# Remarks on the fractional Laplacian with Dirichlet boundary conditions and applications 

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#### Abstract

We prove nonlinear lower bounds and commutator estimates for the Dirichlet fractional Laplacian in bounded domains. The applications include bounds for linear drift-diffusion equations with nonlocal dissipation and global existence of weak solutions of critical surface quasi-geostrophic equations.


## 1. Introduction

Drift-diffusion equations with nonlocal dissipation naturally occur in hydrodynamics and in models of electroconvection. The study of these equations in bounded domains is hindered by a lack of explicit information on the kernels of the nonlocal operators appearing in them. In this paper we develop tools adapted for the Dirichlet boundary case: the Córdoba-Córdoba inequality ( $[\mathbf{3}]$ ) and a nonlinear lower bound in the spirit of ([2]), and commutator estimates. Lower bounds for the fractional Laplacian are instrumental in proofs of regularity of solutions to nonlinear nonlocal drift-diffusion equations. The presence of boundaries requires natural modifications of the bounds. The nonlinear bounds are proved using a representation based on the heat kernel and fine information regarding it ([4], [7], [8]). Nonlocal diffusion operators in bounded domains do not commute in general with differentiation. The commutator estimates are proved using the method of harmonic extension and results of ([1]). We apply these tools to linear drift-diffusion equations with nonlocal dissipation, where we obtain strong global bounds, and to global existence of weak solutions of the surface quasi-geostrophic equation (SQG) in bounded domains.

We consider a bounded open domain $\Omega \subset \mathbb{R}^{d}$ with smooth (at least $C^{2, \alpha}$ ) boundary. We denote by $\Delta$ the Laplacian operator with homogeneous Dirichlet boundary conditions. Its $L^{2}(\Omega)$ - normalized eigenfunctions are denoted $w_{j}$, and its eigenvalues counted with their multiplicities are denoted $\lambda_{j}$ :

$$
\begin{equation*}
-\Delta w_{j}=\lambda_{j} w_{j} \tag{1}
\end{equation*}
$$

It is well known that $0<\lambda_{1} \leq \ldots \leq \lambda_{j} \rightarrow \infty$ and that $-\Delta$ is a positive selfadjoint operator in $L^{2}(\Omega)$ with domain $\mathcal{D}(-\Delta)=H^{2}(\Omega) \cap H_{0}^{1}(\Omega)$. The ground state $w_{1}$ is positive and

$$
\begin{equation*}
c_{0} d(x) \leq w_{1}(x) \leq C_{0} d(x) \tag{2}
\end{equation*}
$$

holds for all $x \in \Omega$, where

$$
\begin{equation*}
d(x)=\operatorname{dist}(x, \partial \Omega) \tag{3}
\end{equation*}
$$

and $c_{0}, C_{0}$ are positive constants depending on $\Omega$. Functional calculus can be defined using the eigenfunction expansion. In particular

$$
\begin{equation*}
(-\Delta)^{\alpha} f=\sum_{j=1}^{\infty} \lambda_{j}^{\alpha} f_{j} w_{j} \tag{4}
\end{equation*}
$$

with

$$
f_{j}=\int_{\Omega} f(y) w_{j}(y) d y
$$

for $f \in \mathcal{D}\left((-\Delta)^{\alpha}\right)=\left\{f \mid\left(\lambda_{j}^{\alpha} f_{j}\right) \in \ell^{2}(\mathbb{N})\right\}$. We will denote by

$$
\begin{equation*}
\Lambda_{D}^{s}=(-\Delta)^{\alpha}, \quad s=2 \alpha \tag{5}
\end{equation*}
$$

the fractional powers of the Dirichlet Laplacian, with $0 \leq \alpha \leq 1$ and with $\|f\|_{s, D}$ the norm in $\mathcal{D}\left(\Lambda_{D}^{s}\right)$ :

$$
\begin{equation*}
\|f\|_{s, D}^{2}=\sum_{j=1}^{\infty} \lambda_{j}^{s} f_{j}^{2} \tag{6}
\end{equation*}
$$

