SOME HIGHER ORDER ISOPERIMETRIC INEQUALITIES VIA THE METHOD OF OPTIMAL TRANSPORT

SUN-YUNG A. CHANG AND YI WANG

ABSTRACT. In this paper, we establish some sharp inequalities between the volume and the integral of the k-th mean curvature for k+1-convex domains in the Euclidean space. The results generalize the classical Alexandrov-Fenchel inequalities for convex domains. Our proof utilizes the method of optimal transportation.

1. Introduction

Classical isoperimetric inequality for domains in Euclidean space was rigorously established by H. A. Schwartz [Sch84](1884) using the method of symmetrization. Later De Giorgi [DG58] gave a simpler proof based on an early argument of Steiner. In [Gro85], Gromov established the inequality by constructing a map from the domain to the unit ball and applying the divergence theorem. Inspired by Gromov's idea, it became well-known that optimal transport method is effective in establishing various sharp geometric inequalities. See for example [McC97], [CENV04], [FMP10] etc..

In this paper, we apply optimal transport method to establish some sharp higher order isoperimetric inequalities of Alexandrov-Flenchel type for a class of domains which includes the convex domains.

Suppose $\Omega \subset \mathbb{R}^m$ is a bounded convex set. Consider the set

$$\Omega + tB := \{x + ty | x \in \Omega, y \in B\}$$

where B is the unit ball and t > 0. By a theorem of Minkowski [Min11], the volume of the set is a polynomial of degree m, whose expansion is given by

$$Vol(\Omega + tB) = \sum_{k=0}^{m} {m \choose k} W_k(\Omega) t^k.$$

Here $W_k(\Omega)$, k = 0, ..., m are coefficients determined by the set Ω , and $\binom{m}{k} = \frac{m!}{k!(m-k)!}$. The k-th quermassintegral V_k is defined as a multiple of the coefficient $W_{m-k}(\Omega)$.

$$V_k(\Omega) := \frac{\omega_k}{\omega_m} W_{m-k}(\Omega). \tag{1.1}$$

Date: December 22, 2012.

¹⁹⁹¹ Mathematics Subject Classification. Primary 35J96; Secondary 52B60.

The research of the first author is partially supported by NSF grant DMS-0758601; the research of the second author is partially supported by NSF grant DMS-1205350.

Here ω_k denotes the volume of the unit k-ball; for an arbitrary domain Ω , $V_m(\Omega) = vol(\Omega)$ denotes the volume of Ω .

If the boundary $\partial\Omega$ is smooth, the quermassintegrals can also be represented as the integrals of invariants of the second fundamental form: Let $L_{\alpha\beta}$ be the second fundamental form on $\partial\Omega$, and let $\sigma_l(L)$ with l=0,...,m-1 be the l-th elementary symmetric function of the eigenvalues of L. (Define $\sigma_0(L)=1$.) Then

$$V_{m-k}(\Omega) := \frac{(m-k)!(k-1)!}{m!} \frac{\omega_{m-k}}{\omega_m} \int_{\partial \Omega} \sigma_{k-1}(L) d\mu, \tag{1.2}$$

where $d\mu$ is the surface area of $\partial\Omega$. From the above definition, one can see that $V_0(\Omega) = 1$, and $V_{m-1}(\Omega) = \frac{\omega_{m-1}}{m\omega_m} Area(\partial\Omega)$. As a consequence of the Alexandrov-Fenchel inequalities [Ale37], one obtains the following family of inequalities: if Ω is a convex domain in \mathbb{R}^m with smooth boundary, then for $0 \leq l \leq m-1$,

$$\left(\frac{V_{l+1}(\Omega)}{V_{l+1}(B)}\right)^{\frac{1}{l+1}} \le \left(\frac{V_l(\Omega)}{V_l(B)}\right)^{\frac{1}{l}}.$$
(1.3)

For $0 \le l \le m-2$, (1.3) is equivalent to, due to the identity (1.2),

$$\left(\int_{\partial\Omega} \sigma_{k-1}(L)d\mu\right)^{\frac{1}{m-k}} \leq \bar{C}\left(\int_{\partial\Omega} \sigma_{k}(L)d\mu\right)^{\frac{1}{m-1-k}},\tag{1.4}$$

where k = m - 1 - l. Here $\bar{C} = C(k, m)$ denotes the (sharp) constant which is obtained only when Ω is a ball in \mathbb{R}^m . When l = m - 1, (1.3) is the well-known isoperimetric inequality

$$vol(\Omega)^{\frac{m-1}{m}} \le \frac{1}{m\omega_m^{\frac{1}{m}}} Area(\partial\Omega).$$
 (1.5)

An open question in the field is if (1.4) holds when the domain is only k-convex in the sense that $\sigma_l(L)(x) > 0$ for all $l \leq k$ and all $x \in \partial\Omega$. (In the following, we denote the condition of k-convexity by $L \in \Gamma_k^+$.) This is indeed the case under the additional assumption that Ω is star-shaped, as established by Guan-Li [GL09]. In the work of Huisken [Hui], he has proved that (1.4) holds for k = 1 when one assumes in addition that the domain is outward minimizing. Inequalities of the type (1.4) were also discussed by Trudinger [Tru94]. In [Cas10], Castillon has applied the method of optimal transport to give a new proof of the Michael-Simon inequality, which in particular implies (1.4) for k = 1 with some constant C(m). In [CW11, CW], we have established inequalities of the type (1.4) for all $l \leq k$ with some (non-sharp) constant C(k, m) when Ω is (k + 1)-convex.

In this note, we apply the method of optimal transport to establish the following "end version" of the sharp inequalities in (1.4).

Theorem 1.1. Let Ω be a domain in \mathbb{R}^m with smooth boundary. Suppose Ω is 2-convex, i.e. $L \in \Gamma_2^+$. Then

$$vol(\Omega)^{\frac{m-2}{m}} \le \left(\frac{1}{\omega_m}\right)^{\frac{2}{m}} \frac{1}{m(m-1)} \int_{\partial \Omega} H d\mu, \tag{1.6}$$

where $H = \sigma_1(L)$ is the mean curvature of $\partial\Omega$ and $d\mu$ is the surface area of $\partial\Omega$. The constant in the inequality is sharp and equality holds only when Ω is a ball in \mathbb{R}^m .

We also prove the inequality between the volume of Ω and the integral of $\sigma_2(L)$ with the sharp constant.

Theorem 1.2. Let Ω be a domain in \mathbb{R}^m with smooth boundary. Suppose Ω is 3-convex, i.e. $L \in \Gamma_3^+$. Then

$$vol(\Omega)^{\frac{m-3}{m}} \le \left(\frac{1}{\omega_m}\right)^{\frac{3}{m}} \frac{1}{3\binom{m}{3}} \int_{\partial\Omega} \sigma_2(L) d\mu. \tag{1.7}$$

The constant in the inequality is sharp and equality holds only when Ω is a ball in \mathbb{R}^m .

We remark that our proof indicates that the sharp version of these inequalities for (k+1)-convex domains are likely to be derived by optimal transport method for all k; but the proof would be algebraically challenging. It also remains an open question if the additional one level of convexity assumption (that is we assume Ω is (k+1)-convex instead of k-convex) in our proof is necessary—but the proof we present here heavily depends on this assumption.

The main difference of Theorem 1.1, and 1.2 from our previous work in [CW] is that we have applied the optimal transport map from a measure on Ω to the unit m-ball, instead of applying the optimal transport map from the projections of the measure on $\partial\Omega$ to the unit (m-1)-balls on hyperplanes of \mathbb{R}^m . Also, in order to obtain the sharp constants, we study the delicate interplays between terms involving the tangential and normal directions of the optimal transport map. We apply the Taylor expansion and derive recursive inequalities in order to estimate each individual term in the expansion.

Finally we would like to clarify that although an optimal transport map $\overline{\nabla}\phi$ from Ω to the unit ball in \mathbb{R}^m is smooth up to the boundary if Ω is strictly convex by the results of Caffarelli ([Caf92a, Caf96]), the proof of our main theorems still work if we only assume Ω is 2 or 3-convex respectively by an approximation argument. This type of approximation process is quite standard and has been explained in detail for example in [CW] and in many other articles in this research field. We will not emphasize this point later in our argument and will take for granted that we can integrate by parts for derivatives of ϕ on $\partial\Omega$.

Acknowledgments: The authors wish to thank Alessio Figalli for his valuable comments and earlier discussions about the subject in the paper. They

are also very grateful to the referees who read the manuscript very carefully and gave many helpful suggestions.

2. Preliminaries

2.1. **Optimal Transport.** We begin with a similar set-up that Gromov has used in establishing the classical isoperimetric inequality.

