

## Math 54 Section 4: Quiz 4

### Problem 1 True Or False?

- (a) If a system  $Ax = b$  has more than one solution, then so does the system  $Ax = 0$ . **True.** If  $Ax = Ay = b$  and  $x \neq y$ , then  $A(x - y) = 0$ .
- (b) If the equation  $Ax = 0$  has only the trivial solution, then  $A$  is row equivalent to the  $n \times n$  identity matrix. **False.** This is the same as being one-to-one, but to be row equivalent to  $I_n$ ,  $A$  must also be onto.
- (c) If the columns of an  $m \times n$  matrix  $A$  are linearly independent, then the columns of  $A$  span  $\mathbb{R}^n$ . **False.** You can have a set of linearly independent vectors that do not form a basis (for instance if the number of vectors is smaller than  $n$ ).
- (d) If  $BC = BD$ , then  $C = D$ . **False.**  $B$  could be non-invertible.
- (e) If  $A$  and  $B$  are  $n \times n$  matrices, then  $(A + B)(A - B) = A^2 - B^2$ . **False.** This is only true if  $AB = BA$ .
- (f) If  $A$  is invertible and  $r \neq 0$ , then  $(rA)^{-1} = rA^{-1}$ . **False.** The real formula is  $(rA)^{-1} = r^{-1}A^{-1}$ .
- (g)  $\det(AB - BA) = 0$  for any  $A$  and  $B$ . **False.** There are  $2 \times 2$  counter-examples for  $A$  and  $B$ .
- (h) Any onto linear transformation is invertible. **Very False.**
- (i) Row operations on a matrix can change the nullspace. **False.**

**Problem 2** Suppose that  $v_1, v_2, v_3$  are distinct points on a line  $L$  in  $\mathbb{R}^3$ . Here  $L$  does **not** necessarily pass through the origin. Show that  $\{v_1, v_2, v_3\}$  is linearly dependent.

**Solution 2** This is obviously true if  $L$  does go through the origin, since then  $v_1, v_2, v_3$  are 3 vectors in a 1-dimensional vector-space  $L$ .

If  $L$  doesn't, then the set of points in  $L$  is given by  $\{ut + v | t \in \mathbb{R}\}$  where  $u$  and  $v$  are non-zero vectors. In particular, every point on  $L$  is a linear combination of  $u$  and  $v$ , and  $L$  lies inside of the plane  $H = \text{span}(u, v)$ .  $H$  is 2-dimensional, so any 3 vectors in  $H$  are linearly dependent. Thus if  $v_1, v_2, v_3$  are 3 points in  $L$ , then they are also in  $H$  and they must be linearly dependent.

**Problem 3** Suppose  $A$  is invertible. Explain why  $A^T A$  is also invertible. Then show that  $A^{-1} = (A^T A)^{-1} A^T$ .

**Solution 3** The determinant  $\det(A^T A) = \det(A^T) \det(A) = \det(A)^2$  is not zero since  $\det(A)$  is not zero. Thus  $A^T A$  is invertible. Furthermore:

$$((A^T A)^{-1} A^T) A = (A^T A)^{-1} (A^T A) = A^{-1} (A^T)^{-1} A^T A = I$$

So  $(A^T A)^{-1} A^T$  must be the inverse of  $A$ , since multiplying it by  $A$  produces 1.

**Problem 4** Suppose that  $A^n = 0$  for some  $n > 1$ . Find an inverse for  $I - A$ .

**Solution 4** Let  $B = 1 + A + \cdots + A^{n-1}$ . Then we see that:

$$B(I - A) = (1 + A + \cdots + A^{n-1})(I - A) = 1 + A + \cdots + A^{n-1} - A - A^2 - \cdots - A^{n-1} - A^n$$

We see on the right that every power of  $A$  cancels except for  $A^n$  and  $I$ . But since  $A^n = 0$ , that means that  $BA = I$ . So  $B = A^{-1}$ .

**Problem 5** Compute the following determinants.

$$\begin{vmatrix} -1 & 5 & 2 \\ 5 & 6 & 3 \\ 1 & 3 & 1 \end{vmatrix} \quad \begin{vmatrix} 9 & 5 & 2 \\ 1 & 0 & 0 \\ 4 & 4 & 1 \end{vmatrix}$$

**Solution 5** For the first matrix  $A$ , we have  $\det(A) = -1(6 - 9) - 5(5 - 3) + 2(15 - 6) = 3 - 10 + 18 = 11$ . For the second matrix  $B$ , we have  $\det(B) = 9(0 - 0) - 5(1 - 0) + 2(4) = 3$ .

