^{n-1}(\Sigma_t^k) + \eta$
- $\mathcal{H}^{n-1}(\Sigma_t^k(1)) < \mathcal{H}^{n-1}(\Sigma_t^k) - \varepsilon(V)$ .

**Remark:** Pitts had only type (1) varifolds and he performed the desired deformation using the  $\Sigma_t^k(s)$ 's.

**Fact:** Pitts' deformation does not destroy the property of  
"intersecting with small volume".

**Fact:** Pitts' deformation does not destroy the property of  
"intersecting with small volume".

Let  $U \subset \Omega$  be an open set, with  $\overline{U} \subset \Omega$  and such that  $\Omega - U$  is inside a small tubular neighborhood of  $\partial\Omega$ .



**Fact:** Pitts' deformation does not destroy the property of  
"intersecting with small volume".

Let  $U \subset \Omega$  be an open set, with  $\bar{U} \subset \Omega$  and such that  $\Omega - U$  is inside a small tubular neighborhood of  $\partial\Omega$ .

If  $\Sigma_t^k$  is also close to a type (2) varifold, then it has small volume in  $U$ . Making  $a(V)$  small enough, we have that

$$\mathcal{H}^{n-1}(\Sigma_t^k(s) \cap \bar{U}) \text{ is small for every } s \in [0, 1].$$

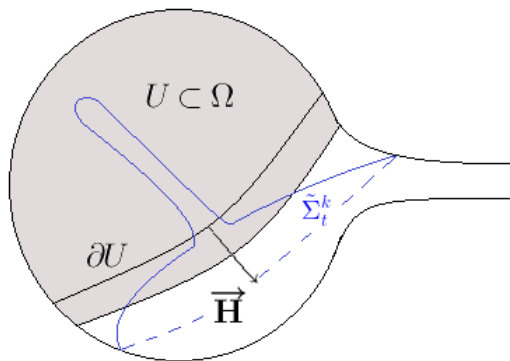
**Fact:** Pitts' deformation does not destroy the property of  
"intersecting with small volume".

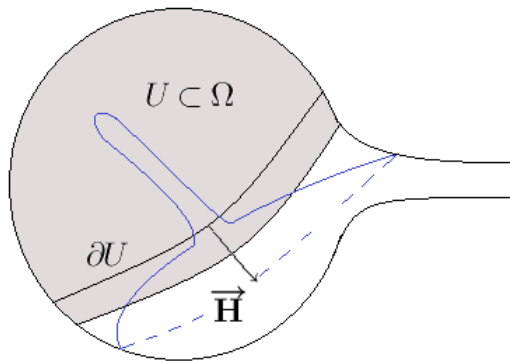
Let  $U \subset \Omega$  be an open set, with  $\bar{U} \subset \Omega$  and such that  $\Omega - U$  is inside a small tubular neighborhood of  $\partial\Omega$ .

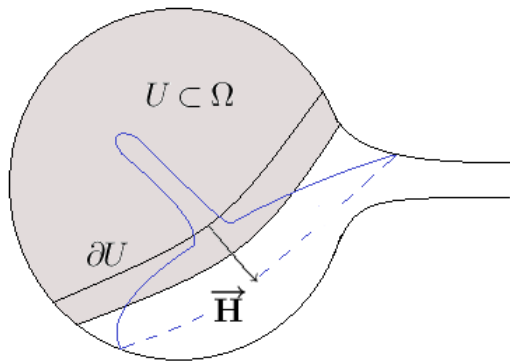
If  $\Sigma_t^k$  is also close to a type (2) varifold, then it has small volume in  $U$ . Making  $a(V)$  small enough, we have that

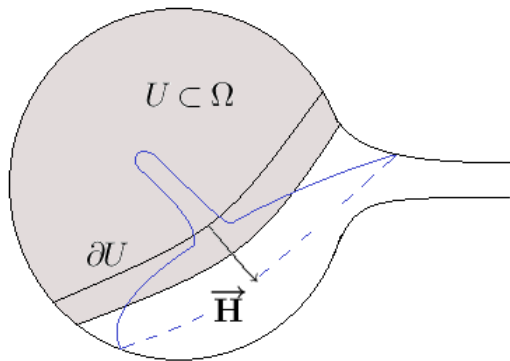
$$\mathcal{H}^{n-1}(\Sigma_t^k(s) \cap \bar{U}) \text{ is small for every } s \in [0, 1].$$

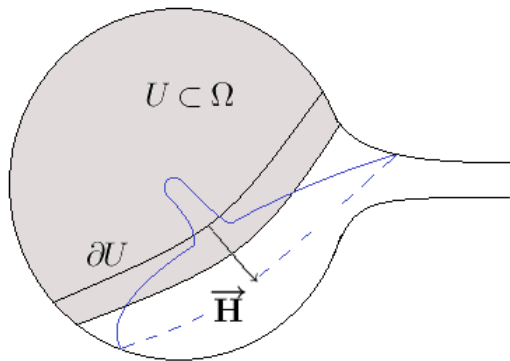
We obtain critical  $\tilde{\mathfrak{S}} = \{\tilde{S}^k\}_{k \in \mathbb{N}}$  such that **the big intersecting slices  $\tilde{\Sigma}_t^k$  have small mass inside  $\bar{U}$ .**

