## IMPORTANT PROBABILITY FACTS AND IDEAS:

A **probability space** is a triple  $(\Omega, \mathcal{F}, \mathbb{P})$  where  $\Omega$  is the sample space,  $\mathcal{F}$  is a set of subsets of  $\Omega$  (forming a  $\sigma$ -algebra) and  $\mathbb{P} : \mathcal{F} \to \mathbb{R}$  is a **probability measure** satisfying:

- $\mathbb{P}[\Omega] = 1$
- $\mathbb{P}[A^c] = 1 \mathbb{P}[A]$  for  $A \in \mathcal{F}$ .
- If  $A_1, \ldots$  is countable sequence of disjoints element of  $\mathcal{F}$  then

$$\mathbb{P}[\bigcup_{i} A_{i}] = \sum_{i} \mathbb{P}[A_{i}].$$

A random variable is a function  $X : \Omega \to \mathbb{R}$  (that is  $\mathcal{F}$  measurable). Two random variables X, Y are equal in distribution or identically distributed if for all  $A \subset \mathbb{R}$  (measurable)

$$\mathbb{P}[X \in A] = \mathbb{P}[Y \in A].$$

The **expectation** of X is denoted  $\mathbb{E}[X]$  and satisfies

- Linear  $\mathbb{E}[cX + dY] = c\mathbb{E}[X] + d\mathbb{E}[Y]$  for  $c, d \in \mathbb{R}$ .
- If  $0 \le X \le M$  then  $0 \le \mathbb{E}[X] \le M$ .
- For  $c \in \mathbb{R}$ ,  $\mathbb{E}[c] = c$ .
- If  $X \leq Y$  then  $\mathbb{E}[X] \leq \mathbb{E}[Y]$ .
- $\mathbb{E}[|X|] \ge |\mathbb{E}[X]|$ .
- If  $\phi$  is convex then  $\mathbb{E}[\phi(X)] \ge \phi(\mathbb{E}[x])$ .
- If X and Y are independent then  $\mathbb{E}[XY] = \mathbb{E}[X]\mathbb{E}[Y]$ .

A sequence of random variables  $X_n$  converges in probability to X if for all  $\epsilon > 0$ 

$$\mathbb{P}[|X_n - X| > \epsilon] \to 0.$$

It converges almost surely to X if

$$\mathbb{P}[\{\omega: X_n(\omega) \to X(\omega)\}] = 1.$$

We say  $X_n$  converges weakly or converges in distribution to X if for all bounded continuous functions f(x),

$$\mathbb{E}[f(X_n)] \to \mathbb{E}[f(X)].$$

Equivalently (in dimension 1)

$$\mathbb{P}[X_n \le x] \to \mathbb{P}[X \le x]$$

for all continuity points of  $F(x) = \mathbb{P}[X \leq x]$ , that x with  $\mathbb{P}[X = x] = 0$ .

The Weak Law of Large Numbers says that if  $X_n$  are independent and identically distributed (IID) with  $\mathbb{E}[|X_i|] < \infty$  and  $\mathbb{E}[X_i] = \mu$  then  $\frac{1}{n} \sum_{i=1}^n X_i \to \mu$  in probability. The Strong Law of Large Numbers is the same but for almost sure convergence.

The Central Limit Theorem says that if  $X_i$  are IID with mean  $\mu$  and variance  $\mathbb{E}[X_i^2] = \sigma^2 < \infty$  then

$$\frac{\sum_{i=1}^{n} X_i - \mu n}{\sigma \sqrt{n}} \to N(0,1)$$

where the convergence is in distribution.

For a random variable X the **conditional expectation with respect** to an event A is

$$\mathbb{E}[X|A] := \frac{\mathbb{E}[XI(A)]}{\mathbb{P}[A]}$$

The conditional expectation with respect to a random variable Y (if Y is a discrete random variable) is

$$\mathbb{E}[X|Y] := \psi(Y), \qquad \psi(y) = \mathbb{E}[X|Y = y].$$

The conditional expectation with respect to a  $\sigma$ -algebra  $\mathcal{G}$  is the  $\mathcal{G}$ -measurable random variable such that for all  $A \in \mathcal{G}$ ,

$$\mathbb{E}[XI(B)] = \mathbb{E}[\mathbb{E}[X|\mathcal{G}]I(B)].$$

It has the following properties

- Linear  $\mathbb{E}[cX + dY] = c\mathbb{E}[X] + d\mathbb{E}[Y]$  for  $c, d \in \mathbb{R}$ .
- Tower Property: If  $\mathcal{G} \subset \mathcal{H}$  then

$$\mathbb{E}[\mathbb{E}[X \mid \mathcal{H}] \mid \mathcal{G}] = \mathbb{E}[X \mid \mathcal{H}].$$

• When  $\mathcal{G}$  is the trivial  $\sigma$ -algebra we have that

$$\mathbb{E}[\mathbb{E}[X \mid \mathcal{H}]] = \mathbb{E}[X].$$

- If X is  $\mathcal{G}$  measurable then  $\mathbb{E}[X \mid \mathcal{G}] = X$  and  $\mathbb{E}[XY \mid \mathcal{G}] = X\mathbb{E}[Y \mid \mathcal{G}]$ .
- If X is independent of  $\mathcal{G}$  then  $\mathbb{E}[X \mid \mathcal{G}] = \mathbb{E}[X]$ .

A filtration is a sequence of increasing  $\sigma$ -algebras  $\mathcal{F}_0 \subset \mathcal{F}_1 \subset \ldots$  This represents an increasing amount of information. A sequence  $X_n$  is a martingale with respect to  $\mathcal{F}_n$  if each  $X_n$  is  $\mathcal{F}_n$  measurable and for all n,

$$\mathbb{E}[X_{n+1} \mid \mathcal{F}_n] = X_n.$$

Often the filtration will be the generated by  $X_1, \ldots, X_n$  and then the definition is

$$\mathbb{E}[X_{n+1} \mid X_1, \dots, X_n] = X_n.$$

For all n > m,  $\mathbb{E}[X_n \mid \mathcal{F}_m] = X_m$  and  $\mathbb{E}[X_n] = \mathbb{E}[X_0]$ . For a continuous family  $X_t$  it is a martingale if  $\mathbb{E}[X_t \mid \mathcal{F}_s] = X_s$  for all  $0 \le s < t$ .