

Non-uniqueness for the Navier–Stokes equations from critical data

Part 1

Stan Palasek (Princeton, IAS)

Aug 11, 2025

NSF-FRG Summer School on Fluids and Computer Assisted Proofs

Navier–Stokes equations

- Incompressible Navier–Stokes equations on $\Omega = \mathbb{R}^3$ or $\mathbb{T}^3$

$$\partial_t u - \Delta u + \operatorname{div} u \otimes u + \nabla p = 0$$

$$\operatorname{div} u = 0$$

$$u(x, 0) = U_0(x)$$

- Unknowns are $u : \Omega \rightarrow \mathbb{R}^3$ and $p : \Omega \rightarrow \mathbb{R}$
- Given initial data U_0 with $\operatorname{div} U_0 = 0$.

Navier–Stokes equations

- Incompressible Navier–Stokes equations on $\Omega = \mathbb{R}^3$ or $\mathbb{T}^3$

$$\partial_t u - \Delta u + \operatorname{div} u \otimes u + \nabla p = 0$$

$$\operatorname{div} u = 0$$

$$u(x, 0) = U_0(x)$$

- Unknowns are $u : \Omega \rightarrow \mathbb{R}^3$ and $p : \Omega \rightarrow \mathbb{R}$
- Given initial data U_0 with $\operatorname{div} U_0 = 0$.
- *Guiding question:* What class of initial data and notion of “solution” guarantees existence, uniqueness, regularity?

Navier–Stokes equations—basic properties

- Sufficiently regular solutions obey the energy equality

$$\int_{\Omega} \frac{|u(t)|^2}{2} dx + \int_0^t \int_{\Omega} |\nabla u|^2 dx dt = \int_{\Omega} \frac{|U_0|^2}{2} dx$$

Navier–Stokes equations—basic properties

- Sufficiently regular solutions obey the energy equality

$$\int_{\Omega} \frac{|u(t)|^2}{2} dx + \int_0^t \int_{\Omega} |\nabla u|^2 dx dt = \int_{\Omega} \frac{|U_0|^2}{2} dx$$

- The Navier–Stokes has a natural scaling symmetry: if $u(t, x)$ is a solution of NSE on $\mathbb{R}^3$ with initial data u^0 , then

$$u_{\lambda}(x, t) = \lambda u(\lambda x, \lambda^2 t), \quad u_{\lambda}^0(x) = \lambda u^0(\lambda x)$$

is also a solution for any $\lambda > 0$.

Navier–Stokes equations—basic properties

- Sufficiently regular solutions obey the energy equality

$$\int_{\Omega} \frac{|u(t)|^2}{2} dx + \int_0^t \int_{\Omega} |\nabla u|^2 dx dt = \int_{\Omega} \frac{|U_0|^2}{2} dx$$

- The Navier–Stokes has a natural scaling symmetry: if $u(t, x)$ is a solution of NSE on $\mathbb{R}^3$ with initial data u^0 , then

$$u_{\lambda}(x, t) = \lambda u(\lambda x, \lambda^2 t), \quad u_{\lambda}^0(x) = \lambda u^0(\lambda x)$$

is also a solution for any $\lambda > 0$.

- A space X is critical if $\|u_{\lambda}^0\|_X = \|u^0\|_X$.

Navier–Stokes equations—basic properties

- Sufficiently regular solutions obey the energy equality

$$\int_{\Omega} \frac{|u(t)|^2}{2} dx + \int_0^t \int_{\Omega} |\nabla u|^2 dx dt = \int_{\Omega} \frac{|U_0|^2}{2} dx$$

- The Navier–Stokes has a natural scaling symmetry: if $u(t, x)$ is a solution of NSE on $\mathbb{R}^3$ with initial data u^0 , then

$$u_{\lambda}(x, t) = \lambda u(\lambda x, \lambda^2 t), \quad u_{\lambda}^0(x) = \lambda u^0(\lambda x)$$

is also a solution for any $\lambda > 0$.

- A space X is critical if $\|u_{\lambda}^0\|_X = \|u^0\|_X$.

- Natural examples of critical spaces: $H^{\frac{1}{2}}$, L^3 , $L^{3,w}$, $B_{p,\infty}^{-1+3/p}$ ($p > 3$)

Navier–Stokes equations—basic properties

- Sufficiently regular solutions obey the energy equality

$$\int_{\Omega} \frac{|u(t)|^2}{2} dx + \int_0^t \int_{\Omega} |\nabla u|^2 dx dt = \int_{\Omega} \frac{|U_0|^2}{2} dx$$

- The Navier–Stokes has a natural scaling symmetry: if $u(t, x)$ is a solution of NSE on $\mathbb{R}^3$ with initial data u^0 , then

$$u_{\lambda}(x, t) = \lambda u(\lambda x, \lambda^2 t), \quad u_{\lambda}^0(x) = \lambda u^0(\lambda x)$$

is also a solution for any $\lambda > 0$.

- A space X is critical if $\|u_{\lambda}^0\|_X = \|u^0\|_X$.
 - Natural examples of critical spaces: $H^{\frac{1}{2}}, L^3, L^{3,w}, B_{p,\infty}^{-1+3/p}$ ($p > 3$)
 - There is small data global existence from data in all these spaces (Fujita–Kato '64, Kato '84, Cannone '94, Planchon '98)

Navier–Stokes equations—basic properties

- ▶ A space X is *subcritical* if $\|u_\lambda^0\|_X = \lambda^c \|u^0\|_X$, $c > 0$.

Navier–Stokes equations—basic properties

- ▶ A space X is *subcritical* if $\|u_\lambda^0\|_X = \lambda^c \|u^0\|_X$, $c > 0$.
 - ▶ Examples: L^∞ , H^1 , etc.

Navier–Stokes equations—basic properties

- ▶ A space X is *subcritical* if $\|u_\lambda^0\|_X = \lambda^c \|u^0\|_X$, $c > 0$.
 - ▶ Examples: L^∞ , H^1 , etc.
 - ▶ Small scales are well-controlled $\rightarrow$ typically expect local well-posedness.

Navier–Stokes equations—basic properties

- ▶ A space X is *subcritical* if $\|u_\lambda^0\|_X = \lambda^c \|u^0\|_X$, $c > 0$.
 - ▶ Examples: L^∞ , H^1 , etc.
 - ▶ Small scales are well-controlled $\rightarrow$ typically expect local well-posedness.
- ▶ A space X is *supercritical* if $\|u_\lambda^0\|_X = \lambda^c \|u^0\|_X$, $c < 0$.