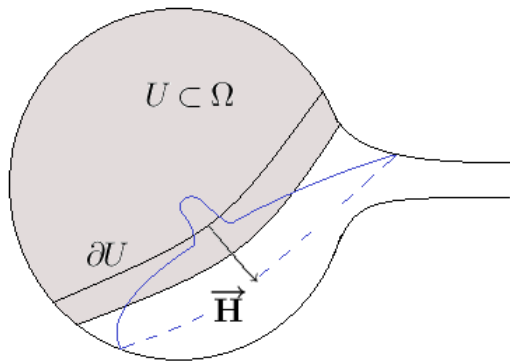




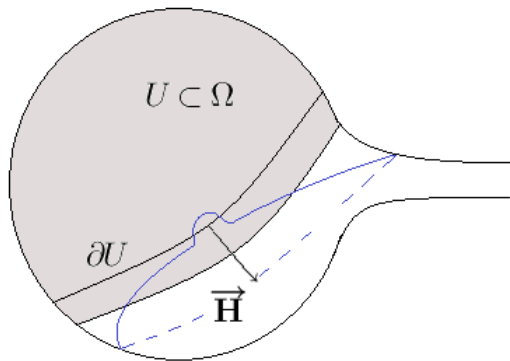


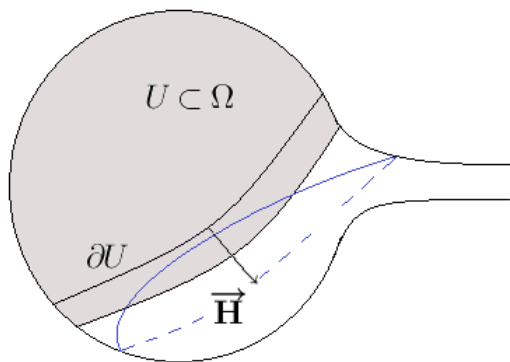




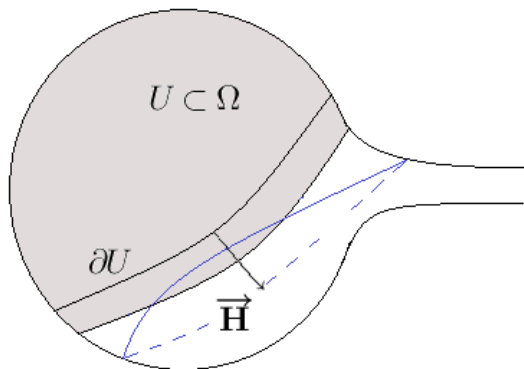


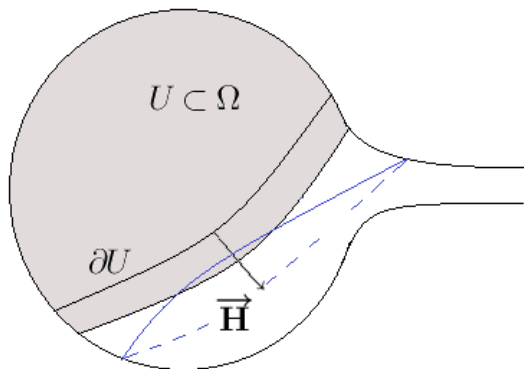


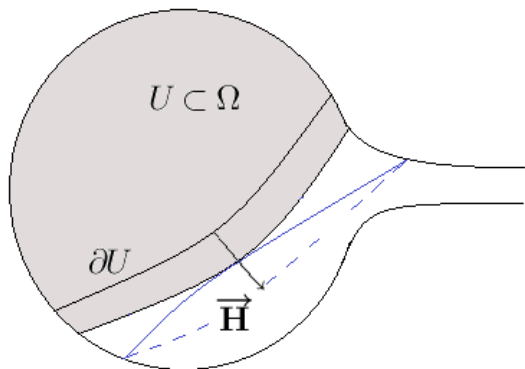


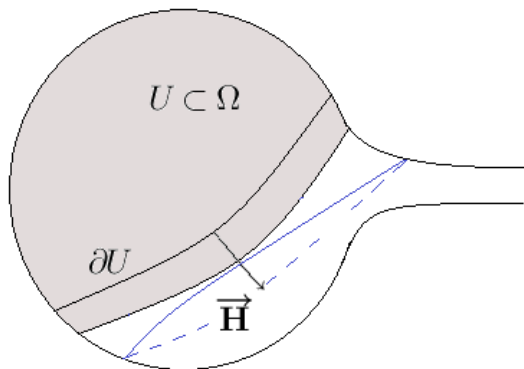


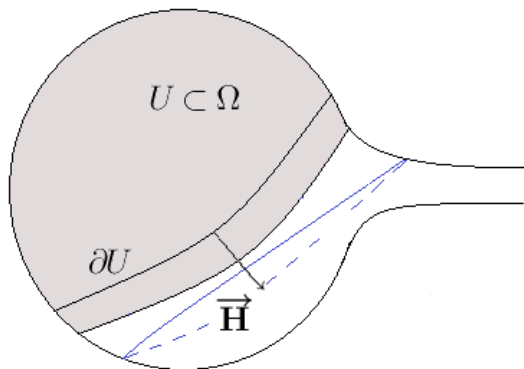
Deformation used by Pitts in the construction of replacements.

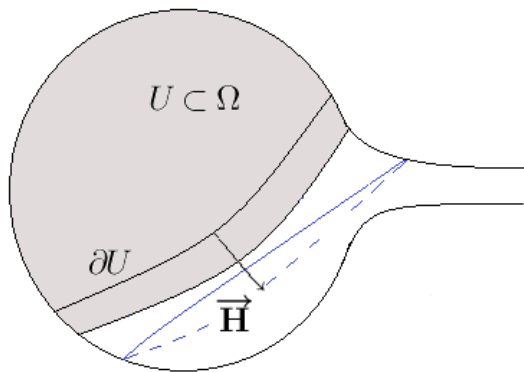












White's maximum principle for general varifolds.



## Part 2: Motivation

- $(S^3, g)$  with positive Ricci curvature in  $S^3$  and scalar curvature  $R \geq 6$ , satisfies the upper bound

$$W(S^3, g) \leq 4\pi$$

and there exists an embedded minimal sphere  $\Sigma$ , of index one and surface area

$$\text{area}_g(\Sigma) = W(S^3, g).$$

In case of equality  $W(S^3, g) = 4\pi$ , the metric  $g$  has constant sectional curvature one.