By the result of Brenier [Bre91] on optimal transportation, given a probability measure f(x)dx on Ω , there exists a convex potential function ϕ : $\mathbb{R}^m \to \mathbb{R}$, such that $\overline{\nabla} \phi$ is the unique optimal transport map from Ω to B(0,1) (the unit m-ball centered at the origin) which pushes forward the probability measure f(x)dx, to the probability measure $g(y)dy = \frac{1}{\omega_m}dy$ on B(0,1). We adopt the convention to denote by $\overline{\nabla} \phi$, $\overline{\nabla}_{ij}^2 \phi$ the gradient and the Hessian of ϕ with respect to the ambient Euclidean metric, in order to distinguish them from $\nabla \phi$, $\nabla_{\alpha\beta}^2 \phi$ (or $\phi_{\alpha\beta}$)—the gradient and the Hessian of ϕ with respect to the metric of $\partial \Omega$. We remark that in our notation, both the coordinate of the form and the coordinate the vector are denoted using the lower index ϕ_{α} (or ϕ_{β} etc.). For simplicity, we denote the boundary $\partial \Omega$ by M from now on.

Since $\overline{\nabla}\phi$ preserves the measure, we have the equation

$$\det(\overline{\nabla}^2\phi)(x) = \frac{f(x)}{g(\overline{\nabla}\phi(x))} = \omega_m f(x). \tag{2.1}$$

The function f(x) will be specified later. Also $\overline{\nabla}\phi$ is the optimal transport map from Ω to B(0,1). Therefore $|\overline{\nabla}\phi| \leq 1$. Thus

$$|\nabla \phi|^2 + \phi_n^2 \le 1. \tag{2.2}$$

Here n denotes the outward unit normal to M, and ϕ_n denotes the directional derivative of ϕ in this direction. This is a fact that will be frequently used later in the argument.

Now the convexity of ϕ implies $\overline{\nabla}^2 \phi$ is nonnegative definite. Therefore by the geometric-arithmetic inequality $(\det(\overline{\nabla}^2 \phi))^{\frac{k+1}{m}} \leq \frac{1}{\binom{m}{k+1}} \sigma_{k+1}(\overline{\nabla}^2 \phi)$. Thus we obtain, by integrating over Ω , that

$$\int_{\Omega} (\omega_m f(x))^{\frac{k+1}{m}} dx = \int_{\Omega} (\det(\overline{\nabla}^2 \phi))^{\frac{k+1}{m}} dx$$

$$\leq \int_{\Omega} \frac{1}{\binom{m}{k+1}} \sigma_{k+1} (\overline{\nabla}^2 \phi) dx$$

$$= \int_{\Omega} \frac{1}{(k+1)\binom{m}{k+1}} \overline{\nabla}_{ij}^2 \phi[T_k]_{ij} (\overline{\nabla}^2 \phi) dx.$$
(2.3)

Here $[T_k]_{ij}$ is the Newton transformation tensor, defined by $[T_k]_{ij}(A) := [T_k]_{ij}(A, ..., A)$ and

$$[T_k]_{ij}(A_1, ..., A_k) := \frac{1}{k!} \delta^{i, i_1, ..., i_k}_{j, j_1, ..., j_k}(A_1)_{i_1 j_1} \cdots (A_k)_{i_k j_k}. \tag{2.4}$$

For example

$$[T_1]_{ij}(A) = Tr(A)\delta_{ij} - A_{ij},$$

where Tr(A) is the trace of A. We used in the last line of (2.3) that $\sigma_{k+1}(A) = \frac{1}{k+1} A_{ij} [T_k]_{ij}(A)$. For more properties of $[T_k]_{ij}$, we refer the readers to [CW11, section 5.1]. Using the fact $\partial_j(\overline{\nabla}_{ij}^2\phi) = \partial_i(\overline{\nabla}_{jj}^2\phi)$, one can easily show that $\partial_j([T_k]_{ij})(\overline{\nabla}^2\phi) = 0$. Here ∂_j is the coordinate derivative on \mathbb{R}^m . Hence we have by the divergence theorem that

$$\int_{\Omega} \frac{1}{(k+1)\binom{m}{k+1}} \overline{\nabla}_{ij}^{2} \phi[T_{k}]_{ij} (\overline{\nabla}^{2} \phi) dx$$

$$= \frac{1}{(k+1)\binom{m}{k+1}} \int_{\Omega} \partial_{j} \left(\phi_{i}[T_{k}]_{ij} (\overline{\nabla}^{2} \phi) \right) dx$$

$$= \frac{1}{(k+1)\binom{m}{k+1}} \int_{M} [T_{k}]_{ij} (\overline{\nabla}^{2} \phi) \phi_{i} n_{j} d\mu,$$
(2.5)

where n_j is the coordinate of the outward unit normal on M. If we combine (2.3) and (2.5) and specify the probability measure $f(x)dx := \frac{1}{vol(\Omega)}dx$ on Ω , we then get

$$vol(\Omega)^{1-\frac{k+1}{m}} \le \left(\frac{1}{\omega_m}\right)^{\frac{k+1}{m}} \frac{1}{(k+1)\binom{m}{k+1}} \int_M [T_k]_{ij} (\overline{\nabla}^2 \phi) \phi_i n_j d\mu. \tag{2.6}$$

Comparing the constants in (2.6) (for k = 1 and 2 respectively) with the constants in (1.6) and (1.7) of Theorem 1.1 and 1.2 respectively, we notice that to prove these theorems it suffices to establish inequalities (2.7) and (2.8) below.

$$\int_{M} [T_1]_{ij}(\overline{\nabla}^2 \phi) \phi_i n_j d\mu \le \int_{M} H d\mu, \tag{2.7}$$

$$\int_{M} [T_2]_{ij}(\overline{\nabla}^2 \phi) \phi_i n_j d\mu \le \int_{M} \sigma_2(L) d\mu. \tag{2.8}$$

In the following, we will in fact prove two inequalities which are slightly stronger than (2.7) and (2.8).

Theorem 2.1. Let ϕ be a smooth convex function on Ω , and $|\nabla \phi| \leq 1$. Suppose $M = \partial \Omega$ is smooth and the second fundamental form $L \in \Gamma_2^+$. Then

$$\int_{M} [T_1]_{ij} (\overline{\nabla}^2 \phi) \phi_i n_j d\mu \le \int_{M} H - \frac{1}{3} [T_1]_{\alpha\beta} (L) \phi_\alpha \phi_\beta d\mu. \tag{2.9}$$

Theorem 2.2. Let ϕ be a smooth convex function on Ω , and $|\nabla \phi| \leq 1$. Suppose $M = \partial \Omega$ is smooth and the second fundamental form $L \in \Gamma_3^+$. Then

$$\int_{M} [T_2]_{ij} (\overline{\nabla}^2 \phi) \phi_i n_j d\mu \le \int_{M} \sigma_2(L) - \frac{1}{4} \int_{M} [T_2]_{\alpha\beta}(L) \phi_\alpha \phi_\beta d\mu. \tag{2.10}$$

Note for $L \in \Gamma_2^+$, $[T_1]_{\alpha\beta}(L) \ge 0$; and for $L \in \Gamma_3^+$, $[T_2]_{\alpha\beta}(L) \ge 0$. In section 3 and 4, we will prove these two theorems.

We remark that although by our optimal transport method with approximation argument, ϕ is smooth on M, it is enough to assume ϕ is C^3 , since in the proof we will only take covariant derivatives of ϕ up to the third order. Also, the assumption that M is smooth can be much weaker. In fact, one only needs to assume M is C^2 (so that the second fundamental form is well defined) and apply an approximation argument. In this paper, however, we do not want to focus on the problem of looking for the weakest regularity assumption, thus we simply assume ϕ and M are smooth.

Proof of Theorem 1.1 and 1.2: It is clear that inequality (2.9) implies (2.7), which in turn implies (1.6); similarly, inequality (2.10) implies (2.8), which in turn implies (1.7). Now we will show that equalities in (1.6) and (1.7) hold only when Ω is a ball. In fact we first claim (1.6) attains the equality only if

$$\overline{\nabla}^2 \phi(x) = \lambda(x) Id. \tag{2.11}$$

The proof of this claim is given in the next paragraph. The same argument applies when (1.7) becomes an equality.

We can approximate Ω by a sequence of subsets $\{\Omega_l\}_{l=1}^{\infty}$ such that $\Omega_l \in \Omega$ and $\partial \Omega_l \to \partial \Omega$ in C^{∞} norm. Since Ω_l is contained in the interior of Ω , and thus ϕ on $\overline{\Omega}_l$ is a smooth function up to the boundary [Caf92b], we can apply Theorem 2.1 on each Ω_l and derive

$$\omega_m^{2/m} vol(\Omega_l) vol(\Omega)^{-2/m} = \int_{\Omega_l} \det^{2/m} (\overline{\nabla}^2 \phi) dx$$

$$\leq \frac{2}{m(m-1)} \int_{\Omega_l} \sigma_2 (\overline{\nabla}^2 \phi) dx \qquad (2.12)$$

$$\leq \frac{1}{m(m-1)} \int_{\partial \Omega_l} H_{\partial \Omega_l} d\mu_l.$$

Here $H_{\partial\Omega_l}$ denotes the mean curvature of boundary of Ω_l ; and μ_l denotes the area form of the boundary of Ω_l . We then take $l \to \infty$. By dominating convergence theorem, we derive the same inequalities for Ω . Namely,

$$\omega_m^{2/m} vol(\Omega)^{1-2/m} = \int_{\Omega} \det^{2/m} (\overline{\nabla}^2 \phi) dx$$

$$\leq \frac{2}{m(m-1)} \int_{\Omega} \sigma_2 (\overline{\nabla}^2 \phi) dx \qquad (2.13)$$

$$\leq \frac{1}{m(m-1)} \int_{\partial \Omega} H d\mu.$$

Hence equality is attained only if $\det^{2/m}(\overline{\nabla}^2\phi) = \frac{2}{m(m-1)}\sigma_2(\overline{\nabla}^2\phi)$, and thus $\overline{\nabla}^2\phi(x) = \lambda(x)Id$. This gives the proof of (2.11).