Navier–Stokes equations—basic properties

- ▶ A space X is *subcritical* if $\|u_\lambda^0\|_X = \lambda^c \|u^0\|_X$, $c > 0$.
 - ▶ Examples: L^∞ , H^1 , etc.
 - ▶ Small scales are well-controlled $\rightarrow$ typically expect local well-posedness.
- ▶ A space X is *supercritical* if $\|u_\lambda^0\|_X = \lambda^c \|u^0\|_X$, $c < 0$.
 - ▶ Example: the energy space for initial data L^2

Navier–Stokes equations—basic properties

- ▶ A space X is *subcritical* if $\|u_\lambda^0\|_X = \lambda^c \|u^0\|_X$, $c > 0$.
 - ▶ Examples: L^∞ , H^1 , etc.
 - ▶ Small scales are well-controlled $\rightarrow$ typically expect local well-posedness.
- ▶ A space X is *supercritical* if $\|u_\lambda^0\|_X = \lambda^c \|u^0\|_X$, $c < 0$.
 - ▶ Example: the energy space for initial data L^2
 - ▶ No control over small scales $\rightarrow$ wild behavior possible.

Navier–Stokes equations—Leray's picture

Leray 1934:

Local theory

Navier–Stokes equations—Leray's picture

Leray 1934:

Local theory

- ▶ Local well-posedness when data is in a subcritical space (e.g. L^p , $p > 3$)
- ▶ Solutions are smooth for positive times
- ▶ Finite time blow up might occur

Navier–Stokes equations—Leray's picture

Leray 1934:

Local theory

- ▶ Local well-posedness when data is in a subcritical space (e.g. L^p , $p > 3$)
- ▶ Solutions are smooth for positive times
- ▶ Finite time blow up might occur

Leray weak solutions

Navier–Stokes equations—Leray's picture

Leray 1934:

Local theory

- ▶ Local well-posedness when data is in a subcritical space (e.g. L^p , $p > 3$)
- ▶ Solutions are smooth for positive times
- ▶ Finite time blow up might occur

Leray weak solutions

- ▶ I.e., weak solutions obeying an energy *inequality*
- ▶ Global existence for any L^2 data
- ▶ Weak-strong uniqueness
- ▶ Global regularity?
- ▶ Uniqueness?

Goal of this work:

Goal of this work:

- Construct two weak solutions u_1, u_2 of 3D Navier–Stokes such that:

Goal of this work:

- ▶ Construct two weak solutions u_1, u_2 of 3D Navier–Stokes such that:
 - ▶ they share the same initial data:

$$u_1(0, x) = u_2(0, x) = U^0(x),$$

Goal of this work:

- ▶ Construct two weak solutions u_1, u_2 of 3D Navier–Stokes such that:
 - ▶ they share the same initial data:

$$u_1(0, x) = u_2(0, x) = U^0(x),$$

- ▶ the initial data has finite energy:

$$U^0 \in L^2,$$

Goal of this work:

- Construct two weak solutions u_1, u_2 of 3D Navier–Stokes such that:
 - they share the same initial data:

$$u_1(0, x) = u_2(0, x) = U^0(x),$$

- the initial data has finite energy:

$$U^0 \in L^2,$$

- energy inequality is obeyed:

$$\frac{1}{2} \|u(t)\|_2^2 + \int_{t_0}^t \|\nabla u(s)\|_2^2 ds \leq \frac{1}{2} \|u(t_0)\|_2^2 \quad \forall t \geq t_0, \text{ a.e. } t_0 \geq 0.$$

Goal of this work:

- ▶ Construct two weak solutions u_1, u_2 of 3D Navier–Stokes such that:
 - ▶ they share the same initial data:

$$u_1(0, x) = u_2(0, x) = U^0(x),$$

- ▶ the initial data has finite energy:

$$U^0 \in L^2,$$

- ▶ energy inequality is obeyed:

$$\frac{1}{2}\|u(t)\|_2^2 + \int_{t_0}^t \|\nabla u(s)\|_2^2 ds \leq \frac{1}{2}\|u(t_0)\|_2^2 \quad \forall t \geq t_0, \text{ a.e. } t_0 \geq 0.$$

- ▶ Paradox: known approaches to this problem would give a solution with even stronger properties:

Goal of this work:

- ▶ Construct two weak solutions u_1, u_2 of 3D Navier–Stokes such that:
 - ▶ they share the same initial data:

$$u_1(0, x) = u_2(0, x) = U^0(x),$$

- ▶ the initial data has finite energy:

$$U^0 \in L^2,$$

- ▶ energy inequality is obeyed:

$$\frac{1}{2}\|u(t)\|_2^2 + \int_{t_0}^t \|\nabla u(s)\|_2^2 ds \leq \frac{1}{2}\|u(t_0)\|_2^2 \quad \forall t \geq t_0, \text{ a.e. } t_0 \geq 0.$$

- ▶ Paradox: known approaches to this problem would give a solution with even stronger properties:
 - ▶ Initial data U^0 is *critical* (e.g., $L^{3,w}, BMO^{-1}$)

Goal of this work:

- ▶ Construct two weak solutions u_1, u_2 of 3D Navier–Stokes such that:
 - ▶ they share the same initial data:

$$u_1(0, x) = u_2(0, x) = U^0(x),$$

- ▶ the initial data has finite energy:

$$U^0 \in L^2,$$

- ▶ energy inequality is obeyed:

$$\frac{1}{2}\|u(t)\|_2^2 + \int_{t_0}^t \|\nabla u(s)\|_2^2 ds \leq \frac{1}{2}\|u(t_0)\|_2^2 \quad \forall t \geq t_0, \text{ a.e. } t_0 \geq 0.$$

- ▶ Paradox: known approaches to this problem would give a solution with even stronger properties:
 - ▶ Initial data U^0 is *critical* (e.g., $L^{3,w}, BMO^{-1}$)
 - ▶ u is a smooth solution for $t > 0$

Approach #1: non-uniqueness by instability

Idea of Jia-Sverak (2013):

- Write Navier–Stokes in the self-similar coordinates $\xi = x/t^{1/2}$, $\tau = \log t$ with the ansatz

$$u(t, x) = t^{-1/2} U(\xi, \tau)$$

Approach #1: non-uniqueness by instability

Idea of Jia-Sverak (2013):