(Marques - Neves)

- $(S^3, g)$  with positive Ricci curvature in  $S^3$  and scalar curvature  $R \geq 6$ , satisfies the upper bound

$$W(S^3, g) \leq 4\pi$$

and there exists an embedded minimal sphere  $\Sigma$ , of index one and surface area

$$\text{area}_g(\Sigma) = W(S^3, g).$$

In case of equality  $W(S^3, g) = 4\pi$ , the metric  $g$  has constant sectional curvature one.

(Marques - Neves)

**Question:** Is there a scalar curv. rigidity version of this theorem?

## Theorem C (—)

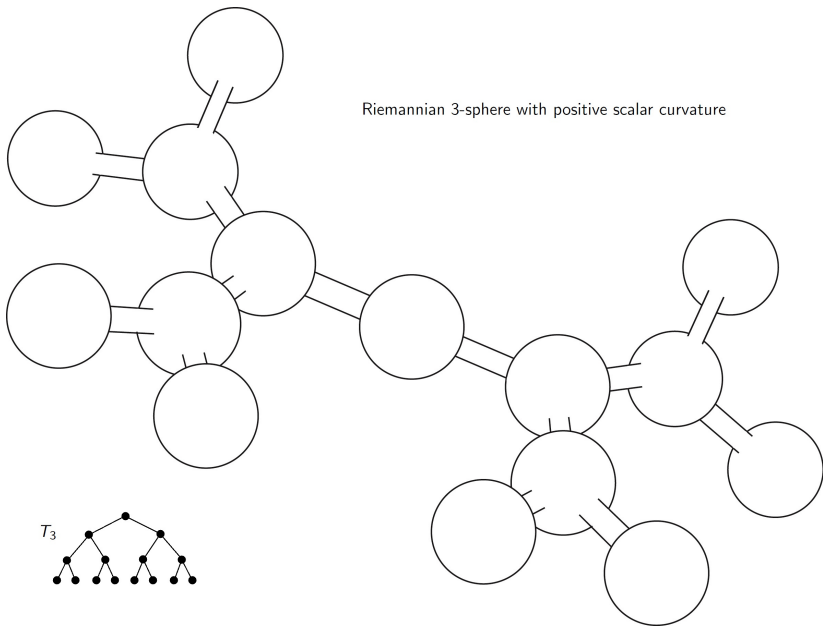
For any  $m > 0$  there exists a Riemannian metric  $g$  on  $S^3$ , with scalar curvature  $R \geq 6$  and width  $W(S^3, g) \geq m$ .

## Theorem C (—)

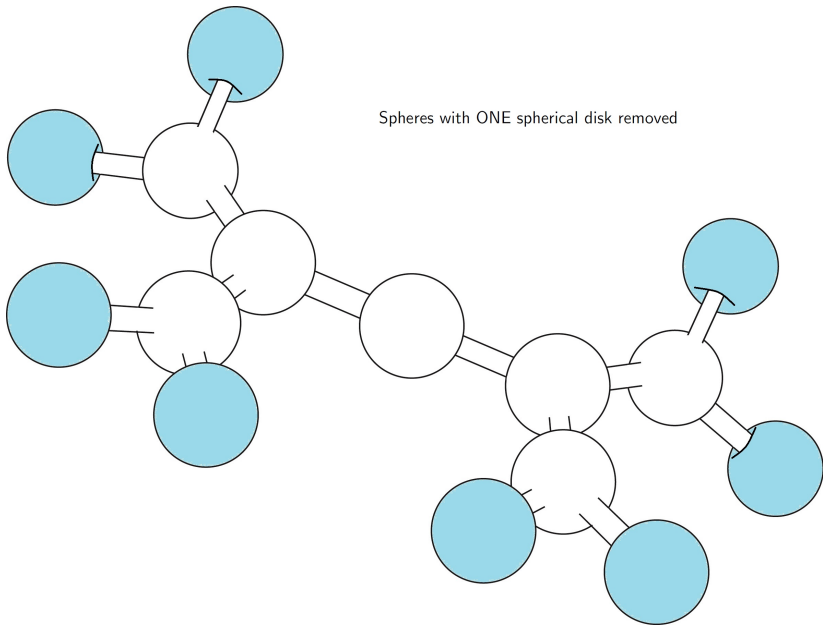
For any  $m > 0$  there exists a Riemannian metric  $g$  on  $S^3$ , with scalar curvature  $R \geq 6$  and width  $W(S^3, g) \geq m$ .

**Remark:** It is interesting to stress that the Riemann curvature tensors of the examples that we construct are uniformly bounded.

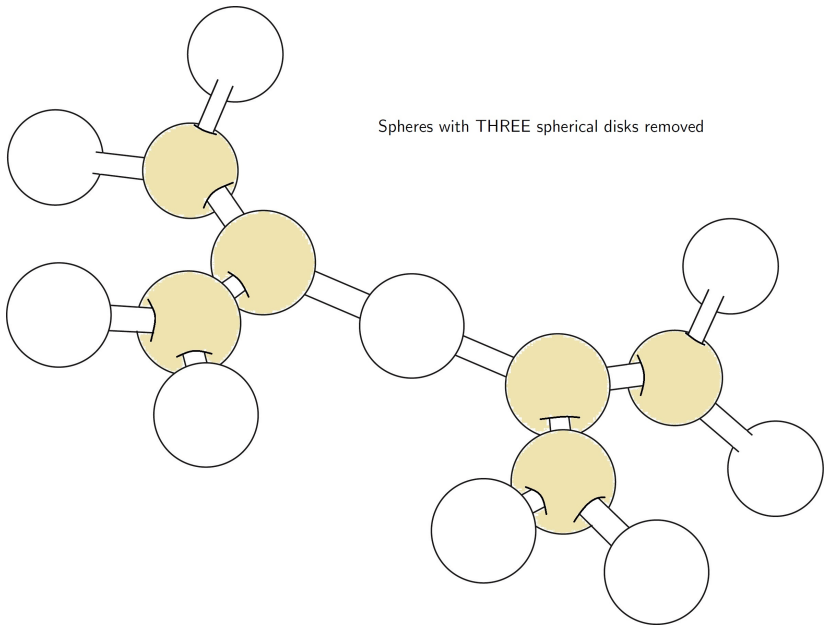
Riemannian 3-sphere with positive scalar curvature