It is well-known and easy to show that

$$
\mathcal{D}\left(\Lambda_{D}\right)=H_{0}^{1}(\Omega) .
$$

Indeed, for $f \in \mathcal{D}(-\Delta)$ we have

$$
\|\nabla f\|_{L^{2}(\Omega)}^{2}=\int_{\Omega} f(-\Delta) f d x=\left\|\Lambda_{D} f\right\|_{L^{2}(\Omega)}^{2}=\|f\|_{1, D}^{2}
$$

We recall that the Poincaré inequality implies that the Dirichlet integral on the left-hand side above is equivalent to the norm in $H_{0}^{1}(\Omega)$ and therefore the identity map from the dense subset $\mathcal{D}(-\Delta)$ of $H_{0}^{1}(\Omega)$ to $\mathcal{D}\left(\Lambda_{D}\right)$ is an isometry, and thus $H_{0}^{1}(\Omega) \subset \mathcal{D}\left(\Lambda_{D}\right)$. But $\mathcal{D}(-\Delta)$ is dense in $\mathcal{D}\left(\Lambda_{D}\right)$ as well, because finite linear combinations of eigenfunctions are dense in $\mathcal{D}\left(\Lambda_{D}\right)$. Thus the opposite inclusion is also true, by the same isometry argument.
Note that in view of the identity

$$
\begin{equation*}
\lambda^{\alpha}=c_{\alpha} \int_{0}^{\infty}\left(1-e^{-t \lambda}\right) t^{-1-\alpha} d t, \tag{7}
\end{equation*}
$$

with

$$
1=c_{\alpha} \int_{0}^{\infty}\left(1-e^{-s}\right) s^{-1-\alpha} d s
$$

valid for $0 \leq \alpha<1$, we have the representation

$$
\begin{equation*}
\left((-\Delta)^{\alpha} f\right)(x)=c_{\alpha} \int_{0}^{\infty}\left[f(x)-e^{t \Delta} f(x)\right] t^{-1-\alpha} d t \tag{8}
\end{equation*}
$$

for $f \in \mathcal{D}\left((-\Delta)^{\alpha}\right)$. We use precise upper and lower bounds for the kernel $H_{D}(t, x, y)$ of the heat operator,

$$
\begin{equation*}
\left(e^{t \Delta} f\right)(x)=\int_{\Omega} H_{D}(t, x, y) f(y) d y \tag{9}
\end{equation*}
$$

These are as follows ([4],[7],[8]). There exists a time $T>0$ depending on the domain $\Omega$ and constants $c$, $C, k, K$, depending on $T$ and $\Omega$ such that

$$
\begin{align*}
& c \min \left(\frac{w_{1}(x)}{\mid x-y}, 1\right) \min \left(\frac{w_{1}(y)}{x-y}, 1\right) t^{-\frac{d}{2}} e^{-\frac{|x-y|^{2}}{k t}} \leq \\
& H_{D}(t, x, y) \leq C \min \left(\frac{w_{1}(x)}{|x-y|}, 1\right) \min \left(\frac{w_{1}(y)}{|x-y|}, 1\right) t^{-\frac{d}{2}} e^{-\frac{|x-y|^{2}}{K t}} \tag{10}
\end{align*}
$$

holds for all $0 \leq t \leq T$. Moreover

$$
\frac{\left|\nabla_{x} H_{D}(t, x, y)\right|}{H_{D}(t, x, y)} \leq C \begin{cases}\frac{1}{d(x)}, & \text { if } \sqrt{t} \geq d(x)  \tag{11}\\ \frac{1}{\sqrt{t}}\left(1+\frac{|x-y|}{\sqrt{t}}\right), & \text { if } \sqrt{t} \leq d(x)\end{cases}
$$

holds for all $0 \leq t \leq T$. Note that, in view of

$$
\begin{equation*}
H_{D}(t, x, y)=\sum_{j=1}^{\infty} e^{-t \lambda_{j}} w_{j}(x) w_{j}(y) \tag{12}
\end{equation*}
$$