- Write Navier–Stokes in the self-similar coordinates $\xi = x/t^{1/2}$, $\tau = \log t$ with the ansatz

$$u(t, x) = t^{-1/2} U(\xi, \tau)$$

- The question of non-uniqueness for u at $t = 0$ is transferred to U at $\tau = -\infty$

Approach #1: non-uniqueness by instability

Idea of Jia-Sverak (2013):

- Write Navier–Stokes in the self-similar coordinates $\xi = x/t^{1/2}$, $\tau = \log t$ with the ansatz

$$u(t, x) = t^{-1/2} U(\xi, \tau)$$

- The question of non-uniqueness for u at $t = 0$ is transferred to U at $\tau = -\infty$
- Find a steady solution $U(\xi, \tau) = \overline{U}(\xi)$ that is nonlinearly unstable in the self-similar dynamics

Approach #1: non-uniqueness by instability

Idea of Jia-Sverak (2013):

- ▶ Write Navier–Stokes in the self-similar coordinates $\xi = x/t^{1/2}$, $\tau = \log t$ with the ansatz

$$u(t, x) = t^{-1/2} U(\xi, \tau)$$

- ▶ The question of non-uniqueness for u at $t = 0$ is transferred to U at $\tau = -\infty$
- ▶ Find a steady solution $U(\xi, \tau) = \overline{U}(\xi)$ that is nonlinearly unstable in the self-similar dynamics
- ▶ Then one can write down infinitely-many distinct solutions:
 - ▶ the stationary (in self-similar coordinates) solution $\overline{U}$
 - ▶ solutions on the unstable manifold of $\overline{U}$ (i.e., converging exponentially to $\overline{U}$ as $\tau \rightarrow -\infty$)

Non-uniqueness by instability cont'd

- ▶ There is a natural method for constructing such an unstable profile (both mathematically and numerically):

Non-uniqueness by instability cont'd

- ▶ There is a natural method for constructing such an unstable profile (both mathematically and numerically):
 - ▶ U obeys a parabolic equation with data encapsulated by the asymptotics as $|\xi| \rightarrow \infty$

Non-uniqueness by instability cont'd

- ▶ There is a natural method for constructing such an unstable profile (both mathematically and numerically):
 - ▶ U obeys a parabolic equation with data encapsulated by the asymptotics as $|\xi| \rightarrow \infty$
 - ▶ Modulate the size of the data at infinity with a parameter $\sigma > 0$:

$$U(\xi) = \sigma a\left(\frac{\xi}{|\xi|}\right)|\xi|^{-1} + o(|\xi|^{-1})$$

Non-uniqueness by instability cont'd

- ▶ There is a natural method for constructing such an unstable profile (both mathematically and numerically):
 - ▶ U obeys a parabolic equation with data encapsulated by the asymptotics as $|\xi| \rightarrow \infty$
 - ▶ Modulate the size of the data at infinity with a parameter $\sigma > 0$:

$$U(\xi) = \sigma a\left(\frac{\xi}{|\xi|}\right)|\xi|^{-1} + o(|\xi|^{-1})$$

- ▶ When $\sigma \ll 1$, there is a unique smooth solution. (GWP for small data in $L^{3,w}$)

Non-uniqueness by instability cont'd

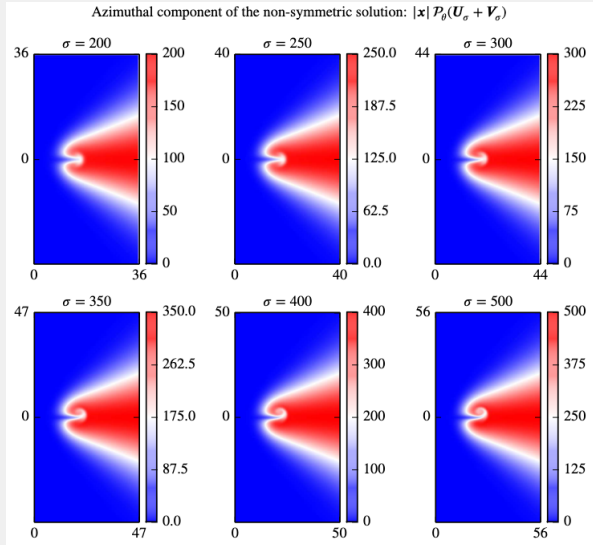
- ▶ There is a natural method for constructing such an unstable profile (both mathematically and numerically):
 - ▶ U obeys a parabolic equation with data encapsulated by the asymptotics as $|\xi| \rightarrow \infty$
 - ▶ Modulate the size of the data at infinity with a parameter $\sigma > 0$:

$$U(\xi) = \sigma a\left(\frac{\xi}{|\xi|}\right) |\xi|^{-1} + o(|\xi|^{-1})$$

- ▶ When $\sigma \ll 1$, there is a unique smooth solution. (GWP for small data in $L^{3,w}$)
- ▶ Conjectured scenario: as σ increases, the solution set bifurcates, an eigenvalue crosses the imaginary axis.

Approach #1: non-uniqueness by instability

This scenario is supported by numerics: (Guillod-Šverák, JMFM 2023)



Non-uniqueness by instability (cont'd)

- ▶ Rigorous justification is challenging

Non-uniqueness by instability (cont'd)

- ▶ Rigorous justification is challenging
- ▶ Vishik (2018): these problems can be relaxed by introducing a force

Non-uniqueness by instability (cont'd)

- ▶ Rigorous justification is challenging
- ▶ Vishik (2018): these problems can be relaxed by introducing a force
- ▶ Albritton-Brué-Colombo (2021): non-unique Leray solutions of *forced* Navier–Stokes from critical initial data

Approach #2: convex integration

- ▶ A very flexible method for constructing wild weak solutions of fluid equations (De Lellis–Székelyhidi 2009)

Approach #2: convex integration

- ▶ A very flexible method for constructing wild weak solutions of fluid equations (De Lellis–Székelyhidi 2009)
- ▶ For Navier–Stokes: Buckmaster–Vicol 2017, Buckmaster–Colombo–Vicol 2018, Cheskidov–Luo 2020–21, Cheskidov–Zeng–Zhang 2025, etc.

Approach #2: convex integration

- ▶ A very flexible method for constructing wild weak solutions of fluid equations (De Lellis–Székelyhidi 2009)
- ▶ For Navier–Stokes: Buckmaster–Vicol 2017, Buckmaster–Colombo–Vicol 2018, Cheskidov–Luo 2020–21, Cheskidov–Zeng–Zhang 2025, etc.
- ▶ Current techniques seem very far from reaching the energy space $L_t^\infty L_x^2 \cap L_t^2 H_x^1$.