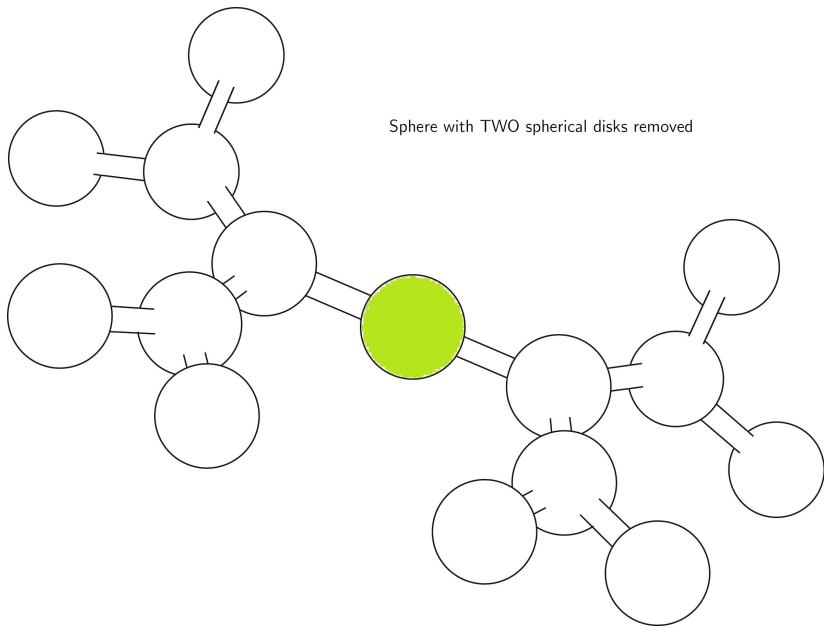
Spheres with ONE spherical disk removed



Spheres with THREE spherical disks removed

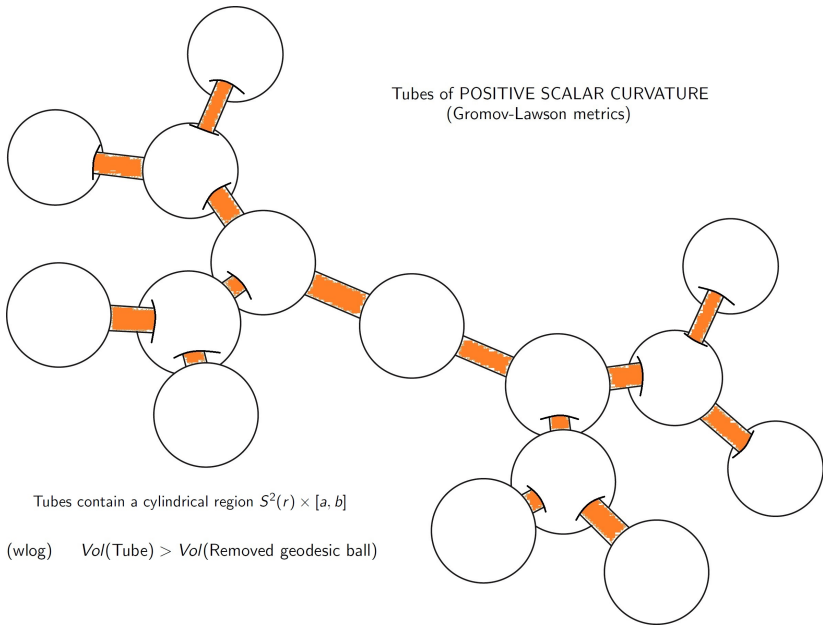


Sphere with TWO spherical disks removed





Tubes of POSITIVE SCALAR CURVATURE  
(Gromov-Lawson metrics)



Tubes contain a cylindrical region  $S^2(r) \times [a, b]$

(wlog)  $Vol(\text{Tube}) > Vol(\text{Removed geodesic ball})$

**Main Idea:** Choose  $\Omega \subset (S^3, g_m)$  so that we can obtain

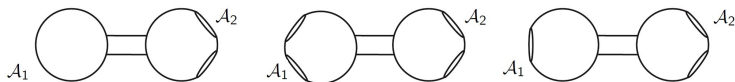
$$\text{area}(\partial\Omega \cap \mathcal{A}) \geq C, \quad \text{for MANY disjoint regions } \mathcal{A}.$$

**Main Idea:** Choose  $\Omega \subset (S^3, g_m)$  so that we can obtain

$$\text{area}(\partial\Omega \cap \mathcal{A}) \geq C, \quad \text{for MANY disjoint regions } \mathcal{A}.$$

**Step 1:** ("Local lower bounds")

- $\mathcal{A}$ -type regions = neighboring spherical regions and the connecting tube.