Now, by our choice $f(x) = \frac{1}{vol(\Omega)}$ as well as the equation (2.1), we see that $\lambda(x)$ must be a constant λ on each connected component of Ω , possibly with different values of λ on different components. Thus the unique solution $\overline{\nabla}\phi$ to the optimal transport problem is a dilation map $\overline{\nabla}\phi(x) = \lambda x$ on each connected component of Ω . Hence each connected component of Ω is a ball. However, if Ω is the union of two or more balls, we can compute directly that it does not attain the equality in (2.9). Therefore Ω is a ball.

2.2. Elementary facts. By Taylor expansion

$$(1 - s^2)^{1/2} = 1 - \sum_{k=1}^{\infty} C_k s^{2k}, \qquad (2.14)$$

where $C_k = {2k \choose k} \frac{1}{2^{2k}(2k-1)} = \frac{(2k-3)!!}{k!2^k} \geq 0$. In the following, we always take $s = |\nabla \phi|$, and $\psi := \sqrt{1-|\nabla \phi|^2}$. By (2.2), $0 \leq s \leq 1$. Formally, the convergence holds uniformly only if |s| < 1. In the proof of Proposition 3.3, we will assume $0 \leq s < 1$ and apply the Taylor expansion. Later in the proof of Theorem 2.1, we will use an approximation argument to derive the theorem for general $0 \leq s \leq 1$. For $0 \leq s < 1$, we have the following facts. Fact (a):

$$\psi = 1 - \sum_{k=1}^{\infty} C_k |\nabla \phi|^{2k}.$$
 (2.15)

Fact (b):

$$\sum_{k=1}^{\infty} 2kC_k |\nabla \phi|^{2(k-1)} \psi \equiv 1.$$
 (2.16)

Proof. If we take derivative on both sides of (2.14), then

$$\frac{-s}{(1-s^2)^{1/2}} = -\sum_{k=1}^{\infty} 2kC_k s^{2k-1}.$$
 (2.17)

Let $s = |\nabla \phi|$. It then deduces (2.16).

Define

$$F(x) := \sum_{k=1}^{\infty} \frac{k}{k+1} C_k |\nabla \phi(x)|^{2(k-1)},$$

and

$$G(x) := \frac{1}{2} - \sum_{k=1}^{\infty} \frac{1}{2(k+1)} C_k |\nabla \phi(x)|^{2k}.$$

F and G will appear in the proof of Theorem 2.2. If we multiply s on both sides of (2.14) and integrate over [0, s], then we derive

Fact (c):
$$3G|\nabla \phi|^2 = 1 - \psi^3$$
.

By a simple calculation, we also have **Fact** (d): $2G = \psi + F |\nabla \phi|^2$.

Fact (e): $F\psi \leq \frac{1}{4}$. Proof of Fact (e): Since $\frac{1}{2(k+1)} \leq \frac{1}{4}$ for $k \geq 1$,

$$F\psi = (\sum_{k=1}^{\infty} \frac{k}{k+1} C_k |\nabla \phi|^{2(k-1)}) \psi$$

$$\leq \frac{1}{4} \sum_{k=1}^{\infty} 2k C_k |\nabla \phi|^{2(k-1)} \psi = \frac{1}{4},$$
(2.18)

where the last equality uses Fact (b).

3. Proof of Theorem 2.1

Consider the isometric embedding $i:M\to\mathbb{R}^m$, where $M:=\partial\Omega$. For $x\in M$, one can write the Hessian of ϕ in coordinates of tangential derivatives and normal derivatives of T_xM . Let indices α , β with α , $\beta=1,...,m-1$ be the tangential directions, n be the outward unit normal direction on M, and let i,j with i,j=1,...,m be the coordinates of \mathbb{R}^m . It is well known that

$$\overline{\nabla}_{\alpha\beta}^2 \phi = \phi_{\alpha\beta} + L_{\alpha\beta}\phi_n,$$

and

$$\overline{\nabla}_{\alpha n}^2 \phi = \nabla_{\alpha}(\phi_n) - L_{\alpha\beta}\phi_{\beta}.$$

Thus we can decompose $\overline{\nabla}^2 \phi = A + B$, where

$$A = \begin{pmatrix} \cdots & \cdots & \cdots & \vdots \\ \cdots & \phi_{\alpha\beta} & \cdots & \nabla_{\alpha}(\phi_n) \\ \cdots & \cdots & \cdots & \vdots \\ \cdots & \nabla_{\alpha}(\phi_n) & \cdots & \overline{\nabla}_{nn}^2 \phi \end{pmatrix}, \tag{3.1}$$

and

$$B = \begin{pmatrix} \dots & \dots & \dots & \vdots \\ \dots & L_{\alpha\beta}\phi_n & \dots & -L_{\alpha\beta}\phi_{\beta} \\ \dots & \dots & \dots & \vdots \\ \dots & -L_{\alpha\beta}\phi_{\beta} & \dots & 0 \end{pmatrix}.$$
 (3.2)

Define

$$L_k := \int_M [T_{k-1}]_{ij} (A+B) \phi_i n_j d\mu.$$
 (3.3)

The inequality in Theorem 2.1 is equivalent to

$$L_2 \le \int_M H - \frac{1}{3} [T_1]_{\alpha\beta}(L) \phi_\alpha \phi_\beta d\mu. \tag{3.4}$$

To prove this, we write $L_2 = L_{2,1} + L_{2,2}$, where

$$L_{2,1} := \int_{M} [T_1]_{ij}(A)\phi_i n_j d\mu,$$

and

$$L_{2,2} := \int_{M} [T_1]_{ij}(B)\phi_i n_j d\mu.$$

Proposition 3.1.

$$L_{2,1} = 2 \int_{M} \Delta \phi \phi_n d\mu. \tag{3.5}$$

$$L_{2,2} = \int_{M} H\phi_n^2 + L_{\alpha\beta}\phi_{\alpha}\phi_{\beta}d\mu. \tag{3.6}$$

Proof. Recall

$$[T_1]_{ij}(A) = Tr(A)\delta_{ij} - A_{ij},$$

where Tr(A) denotes the trace of A.

$$L_{2,1} = \int_{M} (\Delta \phi + \phi_{nn}) \phi_{n} - (\nabla_{\alpha}(\phi_{n}) \phi_{\alpha} + \phi_{nn} \phi_{n}) d\mu$$

$$= \int_{M} \Delta \phi \phi_{n} - \nabla_{\alpha}(\phi_{n}) \phi_{\alpha} d\mu$$

$$= \int_{M} 2\Delta \phi \phi_{n} d\mu.$$
(3.7)

$$L_{2,2} = \int_{M} (Tr(B)\delta_{in} - B_{in})\phi_{i}d\mu$$

$$= \int_{M} (Tr(B)\delta_{\alpha n} - B_{\alpha n})\phi_{\alpha}d\mu + \int_{M} (Tr(B)\delta_{nn} - B_{nn})\phi_{n}d\mu \qquad (3.8)$$

$$= \int_{M} H\phi_{n}^{2} + L_{\alpha\beta}\phi_{\alpha}\phi_{\beta}d\mu.$$

We now define $M_{2,1}$, and $M_{2,2}$ the analogous expressions of $L_{2,1}$, $L_{2,2}$ in (3.5) and (3.6), with ϕ_n replaced by ψ :

Definition 3.2. Define

$$M_{2,1} := 2 \int_M \Delta \phi \psi d\mu, \tag{3.9}$$

and

$$M_{2,2} := \int_{M} H\psi^2 + L_{\alpha\beta}\phi_{\alpha}\phi_{\beta}d\mu. \tag{3.10}$$

Proposition 3.3. Suppose ϕ in addition satisfies $|\nabla \phi| < 1$. Then

$$M_{2,1} \leq \frac{2}{3} \int_{M} (H\delta_{\alpha\beta} - L_{\alpha\beta}) \phi_{\alpha} \phi_{\beta} d\mu$$

$$= \frac{2}{3} \int_{M} [T_{1}]_{\alpha\beta}(L) \phi_{\alpha} \phi_{\beta} d\mu.$$
(3.11)

$$M_{2,2} = \int_{M} H - [T_1]_{\alpha\beta}(L)\phi_{\alpha}\phi_{\beta}d\mu. \tag{3.12}$$