Approach #3: breaking a discrete scaling symmetry

Approach #3: breaking a discrete scaling symmetry

- Let $N_k = N_0 \lambda^k$ be a sequence of frequency scales ($\lambda > 1$). Consider a Littlewood-Paley decomposition of a solution:

$$u \sim \sum_{k \geq 1} P_{N_k} u.$$

Approach #3: breaking a discrete scaling symmetry

- Let $N_k = N_0 \lambda^k$ be a sequence of frequency scales ($\lambda > 1$). Consider a Littlewood-Paley decomposition of a solution:

$$u \sim \sum_{k \geq 1} P_{N_k} u.$$

- We model the energy distribution across frequency shells: let the scalar functions $X_k(t)$ model the L^2 of the velocity in the k th shell:

$$X_k \sim \|P_{N_k} u\|_{L^2}$$

Approach #3: breaking a discrete scaling symmetry

- ▶ Let $N_k = N_0 \lambda^k$ be a sequence of frequency scales ($\lambda > 1$). Consider a Littlewood-Paley decomposition of a solution:

$$u \sim \sum_{k \geq 1} P_{N_k} u.$$

- ▶ We model the energy distribution across frequency shells: let the scalar functions $X_k(t)$ model the L^2 of the velocity in the k th shell:

$$X_k \sim \|P_{N_k} u\|_{L^2}$$

- ▶ The Navier-Stokes nonlinearity transfers energy between the modes. Accounting for the nearest-neighbor interactions:

$$\begin{aligned} \dot{X}_k = & -N_k^2 X_k + c_1 (N_{k-1}^\alpha X_{k-1}^2 - N_k^\alpha X_k X_{k+1}) \\ & + c_2 (N_{k-1}^\alpha X_{k-1} X_k - N_k^\alpha X_{k+1}^2) \end{aligned}$$

Approach #3: breaking a discrete scaling symmetry

- Let $N_k = N_0 \lambda^k$ be a sequence of frequency scales ($\lambda > 1$). Consider a Littlewood-Paley decomposition of a solution:

$$u \sim \sum_{k \geq 1} P_{N_k} u.$$

- We model the energy distribution across frequency shells: let the scalar functions $X_k(t)$ model the L^2 of the velocity in the k th shell:

$$X_k \sim \|P_{N_k} u\|_{L^2}$$

- The Navier-Stokes nonlinearity transfers energy between the modes. Accounting for the nearest-neighbor interactions:

$$\begin{aligned} \dot{X}_k = & -N_k^2 X_k + c_1 (N_{k-1}^\alpha X_{k-1}^2 - N_k^\alpha X_k X_{k+1}) \\ & + c_2 (N_{k-1}^\alpha X_{k-1} X_k - N_k^\alpha X_{k+1}^2) \end{aligned}$$

- This model has an analogous theory of Leray solutions which exhibit weak-strong uniqueness.

Breaking a discrete scaling symmetry (cont'd)

- The scenario is captured by the Obukhov model ($c_1 = 0$, $c_2 = 1$):

$$\begin{aligned}\dot{X}_k &= -N_k^2 X_k + N_{k-1}^\alpha X_{k-1} X_k - N_k^\alpha X_{k+1}^2 \\ X_k(0) &= X_k^0\end{aligned}$$

Breaking a discrete scaling symmetry (cont'd)

- The scenario is captured by the Obukhov model ($c_1 = 0$, $c_2 = 1$):

$$\begin{aligned}\dot{X}_k &= -N_k^2 X_k + N_{k-1}^\alpha X_{k-1} X_k - N_k^\alpha X_{k+1}^2 \\ X_k(0) &= X_k^0\end{aligned}$$

- There is an energy identity for regular solutions:

$$\frac{1}{2} \sum_{k \geq 0} X_k^2 + \int_0^t \sum_{k \geq 0} N_k^2 X_k^2 = \frac{1}{2} \sum_{k \geq 0} (X_k^0)^2$$

Breaking a discrete scaling symmetry (cont'd)

- The scenario is captured by the Obukhov model ($c_1 = 0$, $c_2 = 1$):

$$\begin{aligned}\dot{X}_k &= -N_k^2 X_k + N_{k-1}^\alpha X_{k-1} X_k - N_k^\alpha X_{k+1}^2 \\ X_k(0) &= X_k^0\end{aligned}$$

- There is an energy identity for regular solutions:

$$\frac{1}{2} \sum_{k \geq 0} X_k^2 + \int_0^t \sum_{k \geq 0} N_k^2 X_k^2 = \frac{1}{2} \sum_{k \geq 0} (X_k^0)^2$$

- There is a discrete scaling symmetry:

$$X_k^0 \mapsto \lambda^{(2-\alpha)n} X_{k-n}^0, \quad X_k(t) \mapsto \lambda^{(2-\alpha)n} X_{k-n}(\lambda^{2n} t), \quad \forall n \in \mathbb{Z}$$

Breaking a discrete scaling symmetry (cont'd)

- The scenario is captured by the Obukhov model ($c_1 = 0$, $c_2 = 1$):

$$\begin{aligned}\dot{X}_k &= -N_k^2 X_k + N_{k-1}^\alpha X_{k-1} X_k - N_k^\alpha X_{k+1}^2 \\ X_k(0) &= X_k^0\end{aligned}$$

- There is an energy identity for regular solutions:

$$\frac{1}{2} \sum_{k \geq 0} X_k^2 + \int_0^t \sum_{k \geq 0} N_k^2 X_k^2 = \frac{1}{2} \sum_{k \geq 0} (X_k^0)^2$$

- There is a discrete scaling symmetry:

$$X_k^0 \mapsto \lambda^{(2-\alpha)n} X_{k-n}^0, \quad X_k(t) \mapsto \lambda^{(2-\alpha)n} X_{k-n}(\lambda^{2n} t), \quad \forall n \in \mathbb{Z}$$

- The parameter $\alpha \in [1, \frac{5}{2}]$ captures the spatial localization of the velocity at small scales (“intermittency”)
 - $\alpha < 2$: energy is subcritical (local regularity)

Breaking a discrete scaling symmetry (cont'd)

- The scenario is captured by the Obukhov model ($c_1 = 0$, $c_2 = 1$):

$$\begin{aligned}\dot{X}_k &= -N_k^2 X_k + N_{k-1}^\alpha X_{k-1} X_k - N_k^\alpha X_{k+1}^2 \\ X_k(0) &= X_k^0\end{aligned}$$