elliptic regularity estimates and Sobolev embedding which imply uniform absolute convergence of the series (if $\partial \Omega$ is smooth enough), we have that

$$
\begin{equation*}
\partial_{1}^{\beta} H_{D}(t, y, x)=\partial_{2}^{\beta} H_{D}(t, x, y)=\sum_{j=1}^{\infty} e^{-t \lambda_{j}} \partial_{y}^{\beta} w_{j}(y) w_{j}(x) \tag{13}
\end{equation*}
$$

for positive $t$, where we denoted by $\partial_{1}^{\beta}$ and $\partial_{2}^{\beta}$ derivatives with respect to the first spatial variables and the second spatial variables, respectively.

Therefore, the gradient bounds (11) result in

$$
\frac{\left|\nabla_{y} H_{D}(t, x, y)\right|}{H_{D}(t, x, y)} \leq C \begin{cases}\frac{1}{d(y)}, & \text { if } \sqrt{t} \geq d(y)  \tag{14}\\ \frac{1}{\sqrt{t}}\left(1+\frac{|x-y|}{\sqrt{t}}\right), & \text { if } \sqrt{t} \leq d(y)\end{cases}
$$

## 2. The Córdoba - Córdoba inequality

Proposition 1. Let $\Phi$ be a $C^{2}$ convex function satisfying $\Phi(0)=0$. Let $f \in C_{0}^{\infty}(\Omega)$ and let $0 \leq s \leq$ 2. Then

$$
\begin{equation*}
\Phi^{\prime}(f) \Lambda_{D}^{s} f-\Lambda_{D}^{s}(\Phi(f)) \geq 0 \tag{15}
\end{equation*}
$$

holds pointwise almost everywhere in $\Omega$.
Proof. In view of the fact that both $f \in H_{0}^{1}(\Omega) \cap H^{2}(\Omega)$ and $\Phi(f) \in H_{0}^{1}(\Omega) \cap H^{2}(\Omega)$, the terms in the inequality $(15)$ are well defined. We define

$$
\begin{equation*}
\left[(-\Delta)^{\alpha} f\right]_{\epsilon}(x)=c_{\alpha} \int_{\epsilon}^{\infty}\left[f(x)-e^{t \Delta} f(x)\right] t^{-1-\alpha} d t \tag{16}
\end{equation*}
$$

and approximate the representation (8):

$$
\begin{equation*}
\left((-\Delta)^{\alpha} f\right)(x)=\lim _{\epsilon \rightarrow 0}\left[(-\Delta)^{\alpha} f\right]_{\epsilon}(x) \tag{17}
\end{equation*}
$$

The limit is strong in $L^{2}(\Omega)$. We start the calculation with this approximation and then we rearrange terms:

$$
\begin{aligned}
& \Phi^{\prime}(f(x))\left[\Lambda_{D}^{2 \alpha} f\right]_{\epsilon}(x)-\left[\Lambda_{D}^{2 \alpha}(\Phi(f))\right]_{\epsilon}(x) \\
& =c_{\alpha} \int_{\epsilon}^{\infty} t^{-1-\alpha} d t \int_{\Omega}\left\{\Phi^{\prime}(f(x))\left[\frac{1}{|\Omega|} f(x)-H_{D}(t, x, y) f(y)\right]-\frac{1}{|\Omega|} \Phi(f(x))+H_{D}(t, x, y) \Phi(f(y))\right\} d y \\
& =c_{\alpha} \int_{\epsilon}^{\infty} t^{-1-\alpha} d t \int_{\Omega} H_{D}(t, x, y)\left[\Phi(f(y))-\Phi(f(x))-\Phi^{\prime}(f(x))(f(y)-f(x))\right] d y \\
& \left.+c_{\alpha} \int_{\epsilon}^{\infty} t^{-1-\alpha} d t \int_{\Omega}\left[f(x) \Phi^{\prime}(f(x))-\Phi(f(x))\right]\left(\frac{1}{|\Omega|}-H_{D}(t, x) y\right)\right) d y \\
& =c_{\alpha} \int_{\epsilon}^{\infty} t^{-1-\alpha} d t \int_{\Omega} H_{D}(t, x, y)\left[\Phi(f(y))-\Phi(f(x))-\Phi^{\prime}(f(x))(f(y)-f(x))\right] d y \\
& +\left[f(x) \Phi^{\prime}(f(x))-\Phi(f(x))\right] c_{\alpha} \int_{\epsilon}^{\infty} t^{-1-\alpha}\left(1-e^{t \Delta} 1\right) d t
\end{aligned}
$$

