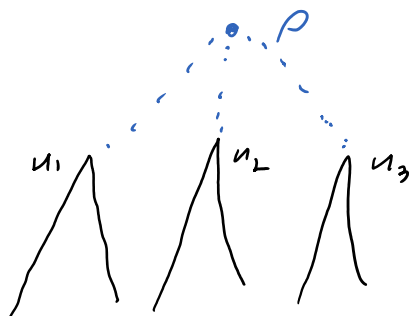


# Spin systems on trees

Friday, March 23, 2018 1:26 PM

Recursive structure



- Initially we have  $d$  trees rooted at  $u_1, \dots, u_d$  with marginals  $m_1, \dots, m_d$
- We add a new layer to the tree rooted at  $p$ , what is the marginal of  $p$ ?

$$Z = \left( \prod z_i \right) \cdot \sum_{\alpha} \psi(\alpha) \sum_{\{x_i\}} \prod_{i=1}^d \psi(x, x_i) m_i(x_i)$$

$$= \left( \prod z_i \right) \sum_{\alpha} \psi(\alpha) \prod_{i=1}^d \left( \sum_{x_i} \psi(x, x_i) m_i(x_i) \right)$$

and

$$m(p) = \frac{\psi(\alpha) \prod_{i=1}^d \left( \sum_{x_i} \psi(x, x_i) m_i(x_i) \right)}{\sum_{\alpha'} \psi(\alpha') \prod_{i=1}^d \left( \sum_{x_i} \psi(x', x_i) m_i(x_i) \right)}$$

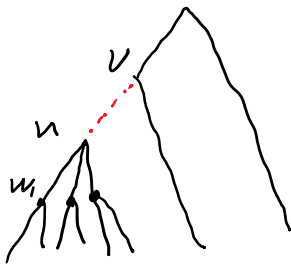
To calculate marginals recursively from the leaves up write

$$m_{u \rightarrow v}(x) = \mathbb{P}_{T \setminus (u,v)}[\sigma_u = x]$$

and

$$m_{u \rightarrow v}(x) = \frac{\psi(x) \prod_{\substack{w \sim u \\ w \neq v}} \sum_{x_w} \psi(x, x_w) m_{w \rightarrow u}(x_w)}{\sum_{x'} \psi(x') \prod_{\substack{w \sim u \\ w \neq v}} \sum_{x_w} \psi(x', x_w) m_{w \rightarrow u}(x_w)}$$

$$=: \text{BP}(\{m_{w \rightarrow u}\})(x)$$

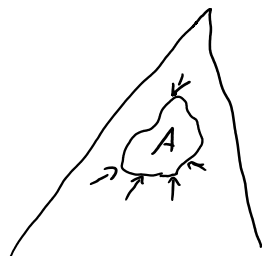


This is the belief propagation function.

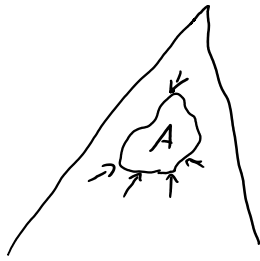
The marginal at  $v$  is

$$\text{BP}(\{m_{u \rightarrow v}\}_{u \sim v}).$$

A fixed point of  $\{m_{u \rightarrow v}\}$  of BP equations gives rise to a Gibbs measure as it gives



a consistent set of distributions on finite sets



a consistent set of distributions  
on finite sets

A fixed point  $m = BP(m, \dots, m)$

Corresponds to a translation invariant  
Gibbs measure on the regular tree.

Example: Ising model,  $h=0$ ,  $d$ -ary tree

Let  $m = m(t)$ ,

$$BP(m) = \frac{(m e^{\beta} + (1-m)e^{-\beta})^d}{(m e^{\beta} + (1-m)e^{-\beta})^d + (m e^{-\beta} + (1-m)e^{\beta})^d}$$

$$\begin{aligned} m e^{\beta} + (1-m)e^{-\beta} &= \frac{1}{2} \cosh \beta + (m - \frac{1}{2}) \sinh \beta \\ &= \frac{1 + 2(m - \frac{1}{2}) \tanh \beta}{\cosh \beta} \end{aligned}$$

So

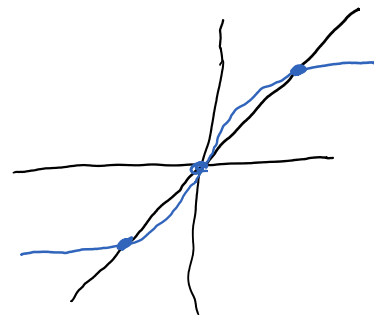
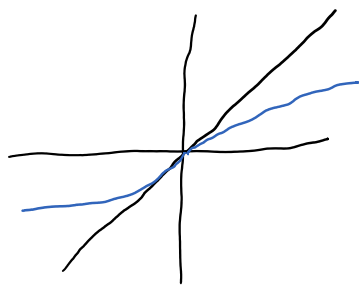
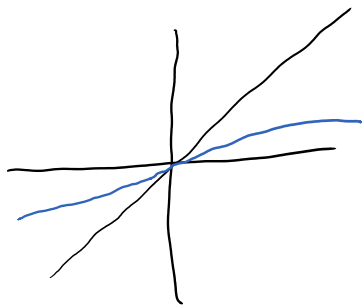
$$BP(m) - \frac{1}{2} = \frac{\frac{1}{2} [1 + 2(m - \frac{1}{2}) \tanh \beta]^d - \frac{1}{2} [1 - 2(m - \frac{1}{2}) \tanh \beta]^d}{(1 + 2(m - \frac{1}{2}) \tanh \beta)^d + (1 - 2(m - \frac{1}{2}) \tanh \beta)^d}$$

with  $y = m - \frac{1}{2}$ ,

$$f(y) = \frac{\frac{1}{2}(1 + 2y \tanh \beta)^d - \frac{1}{2}(1 - 2y \tanh \beta)^d}{(1 + 2y \tanh \beta)^d + (1 - 2y \tanh \beta)^d}$$

$$f(0) = 0,$$

$$f'(0) = \frac{2d(\tanh \beta) \cdot 2}{4} = d \tanh \beta.$$



$$0 < d \tanh \beta < 1$$

$$d \tanh \beta = 1$$

$$d \tanh \beta > 1$$

one fixed point

uniqueness

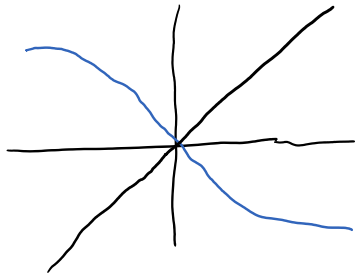
$\geq 3$  fixed point

non-uniqueness

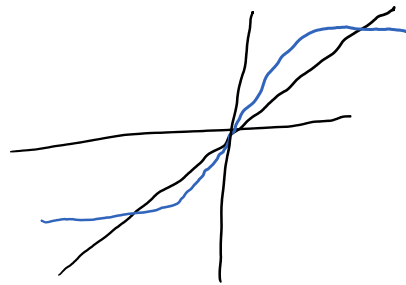
When  $d > \tanh \beta$  there are 3 measures, the symmetric "free measure" plus  $\mu_+$ ,  $\mu_-$ .

If  $\beta < 0$ ,

$f(f(y))$



One fixed point



semi-translation invariant  
measure.