- There is an energy identity for regular solutions:

$$\frac{1}{2} \sum_{k \geq 0} X_k^2 + \int_0^t \sum_{k \geq 0} N_k^2 X_k^2 = \frac{1}{2} \sum_{k \geq 0} (X_k^0)^2$$

- There is a discrete scaling symmetry:

$$X_k^0 \mapsto \lambda^{(2-\alpha)n} X_{k-n}^0, \quad X_k(t) \mapsto \lambda^{(2-\alpha)n} X_{k-n}(\lambda^{2n} t), \quad \forall n \in \mathbb{Z}$$

- The parameter $\alpha \in [1, \frac{5}{2}]$ captures the spatial localization of the velocity at small scales (“intermittency”)
 - $\alpha < 2$: energy is subcritical (local regularity)
 - $\alpha = 2$: energy critical

Breaking a discrete scaling symmetry (cont'd)

- ▶ The scenario is captured by the Obukhov model ($c_1 = 0$, $c_2 = 1$):

$$\begin{aligned}\dot{X}_k &= -N_k^2 X_k + N_{k-1}^\alpha X_{k-1} X_k - N_k^\alpha X_{k+1}^2 \\ X_k(0) &= X_k^0\end{aligned}$$

- ▶ There is an energy identity for regular solutions:

$$\frac{1}{2} \sum_{k \geq 0} X_k^2 + \int_0^t \sum_{k \geq 0} N_k^2 X_k^2 = \frac{1}{2} \sum_{k \geq 0} (X_k^0)^2$$

- ▶ There is a discrete scaling symmetry:

$$X_k^0 \mapsto \lambda^{(2-\alpha)n} X_{k-n}^0, \quad X_k(t) \mapsto \lambda^{(2-\alpha)n} X_{k-n}(\lambda^{2n} t), \quad \forall n \in \mathbb{Z}$$

- ▶ The parameter $\alpha \in [1, \frac{5}{2}]$ captures the spatial localization of the velocity at small scales (“intermittency”)
 - ▶ $\alpha < 2$: energy is subcritical (local regularity)
 - ▶ $\alpha = 2$: energy critical
 - ▶ $\alpha > 2$: energy supercritical (ill-posedness?)

Breaking a discrete scaling symmetry (cont'd)

- Suppose X is now indexed by $k \in \mathbb{Z}$ and:

Breaking a discrete scaling symmetry (cont'd)

- ▶ Suppose X is now indexed by $k \in \mathbb{Z}$ and:
 - ▶ Data X^0 is invariant under scaling by $\lambda > 1$:

$$X_k(0) = \lambda^{(2-\alpha)n} X_{k-n}(0), \quad \forall n \in \mathbb{Z}$$

Breaking a discrete scaling symmetry (cont'd)

- ▶ Suppose X is now indexed by $k \in \mathbb{Z}$ and:
 - ▶ Data X^0 is invariant under scaling by $\lambda > 1$:

$$X_k(0) = \lambda^{(2-\alpha)n} X_{k-n}(0), \quad \forall n \in \mathbb{Z}$$

- ▶ Solution $X(t)$ invariant under scaling by multiples of λ^2 (but not λ^1):

$$X_k(t) = (\lambda^2)^{(2-\alpha)n} X_{k-2n}((\lambda^2)^{2n} t), \quad \forall n \in \mathbb{Z}$$

Breaking a discrete scaling symmetry (cont'd)

- ▶ Suppose X is now indexed by $k \in \mathbb{Z}$ and:
 - ▶ Data X^0 is invariant under scaling by $\lambda > 1$:

$$X_k(0) = \lambda^{(2-\alpha)n} X_{k-n}(0), \quad \forall n \in \mathbb{Z}$$

- ▶ Solution $X(t)$ invariant under scaling by multiples of λ^2 (but not λ^1):

$$X_k(t) = (\lambda^2)^{(2-\alpha)n} X_{k-2n}((\lambda^2)^{2n} t), \quad \forall n \in \mathbb{Z}$$

- ▶ It follows that X^0 gives rise to distinct solutions: $X(t)$ and $\lambda^{2-\alpha} L X(\lambda^2 t)$ where L is the left shift operator.

Breaking a discrete scaling symmetry (cont'd)

- ▶ Suppose X is now indexed by $k \in \mathbb{Z}$ and:
 - ▶ Data X^0 is invariant under scaling by $\lambda > 1$:

$$X_k(0) = \lambda^{(2-\alpha)n} X_{k-n}(0), \quad \forall n \in \mathbb{Z}$$

- ▶ Solution $X(t)$ invariant under scaling by multiples of λ^2 (but not λ^1):

$$X_k(t) = (\lambda^2)^{(2-\alpha)n} X_{k-2n}((\lambda^2)^{2n} t), \quad \forall n \in \mathbb{Z}$$

- ▶ It follows that X^0 gives rise to distinct solutions: $X(t)$ and $\lambda^{2-\alpha} L X(\lambda^2 t)$ where L is the left shift operator.
- ▶ In practice, the solutions are not *exactly* discretely self-similar, but are nearly so (and converge to exactly SS as $\lambda \rightarrow \infty$).

Breaking a discrete scaling symmetry (cont'd)

- ▶ Suppose X is now indexed by $k \in \mathbb{Z}$ and:
 - ▶ Data X^0 is invariant under scaling by $\lambda > 1$:

$$X_k(0) = \lambda^{(2-\alpha)n} X_{k-n}(0), \quad \forall n \in \mathbb{Z}$$

- ▶ Solution $X(t)$ invariant under scaling by multiples of λ^2 (but not λ^1):

$$X_k(t) = (\lambda^2)^{(2-\alpha)n} X_{k-2n}((\lambda^2)^{2n} t), \quad \forall n \in \mathbb{Z}$$

- ▶ It follows that X^0 gives rise to distinct solutions: $X(t)$ and $\lambda^{2-\alpha} L X(\lambda^2 t)$ where L is the left shift operator.
- ▶ In practice, the solutions are not *exactly* discretely self-similar, but are nearly so (and converge to exactly SS as $\lambda \rightarrow \infty$).
- ▶ Additional symmetry breaking is necessary to get a finite energy solution. (Truncation of low frequencies.)

Non-uniqueness result for the Obukhov model

In the model case, we can solve the full problem.

Non-uniqueness result for the Obukhov model

In the model case, we can solve the full problem.