**Problem 6** Let  $A, B, C, D$  be  $n \times n$  matrices with  $A$  invertible. Find matrices  $X$  and  $Y$  to produce the block factorization:

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} I & 0 \\ X & I \end{bmatrix} \begin{bmatrix} A & B \\ 0 & Y \end{bmatrix}$$

and use this to show that:

$$\det \begin{bmatrix} A & B \\ C & D \end{bmatrix} = \det(A) \det(D - CA^{-1}B)$$

**Solution 6** Multiplying out the block matrices, we see that:

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} A & B \\ XA & XB + Y \end{bmatrix}$$

Therefore  $XA = C$ , so  $X = CA^{-1}$ , and  $XB + Y = CA^{-1}B + Y = D$  so  $Y = D - CA^{-1}B$ . Therefore we have:

$$\det \begin{bmatrix} A & B \\ C & D \end{bmatrix} = \det \begin{bmatrix} I & 0 \\ CZ^{-1} & I \end{bmatrix} \cdot \det \begin{bmatrix} A & B \\ 0 & D - CA^{-1}B \end{bmatrix} = \det M \cdot \det N$$

Here we define:

$$M = \begin{bmatrix} I & 0 \\ CZ^{-1} & I \end{bmatrix} \quad N = \begin{bmatrix} A & B \\ 0 & D - CA^{-1}B \end{bmatrix}$$

By subtracting multiples of the top  $n$  rows of  $M$  from the bottom rows of  $N$ , we can turn  $M$  into the  $2n \times 2n$  identity. These operations don't change the determinant, so  $\det M = 1$ . Likewise, we can subtract the first  $n$  columns of  $N$  from the second  $n$  columns of  $N$  to make  $N$  into the matrix:

$$\begin{bmatrix} A & 0 \\ 0 & D - CA^{-1}B \end{bmatrix}$$

This doesn't change the determinant and the resulting matrix has determinant  $\det A \cdot \det(D - CA^{-1}B)$  due to the block structure. Thus  $\det M \cdot \det N = 1 \cdot \det(A) \cdot \det(D - CA^{-1}B)$ .

**Problem 7** Let  $V$  be a vector-space. We say that a subspace  $G$  is smaller than a subspace  $H$  of  $V$  if  $G \subset H$ , that is if  $G$  is a subspace of  $H$ . Let  $v_1, \dots, v_p$  be vectors in a vector-space  $V$ . What is the smallest subspace containing  $v_1, \dots, v_p$ ? Prove it.

**Solution 7** The smallest subspace containing  $v_1, \dots, v_p$  is the span  $S = \text{span}(v_1, \dots, v_p)$ .

We can prove that  $S$  is the smallest subspace containing  $v_1, \dots, v_p$  as so. Let  $H$  be such a subspace. Then since  $H$  is closed under addition and scalar multiplication (by definition) and since  $v_1, \dots, v_p$  are in  $H$ , we have that any linear combination  $c_1v_1 + c_2v_2 + \dots + c_pv_p$  is in  $H$  also. In other words, every vector in the span  $S$  is in  $H$ . Thus  $S \subset H$ , and  $S$  is smaller than any subspace  $H$  containing  $v_1, \dots, v_p$ .

**Problem 8** The rank of a matrix  $A$ , denoted by  $\text{rank}(A)$ , is the number of pivots of  $A$  after row reduction. Equivalently, the rank is the dimension of the range/image of the linear map  $T_A$  of  $A$ , and the rank is also the dimension of the column space of  $A$ .

Let  $A$  be an  $m \times n$  matrix and let  $B$  be an  $n \times p$  matrix, such that  $AB = 0$ . Show that  $\text{rank}(A) + \text{rank}(B) \leq n$ .

**Solution 8** The dimension  $\text{null}(A) = \dim(\text{Null}(A))$  of the null space of  $A$  and the dimension  $\text{rank}(A) = \dim(\text{Im}(A))$  of the column space of  $A$  satisfy:

$$\text{null}(A) + \text{rank}(A) = n$$

This is true for  $A$  and  $B$ . Furthermore, if  $AB = 0$ , then the column space of  $A$  must be a subspace of the nullspace of  $B$ . Thus means that  $\text{rank}(A) = \dim(\text{Im}(A)) \leq \dim(\text{Null}(B)) = \text{null}(B)$ . So:

$$n = \text{null}(A) + \text{rank}(A) \geq \text{rank}(B) + \text{rank}(A)$$