We now assert the inequality (2.9) in Theorem 2.1 follows the inequalities in the above proposition. To see this, we have

$$L_{2} = L_{2,1} + L_{2,2}$$

$$= M_{2,1} + M_{2,2} + \int_{M} 2\Delta\phi(\phi_{n} - \psi) + H(\phi_{n}^{2} - \psi^{2})d\mu$$
(3.13)

We claim that

$$\int_{M} 2\Delta \phi(\phi_n - \psi) + H(\phi_n^2 - \psi^2) d\mu \le 0.$$
 (3.14)

To see (3.14), we re-write $\Delta \phi$ as $\Delta \phi = \overline{\Delta}|_{T_x M} \phi - H \phi_n$, where $\overline{\Delta}|_{T_x M} \phi$ denotes the trace of $\overline{\nabla}^2 \phi$ restricted on $T_x M$. Since $\overline{\nabla}^2 \phi$ is nonnegative, $\overline{\Delta}|_{T_x M} \phi \geq 0$. Therefore, we obtain

$$\int_{M} 2\Delta\phi(\phi_{n} - \psi) + H(\phi_{n}^{2} - \psi^{2})d\mu$$

$$= \int_{M} 2\overline{\Delta}|_{T_{x}M}\phi(\phi_{n} - \psi) - 2H\phi_{n}(\phi_{n} - \psi) + H(\phi_{n}^{2} - \psi^{2})d\mu$$

$$= \int_{M} 2\overline{\Delta}|_{T_{x}M}\phi(\phi_{n} - \psi) - H(\phi_{n} - \psi)^{2}d\mu.$$
(3.15)

Using (2.2), $\phi_n \leq \psi = \sqrt{1 - |\nabla \phi|^2}$; we also have $\overline{\Delta}|_{T_xM} \phi \geq 0$ and $H \geq 0$. Thus (3.14) holds.

We now deduce from (3.13), (3.14) and Proposition 3.3 that for ϕ satisfying $|\nabla \phi| < 1$,

$$L_2 \le M_{2,1} + M_{2,2}$$

 $\le \int_M H - \frac{1}{3} [T_1]_{\alpha\beta}(L) \phi_\alpha \phi_\beta d\mu.$ (3.16)

This finishes the proof of Theorem 2.1 for ϕ satisfying $|\nabla \phi| < 1$.

If $|\nabla \phi| \leq 1$, then we can apply the above argument to the function $\phi_{\delta} := (1 - \delta) \cdot \phi$. It is obvious that ϕ_{δ} is a smooth convex function on Ω , and $|\nabla \phi_{\delta}| < 1$. Therefore, Theorem 2.1 holds for each individual ϕ_{δ} . Namely

$$\int_{M} [T_{1}]_{ij} (\overline{\nabla}^{2} \phi_{\delta})(\phi_{\delta})_{i} n_{j} d\mu \leq \int_{M} H - \frac{1}{3} [T_{1}]_{\alpha\beta} (L)(\phi_{\delta})_{\alpha} (\phi_{\delta})_{\beta} d\mu.$$

When $\delta \to 0$, ϕ_{δ} converges to ϕ in C^{∞} on M. Thus the above inequality is also valid for ϕ . This finishes the proof of Theorem 2.1 for general $|\nabla \phi| \le 1$.

We now begin the proof of Proposition 3.3. The strategy we will apply is to expand ψ by the Taylor series and to derive a recursive inequality for each individual term $\int_M \Delta \phi |\nabla \phi|^{2k} d\mu$ in the Taylor series. Let us begin with the following lemma.

Lemma 3.4. Define

$$J_k := \int_M \Delta \phi |\nabla \phi|^{2k} d\mu.$$

Then

$$J_k = \frac{2k}{2k+1} \int_M [T_1]_{\alpha\beta}(\nabla^2 \phi) \phi_\alpha \phi_\beta |\nabla \phi|^{2(k-1)} d\mu. \tag{3.17}$$

Proof. By integration by parts

$$J_k := \int_M \Delta \phi |\nabla \phi|^{2k} d\mu$$

$$= \int_M -2k \phi_\alpha \phi_\beta \phi_{\alpha\beta} |\nabla \phi|^{2(k-1)} d\mu.$$
(3.18)

By the definition of $[T_1]$, $\phi_{\alpha\beta} = \Delta\phi\delta_{\alpha\beta} - [T_1]_{\alpha\beta}(\nabla^2\phi)$. Then

$$J_{k} = \int_{M} -2k\Delta\phi |\nabla\phi|^{2k} d\mu$$

$$+ \int_{M} 2k[T_{1}]_{\alpha\beta} (\nabla^{2}\phi)\phi_{\alpha}\phi_{\beta} |\nabla\phi|^{2(k-1)} d\mu$$

$$= -2kJ_{k} + \int_{M} 2k[T_{1}]_{\alpha\beta} (\nabla^{2}\phi)\phi_{\alpha}\phi_{\beta} |\nabla\phi|^{2(k-1)} d\mu.$$
(3.19)

Thus

$$J_k = \frac{2k}{2k+1} \int_M [T_1]_{\alpha\beta}(\nabla^2 \phi) \phi_\alpha \phi_\beta |\nabla \phi|^{2(k-1)} d\mu. \tag{3.20}$$

This finishes the proof of Lemma 3.4.

Proof of Proposition 3.3: First, by Taylor expansion

$$M_{2,1} := \int_{M} 2\Delta\phi \psi d\mu$$

$$= 2 \int_{M} \Delta\phi (1 - \sum_{k=1}^{\infty} C_{k} |\nabla\phi|^{2k}) d\mu.$$
(3.21)

Notice that $\int_M \Delta \phi d\mu=0$ and for $|\nabla \phi|<1$ the convergence in the Taylor expansion is uniform. Thus

$$M_{2,1} = -2\sum_{k=1}^{\infty} C_k J_k,$$

where $J_k := \int_M \Delta \phi |\nabla \phi|^{2k} d\mu$. Using Lemma 3.4, we get

$$M_{2,1} = -2\sum_{k=1}^{\infty} \frac{2k}{2k+1} C_k \int_M [T_1]_{\alpha\beta} (\nabla^2 \phi) \phi_{\alpha} \phi_{\beta} |\nabla \phi|^{2(k-1)} d\mu.$$

Since $\nabla^2_{\alpha\beta}\phi = \overline{\nabla}^2_{\alpha\beta}\phi - L_{\alpha\beta}\phi_n$,

$$M_{2,1} = -\sum_{k=1}^{\infty} \frac{4k}{2k+1} C_k \int_M [T_1]_{\alpha\beta} (\overline{\nabla}^2 \phi) \phi_{\alpha} \phi_{\beta} |\nabla \phi|^{2(k-1)} d\mu + \sum_{k=1}^{\infty} \frac{4k}{2k+1} C_k \int_M [T_1]_{\alpha\beta} (L) \phi_n \phi_{\alpha} \phi_{\beta} |\nabla \phi|^{2(k-1)} d\mu.$$
(3.22)

Since $[T_1]_{\alpha\beta}(\overline{\nabla}^2\phi) \geq 0$, the first sum in (3.22) is non-positive. Also, in the second sum, we notice $\frac{2}{2k+1} \leq \frac{2}{3}$ for any $k \geq 1$. Therefore

$$M_{2,1} \le \frac{2}{3} \int_{M} [T_1]_{\alpha\beta}(L) \phi_{\alpha} \phi_{\beta}(\sum_{k=1}^{\infty} 2kC_k |\nabla \phi|^{2(k-1)}) \phi_n d\mu.$$
 (3.23)

Now by Fact (b),

$$(\sum_{k=1}^{\infty} 2kC_k |\nabla \phi|^{2(k-1)}) \phi_n \le (\sum_{k=1}^{\infty} 2kC_k |\nabla \phi|^{2(k-1)}) \psi = 1.$$

Also we have $[T_1]_{\alpha\beta}(L)\phi_{\alpha}\phi_{\beta} \geq 0$. Therefore

$$\frac{2}{3} \int_{M} [T_1]_{\alpha\beta}(L) \phi_{\alpha} \phi_{\beta}(\sum_{k=1}^{\infty} 2kC_k |\nabla \phi|^{2(k-1)}) \phi_n d\mu \leq \frac{2}{3} \int_{M} [T_1]_{\alpha\beta}(L) \phi_{\alpha} \phi_{\beta} d\mu.$$

This completes the proof for $M_{2,1}$.

For the term $M_{2,2}$, it is straightforward to see that

$$M_{2,2} := \int_{M} H \psi^{2} + L_{\alpha\beta} \phi_{\alpha} \phi_{\beta} d\mu$$

$$= \int_{M} H - H |\nabla \phi|^{2} + L_{\alpha\beta} \phi_{\alpha} \phi_{\beta} d\mu$$

$$= \int_{M} H - [T_{1}]_{\alpha\beta}(L) \phi_{\alpha} \phi_{\beta} d\mu.$$
(3.24)

This finishes the proof of Proposition 3.3.