Theorem (P. 2024)

For any $\alpha > 2$, there exists initial data $X^0 \in \cap_{s < \alpha-2} H^s$ that gives rise to two distinct Leray solutions of the Obukhov system.

Non-uniqueness result for the Obukhov model

In the model case, we can solve the full problem.

Theorem (P. 2024)

For any $\alpha > 2$, there exists initial data $X^0 \in \cap_{s < \alpha-2} H^s$ that gives rise to two distinct Leray solutions of the Obukhov system.

Remarks:

- The solutions decay exponentially in N_k for $t > 0$ and are positive.

Non-uniqueness result for the Obukhov model

In the model case, we can solve the full problem.

Theorem (P. 2024)

For any $\alpha > 2$, there exists initial data $X^0 \in \cap_{s < \alpha-2} H^s$ that gives rise to two distinct Leray solutions of the Obukhov system.

Remarks:

- ▶ The solutions decay exponentially in N_k for $t > 0$ and are positive.
- ▶ We have the stronger critical bound $|X_{0,k}| \lesssim N_k^{-\alpha+2}$ corresponding to data in $B_{p,\infty}^{-1+2(\alpha-1)/p}$.

Idea of the construction

$$\dot{X}_k = -N_k^2 X_k + N_{k-1}^\alpha X_{k-1} X_k - N_k^\alpha X_{k+1}^2, \quad k \geq 1$$

Idea of the construction

$$\dot{X}_k = -N_k^2 X_k + N_{k-1}^\alpha X_{k-1} X_k - N_k^\alpha X_{k+1}^2, \quad k \geq 1$$

- Consider the system for just two adjacent modes:

$$\begin{aligned}\dot{X}_{k-1} &= (-N_{k-1}^2 + N_{k-2}^\alpha X_{k-2}) X_{k-1} - N_{k-1}^\alpha X_k^2 \\ \dot{X}_k &= -N_k^2 X_k + N_{k-1}^\alpha X_{k-1} X_k - N_k^\alpha X_{k+1}^2\end{aligned}$$

Idea of the construction

$$\dot{X}_k = -N_k^2 X_k + N_{k-1}^\alpha X_{k-1} X_k - N_k^\alpha X_{k+1}^2, \quad k \geq 1$$

- Consider the system for just two adjacent modes:

$$\dot{X}_{k-1} = (-N_{k-1}^2 + N_{k-2}^\alpha X_{k-2}) X_{k-1} - N_{k-1}^\alpha X_k^2$$

$$\dot{X}_k = -N_k^2 X_k + N_{k-1}^\alpha X_{k-1} X_k - N_k^\alpha X_{k+1}^2$$

- **Objective:** the main dynamics of (X_{k-1}, X_k) happen on time scale N_k^{-2} and then then dissipate away.

Idea of the construction

$$\dot{X}_k = -N_k^2 X_k + N_{k-1}^\alpha X_{k-1} X_k - N_k^\alpha X_{k+1}^2, \quad k \geq 1$$

- Consider the system for just two adjacent modes:

$$\begin{aligned}\dot{X}_{k-1} &= (-N_{k-1}^2 + N_{k-2}^\alpha X_{k-2}) X_{k-1} - N_{k-1}^\alpha X_k^2 \\ \dot{X}_k &= -N_k^2 X_k + N_{k-1}^\alpha X_{k-1} X_k - N_k^\alpha X_{k+1}^2\end{aligned}$$

- **Objective:** the main dynamics of (X_{k-1}, X_k) happen on time scale N_k^{-2} and then then dissipate away.
- If one can achieve the **objective**, then on this time scale,

Idea of the construction

$$\dot{X}_k = -N_k^2 X_k + N_{k-1}^\alpha X_{k-1} X_k - N_k^\alpha X_{k+1}^2, \quad k \geq 1$$

- Consider the system for just two adjacent modes:

$$\begin{aligned}\dot{X}_{k-1} &= (-N_{k-1}^2 + N_{k-2}^\alpha X_{k-2}) X_{k-1} - N_{k-1}^\alpha X_k^2 \\ \dot{X}_k &= -N_k^2 X_k + N_{k-1}^\alpha X_{k-1} X_k - N_k^\alpha X_{k+1}^2\end{aligned}$$

- **Objective:** the main dynamics of (X_{k-1}, X_k) happen on time scale N_k^{-2} and then then dissipate away.
- If one can achieve the **objective**, then on this time scale,
 - X_{k-2} is roughly constant, and

Idea of the construction

$$\dot{X}_k = -N_k^2 X_k + N_{k-1}^\alpha X_{k-1} X_k - N_k^\alpha X_{k+1}^2, \quad k \geq 1$$

- Consider the system for just two adjacent modes:

$$\begin{aligned}\dot{X}_{k-1} &= (-N_{k-1}^2 + N_{k-2}^\alpha X_{k-2}) X_{k-1} - N_{k-1}^\alpha X_k^2 \\ \dot{X}_k &= -N_k^2 X_k + N_{k-1}^\alpha X_{k-1} X_k - N_k^\alpha X_{k+1}^2\end{aligned}$$

- **Objective:** the main dynamics of (X_{k-1}, X_k) happen on time scale N_k^{-2} and then then dissipate away.
- If one can achieve the **objective**, then on this time scale,
 - X_{k-2} is roughly constant, and
 - X_{k+1} is exponentially small.

Idea of the construction

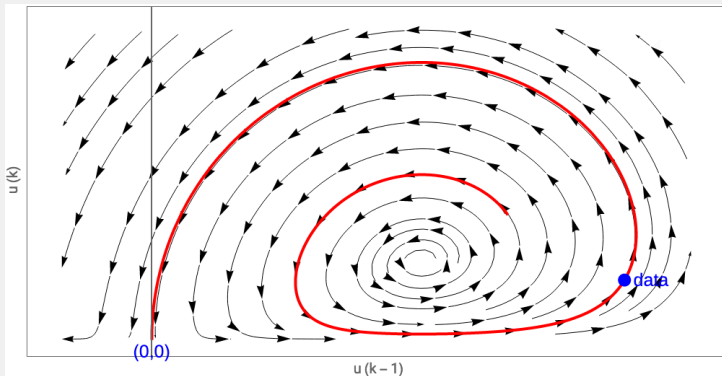
We have (approximately, on a suitable time scale) the *decoupled* system

$$\begin{aligned}\dot{X}_{k-1} &= bX_{k-1} - N_{k-1}^{\alpha} X_k^2 \\ \dot{X}_k &= -N_k^2 X_k + N_{k-1}^{\alpha} X_{k-1} X_k\end{aligned}$$