Because of the convexity of $\Phi$ we have

$$
\Phi(b)-\Phi(a)-\Phi^{\prime}(a)(b-a) \geq 0, \quad \forall a, b \in \mathbb{R}
$$

and because $\Phi(0)=0$ we have

$$
a \Phi^{\prime}(a) \geq \Phi(a), \quad \forall a \in \mathbb{R} .
$$

Consequently $f(x) \Phi^{\prime}(f(x))-\Phi(f(x)) \geq 0$ holds everywhere. The function

$$
\theta=e^{t \Delta} 1
$$

solves the heat equation $\partial_{t} \theta-\Delta \theta=0$ in $\Omega$, with homogeneous Dirichlet boundary conditions, and with initial data equal everywhere to 1 . Although 1 is not in the domain of $-\Delta$, $e^{t \Delta}$ has a unique extension to $L^{2}(\Omega)$ where 1 does belong, and on the other hand, by the maximum principle $0 \leq \theta(x, t) \leq 1$ holds for $t \geq 0, x \in \Omega$. It is only because $1 \notin \mathcal{D}(-\Delta)$ that we had to use the $\epsilon$ approximation. Now we discard the nonnegative term

$$
\left[f(x) \Phi^{\prime}(f(x))-\Phi(f(x))\right] c_{\alpha} \int_{\epsilon}^{\infty}(1-\theta(x, t)) t^{-1-\alpha} d t
$$

in the calculation above, and deduce that

$$
\begin{equation*}
\Phi^{\prime}(f(x))\left[\Lambda_{D}^{2 \alpha} f\right]_{\epsilon}(x)-\left[\Lambda_{D}^{2 \alpha}(\Phi(f))\right]_{\epsilon}(x) \geq 0 \tag{18}
\end{equation*}
$$

as an element of $L^{2}(\Omega)$. (This simply means that its integral against any nonnegative $L^{2}(\Omega)$ function is nonnegative.) Passing to the limit $\epsilon \rightarrow 0$ we obtain the inequality $[15]$. If $\Phi$ and the boundary of the domain are smooth enough then we can prove that the terms in the inequality are continuous, and therefore the inequality holds everywhere.

## 3. The Nonlinear Bound

We prove a bound in the spirit of ([2]). The nonlinear lower bound was used as an essential ingredient in proofs of global regularity for drift-diffusion equations with nonlocal dissipation.

THEOREM 1. Let $f \in L^{\infty}(\Omega) \cap \mathcal{D}\left(\Lambda_{D}^{2 \alpha}\right), 0 \leq \alpha<1$. Assume that $f=\partial q$ with $q \in L^{\infty}(\Omega)$ and $\partial$ a first order derivative. Then there exist constants $c, C$ depending on $\Omega$ and $\alpha$ such that

$$
\begin{equation*}
f \Lambda_{D}^{2 \alpha} f-\frac{1}{2} \Lambda_{D}^{2 \alpha} f^{2} \geq c\|q\|_{L^{\infty}}^{-2 \alpha}\left|f_{d}\right|^{2+2 \alpha} \tag{19}
\end{equation*}
$$

holds pointwise in $\Omega$, with

$$
\left|f_{d}(x)\right|= \begin{cases}|f(x)|, & \text { if }|f(x)| \geq C\|q\|_{L^{\infty}(\Omega)} \max \left(\frac{1}{\operatorname{diam}(\Omega)}, \frac{1}{d(x)}\right)  \tag{20}\\ 0, & \text { if }|f(x)| \leq C\|q\|_{L^{\infty}(\Omega)} \max \left(\frac{1}{\operatorname{diam}(\Omega)}, \frac{1}{d(x)}\right)\end{cases}
$$