4. Proof of Theorem 2.2

In this section, we will prove

$$L_3 := \int_M [T_2]_{ij} (\overline{\nabla}^2 \phi) \phi_i n_j d\mu \le \int_{\partial \Omega} \sigma_2(L) - \frac{1}{4} \int_M [T_2]_{\alpha\beta}(L) \phi_\alpha \phi_\beta d\mu.$$

To prove this, we first decompose L_3 , using the multi-linearity of $[T_2]_{ij}(\cdot)$, into $L_3 = L_{3,1} + L_{3,2} + L_{3,3}$, where

$$L_{3,1} := \int_{M} [T_2]_{ij}(A, A)\phi_i n_j d\mu,$$

$$L_{3,2} := 2 \int_{M} [T_2]_{ij}(A, B)\phi_i n_j d\mu,$$

and

$$L_{3,3} := \int_{M} [T_2]_{ij}(B,B)\phi_i n_j d\mu.$$

A and B are as defined in (3.1) and (3.2).

Proposition 4.1.

$$L_{3,1} = 3 \int_{M} \sigma_2(\nabla^2 \phi) \phi_n d\mu - \int_{M} Ric_{\alpha\beta} \phi_{\alpha} \phi_{\beta} \phi_n d\mu. \tag{4.1}$$

$$L_{3,2} = \frac{3}{2} \int_{M} \Sigma_2(\nabla^2 \phi, L) \phi_n^2 d\mu + \int_{M} [T_1]_{\alpha\beta}(\nabla^2 \phi) L_{\beta\gamma} \phi_\alpha \phi_\gamma d\mu. \tag{4.2}$$

And

$$L_{3,3} = \int_{M} \sigma_2(L)\phi_n^3 d\mu + \int_{M} [T_1]_{\alpha\beta}(L)L_{\beta\gamma}\phi_\alpha\phi_\gamma\phi_n d\mu. \tag{4.3}$$

Here $\Sigma_2(A,B) := Tr(A)Tr(B) - Tr(AB)$ for any two tensors A and B. It is the linear polarization of $\sigma_2(\cdot)$ (up to a multiplicative constant) in the sense that $\Sigma_2(A,A) = 2\sigma_2(A)$, and it is symmetric and linear with respect to A and B. For polarization of σ_k , we refer to [CW11, CW]. The proof of Proposition 4.1 is by direct computation. Thus we omit it here. Now as what we did in the previous section, we define $M_{3,1}$, $M_{3,2}$, $M_{3,3}$, simply by substituting ϕ_n by ψ in the formulas of Proposition 4.1.

Definition 4.2.

$$M_{3,1} = 3 \int_{M} \sigma_2(\nabla^2 \phi) \psi d\mu - \int_{M} Ric_{\alpha\beta} \phi_{\alpha} \phi_{\beta} \psi d\mu. \tag{4.4}$$

$$M_{3,2} = \frac{3}{2} \int_{M} \Sigma_2(\nabla^2 \phi, L) \psi^2 d\mu + \int_{M} [T_1]_{\alpha\beta}(\nabla^2 \phi) L_{\beta\gamma} \phi_{\alpha} \phi_{\gamma} d\mu. \tag{4.5}$$

And

$$M_{3,3} = \int_{M} \sigma_2(L)\psi^3 d\mu + \int_{M} [T_1]_{\alpha\beta}(L) L_{\beta\gamma}\phi_{\alpha}\phi_{\gamma}\psi d\mu. \tag{4.6}$$

We first simplify the formula of $M_{3,2}$.

Proposition 4.3.

$$M_{3,2} = -2 \int_{M} [T_2]_{\alpha\beta}(\nabla^2 \phi, L) \phi_{\alpha} \phi_{\beta} d\mu. \tag{4.7}$$

Proof. Since $\psi^2 = 1 - |\nabla \phi|^2$, applying integration by parts we have

$$\int_{M} \Sigma_{2}(\nabla^{2}\phi, L)\psi^{2}d\mu$$

$$= \int_{M} (\Delta\phi H - \phi_{\alpha\beta}L_{\alpha\beta})(1 - |\nabla\phi|^{2})d\mu$$

$$= -\int_{M} \phi_{\alpha}H_{\alpha}(1 - |\nabla\phi|^{2}) + \phi_{\alpha}H(-2\phi_{\gamma}\phi_{\gamma\alpha})d\mu$$

$$+ \int_{M} \phi_{\alpha}L_{\alpha\beta,\beta}(1 - |\nabla\phi|^{2}) + \phi_{\alpha}L_{\alpha\beta}(-2\phi_{\gamma}\phi_{\gamma\beta})d\mu$$
(4.8)

By Codazzi equation $H_{\alpha} = L_{\alpha\beta,\beta}$. Hence the first term and the third term in the last equality above are canceled. So we have

$$\int_{M} \Sigma_{2}(\nabla^{2}\phi, L)\psi^{2}d\mu$$

$$=2 \int_{M} (\phi_{\alpha}H\phi_{\gamma}\phi_{\gamma\alpha} - \phi_{\alpha}L_{\alpha\beta}\phi_{\gamma}\phi_{\gamma\beta})d\mu$$

$$=2 \int_{M} \phi_{\alpha}\phi_{\gamma}[T_{1}]_{\alpha\beta}(L)\phi_{\beta\gamma}d\mu.$$
(4.9)

Substituting $\frac{1}{2} \int_M \Sigma_2(\nabla^2 \phi, L) \psi^2 d\mu$ by formula (4.9) in $M_{3,2}$, we have

$$M_{3,2} = (1 + \frac{1}{2}) \int_{M} \Sigma_{2}(\nabla^{2}\phi, L)\psi^{2}d\mu + \int_{M} [T_{1}]_{\alpha\beta}(\nabla^{2}\phi)L_{\beta\gamma}\phi_{\alpha}\phi_{\gamma}d\mu$$

$$= \int_{M} \Sigma_{2}(\nabla^{2}\phi, L)\psi^{2} + \phi_{\alpha}\phi_{\gamma}[T_{1}]_{\alpha\beta}(L)\phi_{\beta\gamma} + [T_{1}]_{\alpha\beta}(\nabla^{2}\phi)L_{\beta\gamma}\phi_{\alpha}\phi_{\gamma}d\mu$$

$$= \int_{M} \Sigma_{2}(\nabla^{2}\phi, L)(1 - |\nabla\phi|^{2}) + \phi_{\alpha}\phi_{\gamma}[T_{1}]_{\alpha\beta}(L)\phi_{\beta\gamma}$$

$$+ [T_{1}]_{\alpha\beta}(\nabla^{2}\phi)L_{\beta\gamma}\phi_{\alpha}\phi_{\gamma}d\mu.$$

$$(4.10)$$

By the Codazzi equation again,

$$\int_{M} \Sigma_{2}(\nabla^{2}\phi, L) d\mu = \int_{M} \phi_{\alpha} H_{\alpha} - \phi_{\alpha} L_{\alpha\beta,\beta} d\mu$$

$$= 0.$$
(4.11)

Therefore (4.10) implies

$$M_{3,2} = \int_{M} \Sigma_{2}(\nabla^{2}\phi, L)(-|\nabla\phi|^{2}) + \phi_{\alpha}\phi_{\gamma}[T_{1}]_{\alpha\beta}(L)\phi_{\beta\gamma}$$

$$+ [T_{1}]_{\alpha\beta}(\nabla^{2}\phi)L_{\beta\gamma}\phi_{\alpha}\phi_{\gamma}d\mu.$$

$$(4.12)$$

Using the fact that for tensors $A_{\alpha\beta}$, $B_{\alpha\beta}$

$$2[T_2]_{\alpha\gamma}(A,B) = \Sigma_2(A,B)\delta_{\alpha\gamma} - [T_1]_{\alpha\beta}(A)B_{\beta\gamma} - [T_1]_{\alpha\beta}(B)A_{\beta\gamma}, \quad (4.13)$$

we have

$$M_{3,2} = -2 \int_{M} [T_2]_{\alpha\beta}(\nabla^2 \phi, L) \phi_{\alpha} \phi_{\beta} d\mu. \tag{4.14}$$