Idea of the construction

We have (approximately, on a suitable time scale) the *decoupled* system

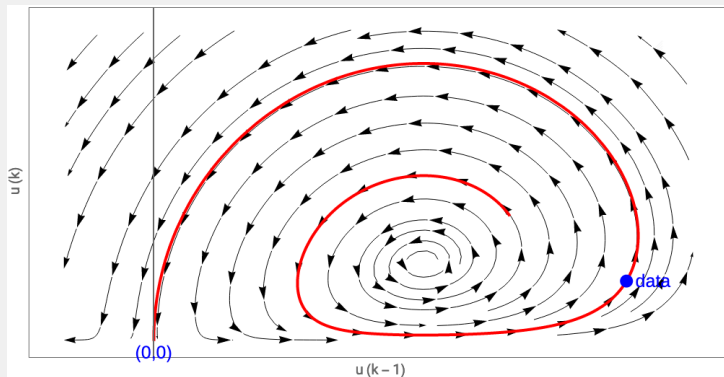
$$\begin{aligned}\dot{X}_{k-1} &= bX_{k-1} - N_{k-1}^\alpha X_k^2 \\ \dot{X}_k &= -N_k^2 X_k + N_{k-1}^\alpha X_{k-1} X_k\end{aligned}$$



Idea of the construction

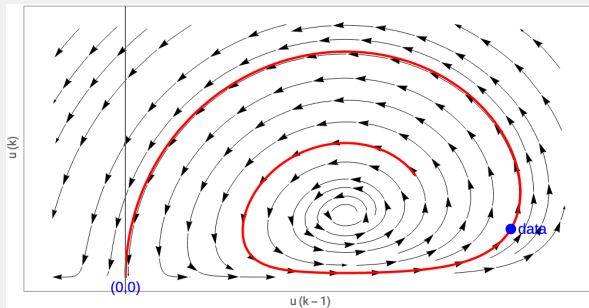
We have (approximately, on a suitable time scale) the *decoupled* system

$$\begin{aligned}\dot{X}_{k-1} &= bX_{k-1} - N_{k-1}^\alpha X_k^2 \\ \dot{X}_k &= -N_k^2 X_k + N_{k-1}^\alpha X_{k-1} X_k\end{aligned}$$



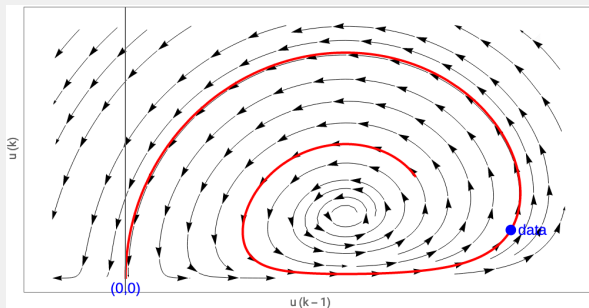
For data on the stable manifold, $(X_{k-1}, X_k) \rightarrow (0, 0)$ on timescale N_k^{-2} .

Idea of the construction



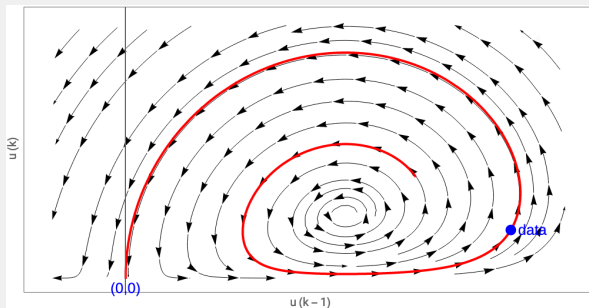
- This configuration can be sustained for (X_{k-1}, X_k) across all k even, or k odd.

Idea of the construction



- This configuration can be sustained for (X_{k-1}, X_k) across all k even, or k odd.
- In other words, there is a family of data for which (X_{2j-1}, X_{2j}) annihilate, and another for which (X_{2j}, X_{2j+1}) annihilate.

Idea of the construction



- This configuration can be sustained for (X_{k-1}, X_k) across all k even, or k odd.
- In other words, there is a family of data for which (X_{2j-1}, X_{2j}) annihilate, and another for which (X_{2j}, X_{2j+1}) annihilate.
- These families have an intersection, so there exists data for which either behavior can happen.

Transfer to the Navier–Stokes equations?

- Consider the actual NSE nonlinearity at frequency N_k :

$$P_{\sim N_k} \operatorname{div} u \otimes u.$$

Transfer to the Navier–Stokes equations?

- Consider the actual NSE nonlinearity at frequency N_k :

$$P_{\sim N_k} \operatorname{div} u \otimes u.$$

- The Obukhov model captures the interactions

$$(P_{\sim N_k} u) \cdot \nabla (P_{\sim N_{k-1}} u)$$

and

$$P_{\sim N_k} \operatorname{div} (P_{\sim N_{k+1}} u) \otimes (P_{\sim N_{k+1}} u).$$

Transfer to the Navier–Stokes equations?

- Consider the actual NSE nonlinearity at frequency N_k :

$$P_{\sim N_k} \operatorname{div} u \otimes u.$$

- The Obukhov model captures the interactions

$$(P_{\sim N_k} u) \cdot \nabla (P_{\sim N_{k-1}} u)$$

and

$$P_{\sim N_k} \operatorname{div} (P_{\sim N_{k+1}} u) \otimes (P_{\sim N_{k+1}} u).$$

- To achieve the same mechanism, one needs to find data so that dominant interactions in the NSE are the following:

$$\partial_t u_{\sim N_{k-1}} \approx -P_{\sim N_{k-1}} \operatorname{div} (u_{\sim N_k} \otimes u_{\sim N_k})$$

$$\partial_t u_{\sim N_k} \approx \Delta u_{\sim N_k} - u_{\sim N_k} \cdot \nabla u_{\sim N_{k-1}}$$

Transfer to the Navier–Stokes equations?

$$\partial_t u_{\sim N_{k-1}} \approx -P_{\sim N_{k-1}} \operatorname{div}(u_{\sim N_k} \otimes u_{\sim N_k})$$

$$\partial_t u_{\sim N_k} \approx \Delta u_{\sim N_k} - u_{\sim N_k} \cdot \nabla u_{\sim N_{k-1}}$$

Transfer to the Navier–Stokes equations?

$$\partial_t u_{\sim N_{k-1}} \approx -P_{\sim N_{k-1}} \operatorname{div}(u_{\sim N_k} \otimes u_{\sim N_k})$$

$$\partial_t u_{\sim N_k} \approx \Delta u_{\sim N_k} - u_{\sim N_k} \cdot \nabla u_{\sim N_{k-1}}$$

- Good news: for these particular nonlinear interactions, $N_k \gg N_{k-1}$ is permitted.