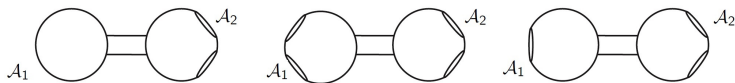
$$\mathcal{A} = \mathcal{A}_1 \cup \text{Tube} \cup \mathcal{A}_2$$

**Main Idea:** Choose  $\Omega \subset (S^3, g_m)$  so that we can obtain

$$\text{area}(\partial\Omega \cap \mathcal{A}) \geq C, \quad \text{for MANY disjoint regions } \mathcal{A}.$$

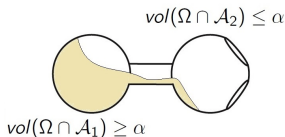
**Step 1:** ("Local lower bounds")

- $\mathcal{A}$ -type regions = neighboring spherical regions and the connecting tube.



$$\mathcal{A} = \mathcal{A}_1 \cup \text{Tube} \cup \mathcal{A}_2$$

- Fix  $\alpha > 0$ . We say a pair  $(\mathcal{A}, \alpha)$  is compatible with  $\Omega$  if



$$\alpha \leq \text{vol}(\Omega \cap \mathcal{A}) \leq \text{vol}(\mathcal{A}) - \alpha$$

$\Downarrow$

Lower bound on  $\text{area}(\partial\Omega \cap \text{int}(\mathcal{A}))$   
(depending on  $\mathcal{A}$  and  $\alpha$  only)

**Step 2:** (Choice of  $\Omega$ )

Need lower bounds for  $\mathbf{L}(\{\Sigma_t\})$ . (ANY sweepout of  $S^3$  w.r.t.  $g_m$ )

**Step 2:** (Choice of  $\Omega$ )

Need lower bounds for  $\mathbf{L}(\{\Sigma_t\})$ . (ANY sweepout of  $S^3$  w.r.t.  $g_m$ )

**Fact:** Associated to  $\{\Sigma_t\}$  there is a continuous family of regions  $\Omega_t$  such that

$$\partial\Omega_t = \Sigma_t, \text{ for all } t \in [0, 1],$$

with  $\Omega_0 = \emptyset$  and  $\Omega_1 = S^3$ .

**Step 2:** (Choice of  $\Omega$ )

Need lower bounds for  $\mathbf{L}(\{\Sigma_t\})$ . (ANY sweepout of  $S^3$  w.r.t.  $g_m$ )

**Fact:** Associated to  $\{\Sigma_t\}$  there is a continuous family of regions  $\Omega_t$  such that

$$\partial\Omega_t = \Sigma_t, \text{ for all } t \in [0, 1],$$

with  $\Omega_0 = \emptyset$  and  $\Omega_1 = S^3$ .

The choice of a good  $\Omega$  reduces to a choice of  $t \in [0, 1]$ .

**Step 2:** (Choice of  $\Omega$ )

Need lower bounds for  $\mathbf{L}(\{\Sigma_t\})$ . (ANY sweepout of  $S^3$  w.r.t.  $g_m$ )

**Fact:** Associated to  $\{\Sigma_t\}$  there is a continuous family of regions  $\Omega_t$  such that

$$\partial\Omega_t = \Sigma_t, \text{ for all } t \in [0, 1],$$

with  $\Omega_0 = \emptyset$  and  $\Omega_1 = S^3$ .

The choice of a good  $\Omega$  reduces to a choice of  $t \in [0, 1]$ .

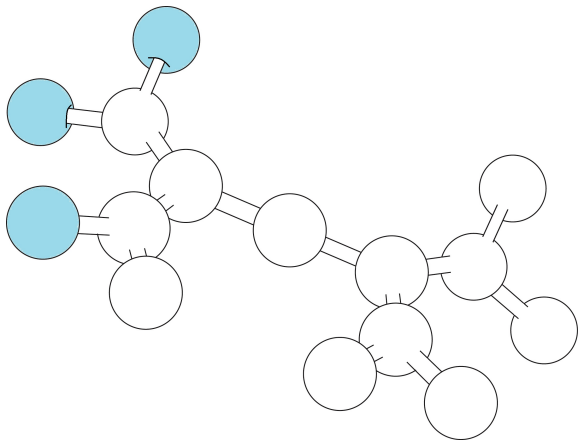
**Claim.**

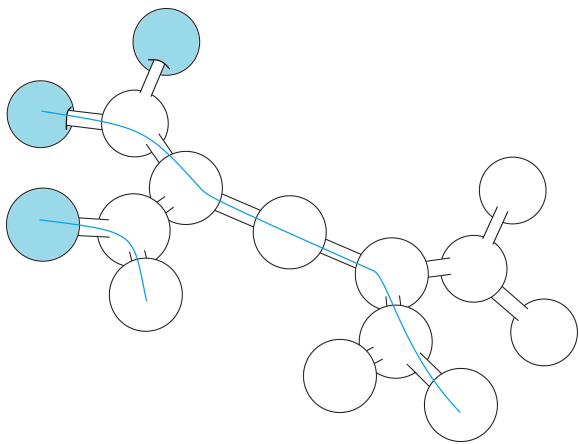
The first  $\Omega_t$  for which

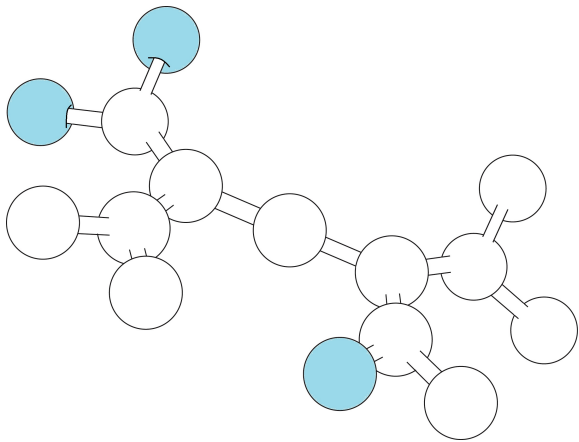
$$\text{vol}(\Omega_t \cap L) \geq \alpha, \text{ at } b(m) \text{ "spherical leaves" } L,$$