Proposition 4.4. Define

$$A_k := \int_{\mathcal{M}} \sigma_2(\nabla^2 \phi) |\nabla \phi|^{2k} d\mu.$$

Then

$$A_{k} = \frac{k}{k+1} \int_{M} [T_{2}]_{\alpha\beta} (\nabla^{2}\phi, \nabla^{2}\phi) \phi_{\alpha} \phi_{\beta} |\nabla\phi|^{2(k-1)} d\mu + \frac{1}{2(k+1)} \int_{M} Ric_{\alpha\beta} \phi_{\alpha} \phi_{\beta} |\nabla\phi|^{2k} d\mu.$$

$$(4.15)$$

Proof. Applying properties of T_1 and the integration by parts, we have

$$A_{k} := \int_{M} \sigma_{2}(\nabla^{2}\phi) |\nabla\phi|^{2k} d\mu$$

$$= \int_{M} \frac{1}{2} \phi_{\alpha\beta} [T_{1}]_{\alpha\beta} (\nabla^{2}\phi) |\nabla\phi|^{2k} d\mu$$

$$= \int_{M} -\frac{1}{2} \phi_{\alpha} ([T_{1}]_{\alpha\beta} (\nabla^{2}\phi))_{\beta} |\nabla\phi|^{2k} - \frac{1}{2} \phi_{\alpha} [T_{1}]_{\alpha\beta} (\nabla^{2}\phi) (|\nabla\phi|^{2k})_{\beta} d\mu.$$

$$(4.16)$$

$$([T_1]_{\alpha\beta}(\nabla^2\phi))_{\beta} = (\Delta\phi\delta_{\alpha\beta} - \phi_{\alpha\beta})_{\beta} = -Ric_{\alpha\beta}\phi_{\beta}, \tag{4.17}$$

where $Ric_{\alpha\beta}$ denotes the Ricci curvature of M. Therefore (4.16) becomes

$$A_{k} = \int_{M} \frac{1}{2} \phi_{\alpha} \phi_{\beta} Ric_{\alpha\beta} |\nabla \phi|^{2k} - k \phi_{\alpha} [T_{1}]_{\alpha\beta} (\nabla^{2} \phi) \phi_{\gamma} \phi_{\gamma\beta} |\nabla \phi|^{2(k-1)} d\mu. \quad (4.18)$$

We now notice that $[T_1]_{\alpha\beta}(\nabla^2\phi)\phi_{\gamma\beta} = \sigma_2(\nabla^2\phi)\delta_{\alpha\gamma} - [T_2]_{\alpha\gamma}(\nabla^2\phi,\nabla^2\phi)$. Thus

$$A_{k} = \int_{M} \left[\frac{1}{2} \phi_{\alpha} \phi_{\beta} Ric_{\alpha\beta} |\nabla \phi|^{2k} - k \phi_{\alpha} \left(\sigma_{2} (\nabla^{2} \phi) \delta_{\alpha\gamma} - [T_{2}]_{\alpha\gamma} (\nabla^{2} \phi, \nabla^{2} \phi) \right) \phi_{\gamma} |\nabla \phi|^{2(k-1)} \right] d\mu$$

$$= \int_{M} \frac{1}{2} \phi_{\alpha} \phi_{\beta} Ric_{\alpha\beta} |\nabla \phi|^{2k} - k A_{k} + k \phi_{\alpha} [T_{2}]_{\alpha\gamma} (\nabla^{2} \phi, \nabla^{2} \phi) \phi_{\gamma} |\nabla \phi|^{2(k-1)} d\mu.$$

$$(4.19)$$

Therefore

$$A_{k} = \frac{k}{k+1} \int_{M} [T_{2}]_{\alpha\beta} (\nabla^{2}\phi, \nabla^{2}\phi) \phi_{\alpha} \phi_{\beta} |\nabla\phi|^{2(k-1)} d\mu + \frac{1}{2(k+1)} \int_{M} Ric_{\alpha\beta} \phi_{\alpha} \phi_{\beta} |\nabla\phi|^{2k} d\mu.$$

$$(4.20)$$

We will now assume $|\nabla \phi| < 1$ as in the previous section.

Corollary 4.5. Suppose ϕ in addition satisfies $|\nabla \phi| < 1$. Then

$$M_{3,1} = 3 \int_{M} \sigma_{2}(\nabla^{2}\phi)\psi d\mu - \int_{M} Ric_{\alpha\beta}\phi_{\alpha}\phi_{\beta}\psi d\mu$$

$$= -3 \int_{M} [T_{2}]_{\alpha\beta}(\nabla^{2}\phi, \nabla^{2}\phi)\phi_{\alpha}\phi_{\beta}F d\mu$$

$$+3 \int_{M} Ric_{\alpha\beta}\phi_{\alpha}\phi_{\beta}G d\mu - \int_{M} Ric_{\alpha\beta}\phi_{\alpha}\phi_{\beta}\psi d\mu,$$

$$(4.21)$$

where

$$F(x) := \sum_{k=1}^{\infty} \frac{k}{k+1} C_k |\nabla \phi|^{2(k-1)}.$$
$$G(x) := \frac{1}{2} - \sum_{k=1}^{\infty} \frac{1}{2(k+1)} C_k |\nabla \phi|^{2k}.$$

Proof. By Fact (a),

$$M_{3,1} = 3 \int_{M} \sigma_{2}(\nabla^{2}\phi)\psi d\mu - \int_{M} Ric_{\alpha\beta}\phi_{\alpha}\phi_{\beta}\psi d\mu$$

$$= 3 \int_{M} \sigma_{2}(\nabla^{2}\phi)(1 - \sum_{k=1}^{\infty} C_{k}|\nabla\phi|^{2k})d\mu - \int_{M} Ric_{\alpha\beta}\phi_{\alpha}\phi_{\beta}\psi d\mu \qquad (4.22)$$

$$= 3 \int_{M} \sigma_{2}(\nabla^{2}\phi)d\mu - 3 \sum_{k=1}^{\infty} C_{k}A_{k} - \int_{M} Ric_{\alpha\beta}\phi_{\alpha}\phi_{\beta}\psi d\mu.$$

Substituting the formula of A_k in Proposition 4.4 and the equality that

$$\int_{M} \sigma_{2}(\nabla^{2}\phi) d\mu = \frac{1}{2} \int_{M} \phi_{\alpha\beta}(\Delta\phi\delta_{\alpha\beta} - \phi_{\alpha\beta}) d\mu$$

$$= \frac{1}{2} \int_{M} -\phi_{\alpha} \left((\Delta\phi)_{\alpha} - \phi_{\alpha\beta,\beta} \right) d\mu$$

$$= \frac{1}{2} \int_{M} Ric_{\alpha\beta}\phi_{\alpha}\phi_{\beta}d\mu,$$
(4.23)

in (4.22), we derive (4.21).

Applying Proposition 4.3 and Corollary 4.5, we get

$$M_{3,1} + M_{3,2} + M_{3,3}$$

$$= -3 \int_{M} [T_{2}]_{\alpha\beta} (\nabla^{2}\phi, \nabla^{2}\phi) \phi_{\alpha} \phi_{\beta} F d\mu + 3 \int_{M} Ric_{\alpha\beta} \phi_{\alpha} \phi_{\beta} G d\mu$$

$$-2 \int_{M} [T_{2}]_{\alpha\beta} (\nabla^{2}\phi, L) \phi_{\alpha} \phi_{\beta} d\mu + \int_{M} \sigma_{2}(L) \psi^{3} d\mu$$

$$+ \int_{M} Ric_{\alpha\beta} \phi_{\alpha} \phi_{\beta} \psi d\mu - \int_{M} [T_{1}]_{\alpha\beta} (L) L_{\beta\gamma} \phi_{\alpha} \phi_{\gamma} \psi d\mu.$$

$$(4.24)$$

By the Gauss equation,

$$Ric_{\alpha\beta} = [T_1]_{\alpha\gamma}(L)L_{\gamma\beta}.$$
 (4.25)

Thus the last two terms in (4.24) are canceled. Therefore

$$M_{3,1} + M_{3,2} + M_{3,3}$$

$$= -3 \int_{M} [T_{2}]_{\alpha\beta} (\nabla^{2}\phi, \nabla^{2}\phi) \phi_{\alpha} \phi_{\beta} F d\mu + 3 \int_{M} Ric_{\alpha\beta} \phi_{\alpha} \phi_{\beta} G d\mu$$

$$-2 \int_{M} [T_{2}]_{\alpha\beta} (\nabla^{2}\phi, L) \phi_{\alpha} \phi_{\beta} d\mu + \int_{M} \sigma_{2}(L) \psi^{3} d\mu.$$

$$(4.26)$$

We now apply Fact (c): $3G|\nabla\phi|^2 = 1 - \psi^3$ to combine the second and the last term in (4.26)

$$3\int_{M} Ric_{\alpha\beta}\phi_{\alpha}\phi_{\beta}Gd\mu + \int_{M} \sigma_{2}(L)\psi^{3}d\mu$$

$$=3\int_{M} Ric_{\alpha\beta}\phi_{\alpha}\phi_{\beta}Gd\mu + \int_{M} \sigma_{2}(L)(1-3G|\nabla\phi|^{2})d\mu$$

$$(4.27)$$

By (4.25) and the fact that

$$[T_1]_{\alpha\gamma}(L)L_{\gamma\beta} - \sigma_2(L)\delta_{\alpha\beta} = [T_2]_{\alpha\beta}(L,L), \tag{4.28}$$