Transfer to the Navier–Stokes equations?

$$\partial_t u_{\sim N_{k-1}} \approx -P_{\sim N_{k-1}} \operatorname{div}(u_{\sim N_k} \otimes u_{\sim N_k})$$

$$\partial_t u_{\sim N_k} \approx \Delta u_{\sim N_k} - u_{\sim N_k} \cdot \nabla u_{\sim N_{k-1}}$$

- Good news: for these particular nonlinear interactions, $N_k \gg N_{k-1}$ is permitted.
- More good news: it is well-understood that $u_{\sim N_k}$ can be chosen so that $P_{\sim N_{k-1}} \operatorname{div}(P_{\sim N_k} u) \otimes (P_{\sim N_k} u)$ behaves in a prescribed way. (convex integration)

Transfer to the Navier–Stokes equations?

$$\partial_t u_{\sim N_{k-1}} \approx -P_{\sim N_{k-1}} \operatorname{div}(u_{\sim N_k} \otimes u_{\sim N_k})$$

$$\partial_t u_{\sim N_k} \approx \Delta u_{\sim N_k} - u_{\sim N_k} \cdot \nabla u_{\sim N_{k-1}}$$

- Good news: for these particular nonlinear interactions, $N_k \gg N_{k-1}$ is permitted.
- More good news: it is well-understood that $u_{\sim N_k}$ can be chosen so that $P_{\sim N_{k-1}} \operatorname{div}(P_{\sim N_k} u) \otimes (P_{\sim N_k} u)$ behaves in a prescribed way. (convex integration)
- Bad news: it is not so clear how to capture $-u_{\sim N_k} \cdot \nabla u_{\sim N_{k-1}}$ in the full PDE

Transfer to Navier–Stokes equations

Joint with M. Coiculescu

Define the critical space BMO^{-1} with the norm

$$\|U\|_{BMO^{-1}} := \sup_{R>0} \sup_{x_0 \in \mathbb{R}^3} \left(\int_0^{R^2} \int_{B(x_0, R)} |e^{t\Delta} U|^2 dx dt \right)^{\frac{1}{2}} < \infty$$

This is the *largest* space where one can implement small data global regularity.

Transfer to Navier–Stokes equations

Joint with M. Coiculescu

Define the critical space BMO^{-1} with the norm

$$\|U\|_{BMO^{-1}} := \sup_{R>0} \sup_{x_0 \in \mathbb{R}^3} \left(\int_0^{R^2} \int_{B(x_0, R)} |e^{t\Delta} U|^2 dx dt \right)^{\frac{1}{2}} < \infty$$

This is the *largest* space where one can implement small data global regularity.

Theorem (Koch and Tataru 2001)

There exists $\epsilon > 0$ such that if U^0 is divergence-free with $\|u\|_{BMO^{-1}} < \epsilon$, then there exists a global-in-time solution that is regular for $t > 0$.

Transfer to Navier–Stokes equations

Joint with M. Coiculescu

Define the critical space BMO^{-1} with the norm

$$\|U\|_{BMO^{-1}} := \sup_{R>0} \sup_{x_0 \in \mathbb{R}^3} \left(\int_0^{R^2} \int_{B(x_0, R)} |e^{t\Delta} U|^2 dx dt \right)^{\frac{1}{2}} < \infty$$

This is the *largest* space where one can implement small data global regularity.

Theorem (Koch and Tataru 2001)

There exists $\epsilon > 0$ such that if U^0 is divergence-free with $\|u\|_{BMO^{-1}} < \epsilon$, then there exists a global-in-time solution that is regular for $t > 0$.

Essentially, they show that the Navier–Stokes bilinear operator

$$u \mapsto - \int_0^t e^{(t-t')\Delta} \mathbb{P} \operatorname{div} u(t') \otimes u(t') dt'$$

is bounded on X_{KT} , the path space corresponding to BMO^{-1} .

What about large initial data?

What about large initial data?

Theorem (Coiculescu–P. 2025)

There exists divergence-free initial data $U^0 \in BMO^{-1}$ such that the Navier–Stokes initial value problem admits two distinct global solutions:

$$u^{(1)}, u^{(2)} \in X_{KT} \cap C_{t,x}^\infty((0, \infty) \times \mathbb{T}^3) \cap C_t([0, \infty); W^{-1,p}(\mathbb{T}^3))$$

for all $p < \infty$.

What about large initial data?

Theorem (Coiculescu–P. 2025)

There exists divergence-free initial data $U^0 \in BMO^{-1}$ such that the Navier–Stokes initial value problem admits two distinct global solutions:

$$u^{(1)}, u^{(2)} \in X_{KT} \cap C_{t,x}^\infty((0, \infty) \times \mathbb{T}^3) \cap C_t([0, \infty); W^{-1,p}(\mathbb{T}^3))$$

for all $p < \infty$.

- The solutions are in the Banach space where Koch–Tataru run the fixed point argument:

$$\sup_{t>0} t^{\frac{1}{2}} \|u^{(i)}(t)\|_{L_x^\infty} + \sup_{x_0, R>0} \left(R^{-3} \int_0^{R^2} \int_{B(R)} |u^{(i)}|^2 dx dt \right)^{1/2} < \infty$$

What about large initial data?

Theorem (Coiculescu–P. 2025)

There exists divergence-free initial data $U^0 \in BMO^{-1}$ such that the Navier–Stokes initial value problem admits two distinct global solutions:

$$u^{(1)}, u^{(2)} \in X_{KT} \cap C_{t,x}^\infty((0, \infty) \times \mathbb{T}^3) \cap C_t([0, \infty); W^{-1,p}(\mathbb{T}^3))$$

for all $p < \infty$.

- ▶ The solutions are in the Banach space where Koch–Tataru run the fixed point argument:

$$\sup_{t>0} t^{\frac{1}{2}} \|u^{(i)}(t)\|_{L_x^\infty} + \sup_{x_0, R>0} \left(R^{-3} \int_0^{R^2} \int_{B(R)} |u^{(i)}|^2 dx dt \right)^{1/2} < \infty$$

- ▶ The data is critical and smooth a.e. (but not L^2).

Thank you!