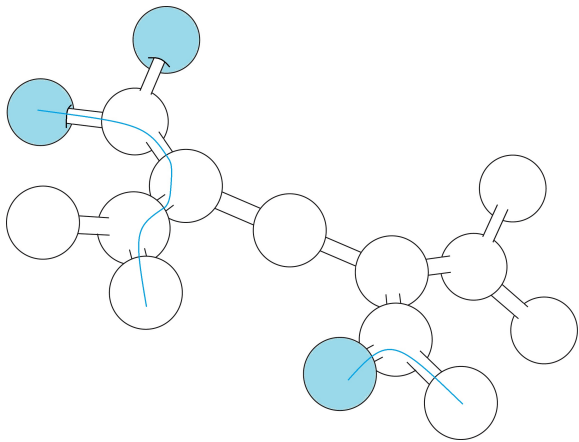
has at least  $\frac{1}{5} \cdot \lceil \frac{m}{2} \rceil$  disjoint compatible pairs  $(\mathcal{A}, \alpha)$ . □

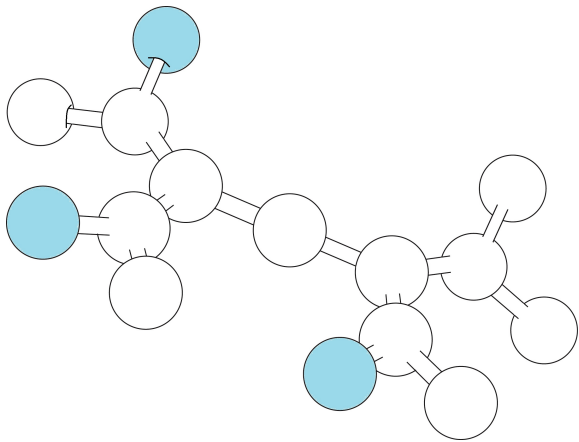


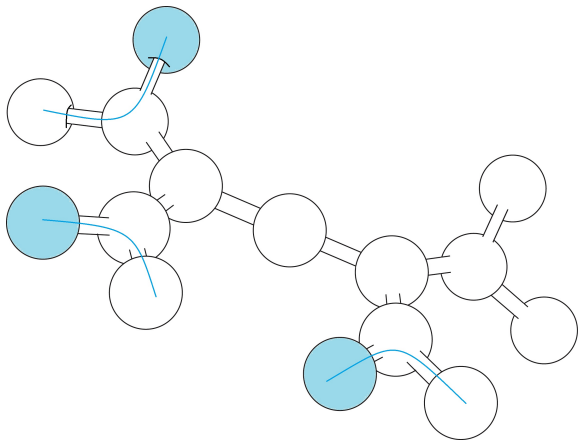












# Isoperimetric profiles

Let  $\Sigma_t = \partial\Omega_t$  be a sweepout of  $(S^3, g)$ . For all  $v \in [0, \text{vol}(S^3, g)]$ , there exists  $t \in [0, 1]$  so that  $\text{vol}(\Omega_t) = v$ . In particular,

$$\mathcal{I}_g(v) = \inf\{\text{area}_g(\partial\Omega) : \text{vol}_g(\Omega) = v\} \leq \text{area}_g(\Sigma_t).$$

# Isoperimetric profiles

Let  $\Sigma_t = \partial\Omega_t$  be a sweepout of  $(S^3, g)$ . For all  $v \in [0, \text{vol}(S^3, g)]$ , there exists  $t \in [0, 1]$  so that  $\text{vol}(\Omega_t) = v$ . In particular,

$$\mathcal{I}_g(v) = \inf\{\text{area}_g(\partial\Omega) : \text{vol}_g(\Omega) = v\} \leq \text{area}_g(\Sigma_t).$$

In conclusion,  $\sup_v \mathcal{I}_g(v) \leq W(S^3, g)$ , for any metric  $g$ .



# Isoperimetric profiles

Let  $\Sigma_t = \partial\Omega_t$  be a sweepout of  $(S^3, g)$ . For all  $v \in [0, \text{vol}(S^3, g)]$ , there exists  $t \in [0, 1]$  so that  $\text{vol}(\Omega_t) = v$ . In particular,

$$\mathcal{I}_g(v) = \inf\{\text{area}_g(\partial\Omega) : \text{vol}_g(\Omega) = v\} \leq \text{area}_g(\Sigma_t).$$

In conclusion,  $\sup_v \mathcal{I}_g(v) \leq W(S^3, g)$ , for any metric  $g$ .

**Remark:** The rigidity result of  $\mathcal{I}_g$  for metrics with  $\text{Ric} > 0$  and  $R \geq 6$  was previously obtained by Eichmair.

# Isoperimetric profiles

Let  $\Sigma_t = \partial\Omega_t$  be a sweepout of  $(S^3, g)$ . For all  $v \in [0, \text{vol}(S^3, g)]$ , there exists  $t \in [0, 1]$  so that  $\text{vol}(\Omega_t) = v$ . In particular,

$$\mathcal{I}_g(v) = \inf\{\text{area}_g(\partial\Omega) : \text{vol}_g(\Omega) = v\} \leq \text{area}_g(\Sigma_t).$$

In conclusion,  $\sup_v \mathcal{I}_g(v) \leq W(S^3, g)$ , for any metric  $g$ .

**Remark:** The rigidity result of  $\mathcal{I}_g$  for metrics with  $\text{Ric} > 0$  and  $R \geq 6$  was previously obtained by Eichmair.

**Question:** What about  $\sup_{m \in \mathbb{N}} (\sup_v \mathcal{I}_{g_m}(v))$ ?

# Isoperimetric profiles

Let  $\Sigma_t = \partial\Omega_t$  be a sweepout of  $(S^3, g)$ . For all  $v \in [0, \text{vol}(S^3, g)]$ , there exists  $t \in [0, 1]$  so that  $\text{vol}(\Omega_t) = v$ . In particular,

$$\mathcal{I}_g(v) = \inf\{\text{area}_g(\partial\Omega) : \text{vol}_g(\Omega) = v\} \leq \text{area}_g(\Sigma_t).$$

In conclusion,  $\sup_v \mathcal{I}_g(v) \leq W(S^3, g)$ , for any metric  $g$ .

**Remark:** The rigidity result of  $\mathcal{I}_g$  for metrics with  $\text{Ric} > 0$  and  $R \geq 6$  was previously obtained by Eichmair.