(4.27) is equal to

$$3\int_{M} [T_{1}]_{\alpha\gamma}(L)L_{\gamma\beta}\phi_{\alpha}\phi_{\beta}Gd\mu + \int_{M} \sigma_{2}(L)(1 - 3G|\nabla\phi|^{2})d\mu$$

$$= \int_{M} \sigma_{2}(L)d\mu - 3\int_{M} [T_{2}]_{\alpha\beta}(L,L)\phi_{\alpha}\phi_{\beta}Gd\mu.$$

$$(4.29)$$

In conclusion (4.26) is deduced to

$$M_{3,1} + M_{3,2} + M_{3,3} = \int_{M} \sigma_2(L)d\mu + E_1 + E_2 + E_3,$$
 (4.30)

where

$$E_{1} = -3 \int_{M} [T_{2}]_{\alpha\beta} (\nabla^{2}\phi, \nabla^{2}\phi) \phi_{\alpha} \phi_{\beta} F d\mu$$

$$E_{2} = -2 \int_{M} [T_{2}]_{\alpha\beta} (\nabla^{2}\phi, L) \phi_{\alpha} \phi_{\beta} d\mu$$

$$E_{3} = -3 \int_{M} [T_{2}]_{\alpha\beta} (L, L) \phi_{\alpha} \phi_{\beta} G d\mu.$$

$$(4.31)$$

In the following we will prove

Proposition 4.6. If ϕ in addition satisfies $|\nabla \phi| < 1$, then

$$E_1 + E_2 + E_3 \le -\frac{1}{4} \int_M [T_2]_{\alpha\beta}(L) \phi_{\alpha} \phi_{\beta} d\mu.$$
 (4.32)

From this, it is obvious that for ϕ satisfying $|\nabla \phi| < 1$,

$$M_{3,1} + M_{3,2} + M_{3,3} \le \int_{M} \sigma_2(L) d\mu - \frac{1}{4} \int_{M} [T_2]_{\alpha\beta}(L) \phi_\alpha \phi_\beta d\mu.$$
 (4.33)

Proof. By $\nabla^2_{\alpha\beta}\phi = \overline{\nabla}^2_{\alpha\beta}\phi - L_{\alpha\beta}\phi_n$, we obtain

$$E_{1} = -3 \int_{M} [T_{2}]_{\alpha\beta} (\overline{\nabla}^{2} \phi - L\phi_{n}, \overline{\nabla}^{2} \phi - L\phi_{n}) \phi_{\alpha} \phi_{\beta} F d\mu$$

$$= -3 \int_{M} [T_{2}]_{\alpha\beta} (\overline{\nabla}^{2} \phi, \overline{\nabla}^{2} \phi) \phi_{\alpha} \phi_{\beta} F d\mu$$

$$+6 \int_{M} [T_{2}]_{\alpha\beta} (\overline{\nabla}^{2} \phi, L) \phi_{n} \phi_{\alpha} \phi_{\beta} F d\mu$$

$$-3 \int_{M} [T_{2}]_{\alpha\beta} (L, L) \phi_{n}^{2} \phi_{\alpha} \phi_{\beta} F d\mu$$

$$=: E_{1,1} + E_{1,2} + E_{1,3}$$

$$(4.34)$$

Since ϕ is a convex function, $\overline{\nabla}^2 \phi$ is nonnegative. Therefore

$$[T_2]_{\alpha\beta}(\overline{\nabla}^2\phi,\overline{\nabla}^2\phi) \ge 0.$$
 (4.35)

This together with $F \ge 0$ implies that $E_{1,1} \le 0$. So $E_1 \le E_{1,2} + E_{1,3}$.

For E_2 , using $\nabla^2_{\alpha\beta}\phi = \overline{\nabla}^2_{\alpha\beta}\phi - L_{\alpha\beta}\phi_n$, we get

$$E_{2} = -2 \int_{M} [T_{2}]_{\alpha\beta} (\overline{\nabla}^{2} \phi, L) \phi_{\alpha} \phi_{\beta} d\mu$$

$$+ 2 \int_{M} [T_{2}]_{\alpha\beta} (L, L) \phi_{n} \phi_{\alpha} \phi_{\beta} d\mu$$

$$:= E_{2,1} + E_{2,2}.$$

$$(4.36)$$

We next observe that

Lemma 4.7.

$$E_{1,2} + E_{2,1} \le -\frac{1}{2} \int_{M} [T_2]_{\alpha\beta} (\overline{\nabla}^2 \phi, L) \phi_{\alpha} \phi_{\beta} d\mu \le 0.$$
 (4.37)

Proof.

$$E_{1,2} + E_{2,1} = \int_{M} [T_2]_{\alpha\beta} (\overline{\nabla}^2 \phi, L) \phi_{\alpha} \phi_{\beta} (6F\phi_n - 2) d\mu. \tag{4.38}$$

On the one hand, $6F\phi_n - 2 \le -\frac{1}{2}$ because $F\phi_n \le F\psi$, and $F\psi \le \frac{1}{4}$ (Fact (e)); on the other hand, since $L_{\alpha\beta} \in \Gamma_3^+$ and $\overline{\nabla}^2 \phi \ge 0$, we have

$$[T_2]_{\alpha\beta}(\overline{\nabla}^2\phi, L) \ge 0.$$
 (4.39)

Therefore

$$E_{1,2} + E_{2,1} \le -\frac{1}{2} \int_{M} [T_2]_{\alpha\beta} (\overline{\nabla}^2 \phi, L) \phi_{\alpha} \phi_{\beta} d\mu \le 0.$$
 (4.40)

We continue the proof of Proposition 4.6. Applying Lemma 4.7, we have

$$E_1 + E_2 + E_3 \le E_{1,3} + E_{2,2} + E_3$$

$$= \int_M [T_2]_{\alpha\beta}(L)\phi_\alpha\phi_\beta P(x)d\mu,$$
(4.41)

where
$$P(x) := -3F\phi_n^2 + 2\phi_n - 3G$$
. By Fact (d), $2G = \psi + F|\nabla\phi|^2$. Thus
$$P = -3F\phi_n^2 + 2\phi_n - \frac{3}{2}\psi - \frac{3}{2}|\nabla\phi|^2.$$

It is not hard to show $P \leq -\frac{1}{4}$. In fact,

$$P = -3F\phi_n^2 + 2\phi_n - \frac{3}{2}\psi - \frac{3}{2}F|\nabla\phi|^2$$

$$= -3\sum_{k=1}^{\infty} \frac{k}{k+1}C_k|\nabla\phi|^{2(k-1)}\phi_n^2 + 2\phi_n - \frac{3}{2}\psi - \frac{3}{2}\sum_{k=1}^{\infty} \frac{k}{k+1}C_k|\nabla\phi|^{2k}.$$
(4.42)

To estimate $-3\sum_{k=1}^{\infty} \frac{k}{k+1} C_k |\nabla \phi|^{2(k-1)} \phi_n^2$ in (4.42), we observe $C_k \geq 0$, and $C_1 = \frac{1}{2}$. So we drop the sum over $k \geq 2$ and get

$$-3\sum_{k=1}^{\infty} \frac{k}{k+1} C_k |\nabla \phi|^{2(k-1)} \phi_n^2 \le -\frac{3}{4} \phi_n^2. \tag{4.43}$$

And to estimate $-\frac{3}{2}\sum_{k=1}^{\infty}\frac{k}{k+1}C_k|\nabla\phi|^{2k}$ in (4.42), we use the fact that $\frac{k}{k+1}\geq \frac{1}{2}$ for all $k\geq 1$, and Fact (a): $\psi=1-\sum_{k=1}^{\infty}C_k|\nabla\phi|^{2k}$ to get

$$-\frac{3}{2}\sum_{k=1}^{\infty} \frac{k}{k+1} C_k |\nabla \phi|^{2k} \le -\frac{3}{4}\sum_{k=1}^{\infty} C_k |\nabla \phi|^{2k} = -\frac{3}{4} (1-\psi). \tag{4.44}$$

Applying (4.43) and (4.44) to (4.42), we have

$$P \le -\frac{3}{4}\phi_n^2 + 2\phi_n - \frac{3}{2}\psi - \frac{3}{4}(1 - \psi)$$

$$\le -\frac{3}{4}\phi_n^2 + 2\phi_n - \frac{3}{4}\phi_n - \frac{3}{4},$$
(4.45)

due to the fact that $\phi_n \leq \psi$. Now

$$-\frac{3}{4}\phi_n^2 + 2\phi_n - \frac{3}{4}\phi_n - \frac{3}{4} = -\frac{1}{4}(3\phi_n - 2)(\phi_n - 1) - \frac{1}{4} \le -\frac{1}{4},\tag{4.46}$$

for $\phi_n \leq 1$. Thus we obtain $P \leq -\frac{1}{4}$. By (4.41), it concludes that

$$E_1 + E_2 + E_3 \le -\frac{1}{4} \int_M [T_2]_{\alpha\beta}(L) \phi_\alpha \phi_\beta d\mu \le 0.$$
 (4.47)

This completes the proof of Proposition 4.6

Finally, we are ready to give the proof of Theorem 2.2 using Proposition 4.6.

Proof. By Proposition 4.1 and Definition 4.2

$$L_{3} = L_{3,1} + L_{3,2} + L_{3,3}$$

$$= M_{3,1} + M_{3,2} + M_{3,3} + \int_{M} 3\sigma_{2}(\nabla^{2}\phi)(\phi_{n} - \psi)$$

$$+ \frac{3}{2}\Sigma_{2}(\nabla^{2}\phi, L)(\phi_{n}^{2} - \psi^{2}) + \sigma_{2}(L)(\phi_{n}^{3} - \psi^{3})d\mu.$$

$$(4.48)$$

We will prove

$$\int_{M} 3\sigma_{2}(\nabla^{2}\phi)(\phi_{n} - \psi) + \frac{3}{2}\Sigma_{2}(\nabla^{2}\phi, L)(\phi_{n}^{2} - \psi^{2}) + \sigma_{2}(L)(\phi_{n}^{3} - \psi^{3})d\mu \le 0.$$
(4.49)

Recall that $\Sigma_2(A, B) := Tr(A)Tr(B) - Tr(AB)$. This immediately implies that

$$\sigma_2(A) = \frac{1}{2}\Sigma_2(A, A).$$

Using $\nabla^2_{\alpha\beta}\phi = \overline{\nabla}^2_{\alpha\beta}\phi - L_{\alpha\beta}\phi_n$ and the linearity of $\Sigma_2(\cdot,\cdot)$, first of all

$$3\int_{M} \sigma_{2}(\nabla^{2}\phi)(\phi_{n} - \psi)d\mu$$

$$= \frac{3}{2}\int_{M} \Sigma_{2}(\overline{\nabla}_{\alpha\beta}^{2}\phi - L_{\alpha\beta}\phi_{n}, \overline{\nabla}_{\alpha\beta}^{2}\phi - L_{\alpha\beta}\phi_{n})(\phi_{n} - \psi)d\mu$$

$$= \int_{M} 3\sigma_{2}(\overline{\nabla}^{2}\phi)(\phi_{n} - \psi) - 3\Sigma_{2}(\overline{\nabla}^{2}\phi, L)\phi_{n}(\phi_{n} - \psi) + 3\sigma_{2}(L)\phi_{n}^{2}(\phi_{n} - \psi)d\mu.$$
(4.50)

Since $\sigma_2(\overline{\nabla}^2\phi) \geq 0$ and $\phi_n \leq \psi$, the first term in the above line is non-positive. Thus

$$3\int_{M} \sigma_{2}(\nabla^{2}\phi)(\phi_{n} - \psi)d\mu$$

$$\leq \int_{M} -3\Sigma_{2}(\overline{\nabla}^{2}\phi, L)\phi_{n}(\phi_{n} - \psi) + 3\sigma_{2}(L)\phi_{n}^{2}(\phi_{n} - \psi)d\mu,$$

$$(4.51)$$

Secondly,

$$\frac{3}{2}\Sigma_{2}(\nabla^{2}\phi, L)(\phi_{n}^{2} - \psi^{2})$$

$$= \frac{3}{2}\Sigma_{2}(\overline{\nabla}^{2}\phi, L)(\phi_{n}^{2} - \psi^{2}) - 3\sigma_{2}(L)\phi_{n}(\phi_{n}^{2} - \psi^{2}).$$
(4.52)

Using (4.51) and (4.52), we have

$$\int_{M} 3\sigma_{2}(\nabla^{2}\phi)(\phi_{n} - \psi) + \frac{3}{2}\Sigma_{2}(\nabla^{2}\phi, L)(\phi_{n}^{2} - \psi^{2}) + \sigma_{2}(L)(\phi_{n}^{3} - \psi^{3})d\mu$$

$$\leq -3 \int_{M} \Sigma_{2}(\overline{\nabla}^{2}\phi, L) \left(\phi_{n}(\phi_{n} - \psi) - \frac{1}{2}(\phi_{n}^{2} - \psi^{2})\right) d\mu$$

$$+ \int_{M} \sigma_{2}(L) \left(3\phi_{n}^{2}(\phi_{n} - \psi) - 3\phi_{n}(\phi_{n}^{2} - \psi^{2}) + (\phi_{n}^{3} - \psi^{3})\right) d\mu$$

$$= -\frac{3}{2} \int_{M} \Sigma_{2}(\overline{\nabla}^{2}\phi, L)(\phi_{n} - \psi)^{2} d\mu$$

$$+ \int_{M} \sigma_{2}(L)(\phi_{n} - \psi)^{3} d\mu.$$
(4.53)

This is less or equal than 0, due to the fact that $\Sigma_2(\overline{\nabla}^2\phi, L) \geq 0$, $\sigma_2(L) \geq 0$ and $\phi_n \leq \psi$. Thus (4.49) is proved.

Plugging (4.49) into (4.48) and applying Proposition 4.6, we conclude that for ϕ satisfying $|\nabla \phi| < 1$,

$$L_{3} \leq M_{3,1} + M_{3,2} + M_{3,3}$$

$$\leq \int_{M} \sigma_{2}(L)d\mu - \frac{1}{4} \int_{M} [T_{2}]_{\alpha\beta}(L)\phi_{\alpha}\phi_{\beta}d\mu. \tag{4.54}$$

As in the previous section, if $|\nabla \phi| \leq 1$, then we can apply the above argument to $\phi_{\delta} := (1 - \delta) \cdot \phi$ and take $\delta \to 0$. This completes the proof of Theorem 2.2.

References

- [Ale37] A. D. Alexandroff, Zur Theorie der gemischten Volumina von konvexen Körpern, II. Neue Ungleichungen zwischen den gemischten Volumina und ihre Anwendungen (in Russian), Mat. Sb. (N.S.) 2 (1937), 1205-1238.
- [Bre91] Y. Brenier, Polar factorization and monotone rearrangement of vector-valued functions, Comm. Pure Appl. Math. 44 (1991), no. 4, 375–417.
- [Caf92a] L. A. Caffarelli, Boundary regularity of maps with convex potentials, Comm. Pure Appl. Math. 45 (1992), no. 9, 1141–1151.
- [Caf92b] L. A. Caffarelli, The regularity of mappings with a convex potential, J. Amer. Math. Soc. 5 (1992), no. 1, 99–104.
- [Caf96] L. A. Caffarelli, Boundary regularity of maps with convex potentials. II, Ann. of Math. (2) 144 (1996), no. 3, 453–496.
- [Cas10] P. Castillon, Submanifolds, isoperimetric inequalities and optimal transportation, J. Funct. Anal. 259 (2010), no. 1, 79–103.
- [CW11] S.-Y. A. Chang and Y. Wang, On Aleksandrov-Fenchel inequalities for kconvex domains, Milan J. Math. 79 (2011), no. 1, 13–38.
 - [CW] S.-Y. A. Chang and Y. Wang, Inequalities for quermassintegrals on k-convex domains, in submission.
- [CENV04] D. Cordero-Erausquin, B. Nazaret, and C. Villani, A mass-transportation approach to sharp Sobolev and Gagliardo-Nirenberg inequalities, Adv. Math. 182 (2004), no. 2, 307–332.
 - [DG58] E. De Giorgi, Sulla proprietà isoperimetrica dell'ipersfera, nella classe degli insiemi aventi frontiera orientata di misura finita, Atti Accad. Naz. Lincei. Mem. Cl. Sci. Fis. Mat. Nat. Sez. I (8) 5 (1958), 33–44.
 - [FMP10] A. Figalli, F. Maggi, and A. Pratelli, A mass transportation approach to quantitative isoperimetric inequalities, Invent. Math. 182 (2010), no. 1, 167–211.
 - [Gro85] M. Gromov, Isometric immersions of Riemannian manifolds, Astérisque Numero Hors Serie (1985), 129–133. The mathematical heritage of Élie Cartan (Lyon, 1984).
 - [GL09] P. Guan and J. Li, The quermassintegral inequalities for k-convex starshaped domains, Adv. Math. **221** (2009), no. 5, 1725–1732.
 - [Hui] G. Huisken, private communication.
 - [HI01] G. Huisken and T. Ilmanen, The inverse mean curvature flow and the Riemannian Penrose inequality, J. Differential Geom. **59** (2001), no. 3, 353–437.
 - [McC97] R. J. McCann, A convexity principle for interacting gases, Adv. Math. 128 (1997), no. 1, 153–179.
 - [Min11] H. Minkowski, Theorie der konvexen Körper, insbesondere Begründung ihres Oberflächenbegriffs., Ges, Abh., Leipzig-Berlin 2 (1911), 131-229.

- [Sch84] H. A. Schwartz, Beweis des Satzes, dass die Kugel kleinere Oberfläche besitzt, als jeder andere Körper gleichen Volumens., Nachrichten Königlichen Gesellschaft Wissenschaften Göttingen (1884), 1-13.
- [Tru94] N. S. Trudinger, Isoperimetric inequalities for quermassintegrals, Ann. Inst. H. Poincaré Anal. Non Linéaire 11 (1994), no. 4, 411–425.

Sun-Yung A. Chang, Department of Mathematics, Princeton University, Princeton NJ 08544, USA

EMAIL: CHANG@MATH.PRINCETON.EDU

YI WANG, DEPARTMENT OF MATHEMATICS, STANFORD UNIVERSITY, STANFORD CA 94305, USA

EMAIL: WANGYI@MATH.STANFORD.EDU