**Question:** What about  $\sup_{m \in \mathbb{N}} (\sup_v \mathcal{I}_{g_m}(v))$ ?

## Theorem

$$\sup_{m \in \mathbb{N}} \left( \sup_v \mathcal{I}_{g_m}(v) \right) = +\infty.$$

The proof is by contradiction. Suppose there exists  $L > 0$  so that

$$\mathcal{I}_{g_m}(v) \leq L, \quad \forall m \in \mathbb{N} \text{ and } 0 \leq v \leq \text{vol}_{g_m}(S^3).$$

The proof is by contradiction. Suppose there exists  $L > 0$  so that

$$\mathcal{I}_{g_m}(v) \leq L, \quad \forall m \in \mathbb{N} \text{ and } 0 \leq v \leq \text{vol}_{g_m}(S^3).$$

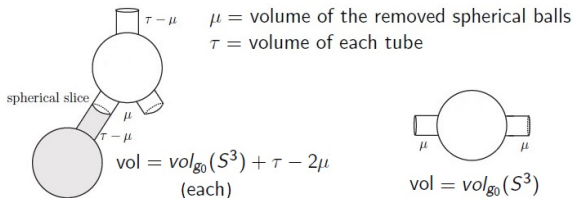
Given  $k \in \mathbb{N}$ , we have  $m = m(k)$  and  $\tilde{b}(k)$ . (combinatorics)

The proof is by contradiction. Suppose there exists  $L > 0$  so that

$$\mathcal{I}_{g_m}(v) \leq L, \quad \forall m \in \mathbb{N} \text{ and } 0 \leq v \leq \text{vol}_{g_m}(S^3).$$

Given  $k \in \mathbb{N}$ , we have  $m = m(k)$  and  $\tilde{b}(k)$ . (combinatorics)

- New  $\mathcal{A}$ -type regions: (balancing volumes)

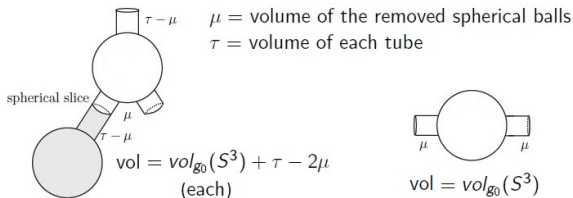


The proof is by contradiction. Suppose there exists  $L > 0$  so that

$$\mathcal{I}_{g_m}(v) \leq L, \quad \forall m \in \mathbb{N} \text{ and } 0 \leq v \leq \text{vol}_{g_m}(S^3).$$

Given  $k \in \mathbb{N}$ , we have  $m = m(k)$  and  $\tilde{b}(k)$ . (combinatorics)

- New  $\mathcal{A}$ -type regions: (balancing volumes)



- Choice of  $\Omega$ :

$$\text{vol}_{g_m}(\Omega_t) = \tilde{b}(k) \cdot (\text{vol}_{g_0}(S^3) + \tau - 2\mu) \Rightarrow$$

$$\left| \# \left\{ \mathcal{A} : \text{vol}(\Omega_t \cap \mathcal{A}) \geq \frac{1}{2} \text{vol}(\mathcal{A}) \right\} - \tilde{b}(k) \right| \leq C(\mathcal{A}\text{-regions}, L, \tau, \mu).$$

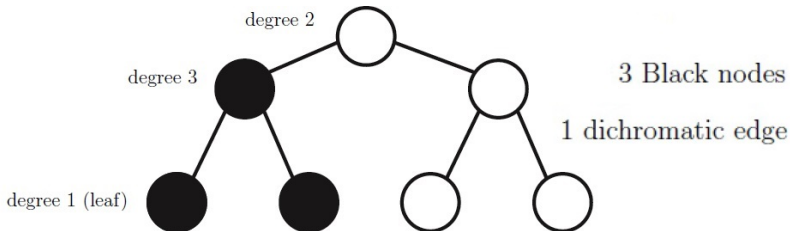
# Combinatorial results

For each  $m \in \mathbb{N}$ ,  $T_m$  denotes the full binary tree of  $2^m$  leaves.  
We consider 2-colorings of the nodes of  $T_m$ .



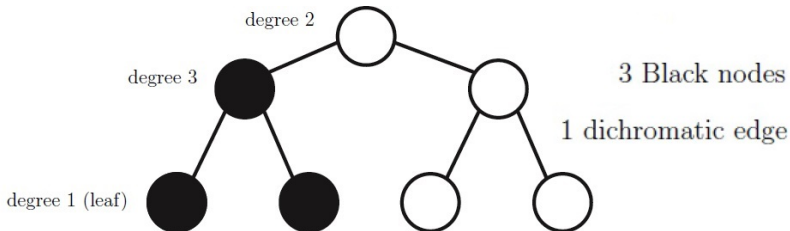
# Combinatorial results

For each  $m \in \mathbb{N}$ ,  $T_m$  denotes the full binary tree of  $2^m$  leaves.  
We consider 2-colorings of the nodes of  $T_m$ .



# Combinatorial results

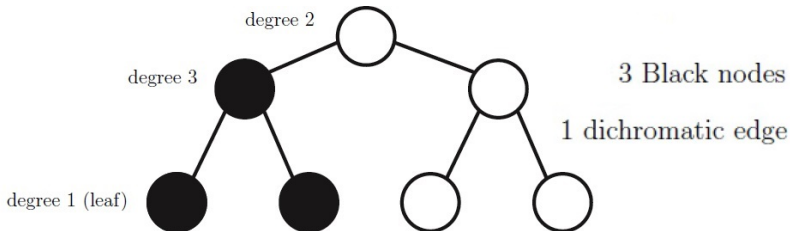
For each  $m \in \mathbb{N}$ ,  $T_m$  denotes the full binary tree of  $2^m$  leaves. We consider 2-colorings of the nodes of  $T_m$ .



**Question:** Let  $k \in \mathbb{N}$ . Can we find integers  $m$  and  $b$  such that any 2-coloring of  $T_m$  with  $b$  black nodes (or leaves) exactly has at least  $k$  dichromatic edges?

# Combinatorial results

For each  $m \in \mathbb{N}$ ,  $T_m$  denotes the full binary tree of  $2^m$  leaves. We consider 2-colorings of the nodes of  $T_m$ .



**Question:** Let  $k \in \mathbb{N}$ . Can we find integers  $m$  and  $b$  such that any 2-coloring of  $T_m$  with  $b$  black nodes (or leaves) exactly has at least  $k$  dichromatic edges?

Yes! (for both, nodes and leaves)

## Theorem (prescribed number of black leaves)

Any 2-coloring of  $T_m$  with

$$b(m) = \begin{cases} 1 + 2 + 2^3 + \dots + 2^{m-2}, & \text{if } m \text{ is odd} \\ 1 + 2^2 + 2^4 + \dots + 2^{m-2}, & \text{if } m \text{ is even,} \end{cases}$$

black leaves exactly has at least

$$\left\lceil \frac{m}{2} \right\rceil \text{ dichromatic edges.}$$

## Theorem (prescribed number of black leaves)

Any 2-coloring of  $T_m$  with

$$b(m) = \begin{cases} 1 + 2 + 2^3 + \dots + 2^{m-2}, & \text{if } m \text{ is odd} \\ 1 + 2^2 + 2^4 + \dots + 2^{m-2}, & \text{if } m \text{ is even,} \end{cases}$$

black leaves exactly has at least

$$\left\lceil \frac{m}{2} \right\rceil \text{ dichromatic edges.}$$

## Theorem (prescribed number of black nodes)

Given  $k \in \mathbb{N}$ , there exist  $m = m(k)$  and  $\tilde{b}(k)$ , such that any 2-coloring of  $T_m$  with  $b$  black nodes exactly has at least

$$\frac{k - |b - \tilde{b}(k)|}{5}$$

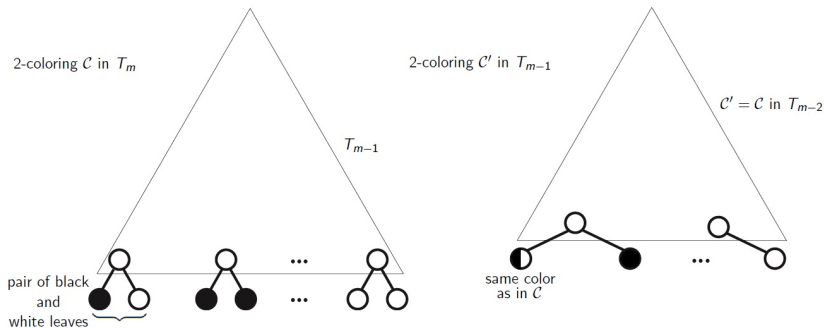
pairwise disjoint pairs of neighboring nodes with different colors.

## Sketch of proof:(in case of leaves)

*First step:* Given a 2-coloring  $\mathcal{C}$  in  $T_m$  with  $b(m)$  black leaves exactly, we associate a 2-coloring of  $T_{m-1}$ .

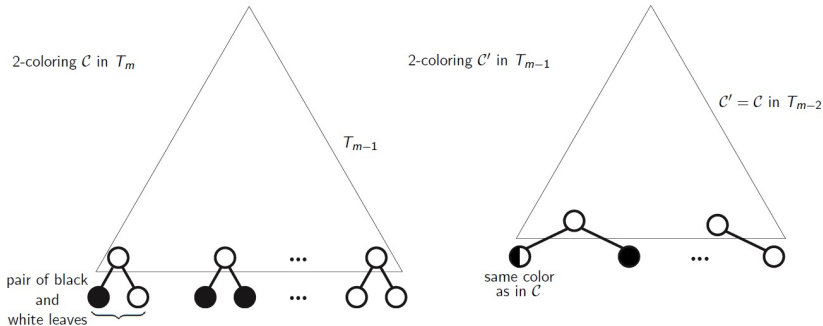
# Sketch of proof:(in case of leaves)

*First step:* Given a 2-coloring  $\mathcal{C}$  in  $T_m$  with  $b(m)$  black leaves exactly, we associate a 2-coloring of  $T_{m-1}$ .



# Sketch of proof:(in case of leaves)

*First step:* Given a 2-coloring  $\mathcal{C}$  in  $T_m$  with  $b(m)$  black leaves exactly, we associate a 2-coloring of  $T_{m-1}$ .



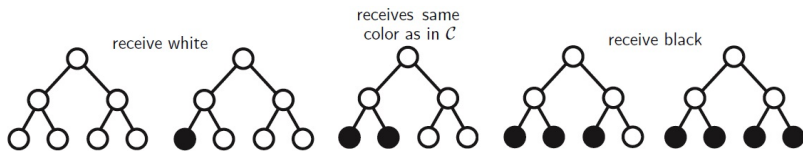
Analyzing  $\#\{\text{black leaves of } \mathcal{C}'\}$  settles the induction step in case:

- $m$  is even; or
- there are at least two pairs of black and white leaves of  $\mathcal{C}$ .



*Second step:* If  $m$  is odd and there is one pair of black and white leaves in  $\mathcal{C}$  only, we induce a 2-coloring in  $T_{m-2}$  and analyze the size of its set of black leaves.

*Second step:* If  $m$  is odd and there is one pair of black and white leaves in  $\mathcal{C}$  only, we induce a 2-coloring in  $T_{m-2}$  and analyze the size of its set of black leaves.



The color induced on each leaf of  $T_{m-2}$  depends only on the  $\mathcal{C}$ -colors of its four associates leaves of  $T_m$ .

Obrigado!