Proof. We start the calculation using the inequality

$$
\begin{equation*}
f \Lambda_{D}^{2 \alpha} f-\frac{1}{2} \Lambda_{D}^{2 \alpha} f^{2} \geq \frac{1}{2} c_{\alpha} \int_{0}^{\infty} \psi\left(\frac{t}{\tau}\right) t^{-1-\alpha} d t \int_{\Omega} H_{D}(t, x, y)(f(x)-f(y))^{2} d y \tag{21}
\end{equation*}
$$

where $\tau>0$ is arbitrary and $0 \leq \psi(s) \leq 1$ is a smooth function, vanishing identically for $0 \leq s \leq 1$ and equal identically to 1 for $s \geq 2$. This follows repeating the calculation of the proof of the Córdoba-Córdoba inequality with $\Phi(f)=\frac{1}{2} f^{2}$ :

$$
\begin{aligned}
& f(x)\left[\Lambda_{D}^{2 \alpha} f\right]_{\epsilon}(x)-\frac{1}{2}\left[\Lambda_{D}^{2 \alpha} f^{2}\right]_{\epsilon}(x) \\
& =c_{\alpha} \int_{\epsilon}^{\infty} t^{-1-\alpha} \int_{\Omega}\left\{\left[\frac{1}{|\Omega|} f(x)^{2}-f(x) H_{D}(t, x, y) f(y)\right]-\frac{1}{2|\Omega|} f^{2}(x)+\frac{1}{2} H_{D}(t, x, y) f^{2}(y)\right\} d y \\
& =c_{\alpha} \int_{\epsilon}^{\infty} t^{-1-\alpha} d t \int_{\Omega}\left\{\frac{1}{2}\left[H_{D}(t, x, y)(f(x)-f(y))^{2}\right]+\frac{1}{2} f^{2}(x)\left[\frac{1}{|\Omega|}-H_{D}(t, x, y)\right]\right\} d y \\
& =c_{\alpha} \int_{\epsilon}^{\infty} t^{-1-\alpha} d t \int_{\Omega}\left\{\frac{1}{2}\left[H_{D}(t, x, y)(f(x)-f(y))^{2}\right] d y+\frac{1}{2} f^{2}(x)\left[1-e^{t \Delta} 1\right](x)\right\} \\
& \geq c_{\alpha} \int_{\epsilon}^{\infty} t^{-1-\alpha} d t \int_{\Omega} \frac{1}{2} H_{D}(t, x, y)(f(x)-f(y))^{2} d y
\end{aligned}
$$

where in the last inequality we used the maximum principle again. Then, we choose $\tau>0$ and let $\epsilon<\tau$. It follows that

$$
f(x)\left[\Lambda_{D}^{2 \alpha} f\right]_{\epsilon}(x)-\frac{1}{2}\left[\Lambda_{D}^{2 \alpha} f^{2}\right]_{\epsilon}(x) \geq \frac{1}{2} c_{\alpha} \int_{0}^{\infty} \psi\left(\frac{t}{\tau}\right) t^{-1-\alpha} d t \int_{\Omega} H_{D}(t, x, y)(f(x)-f(y))^{2} d y
$$

We obtain 21 by letting $\epsilon \rightarrow 0$. We restrict to $t \leq T$,

$$
\begin{equation*}
\left[f \Lambda_{D}^{2 \alpha} f-\frac{1}{2} \Lambda_{D}^{2 \alpha} f^{2}\right](x) \geq \frac{1}{2} c_{\alpha} \int_{0}^{T} \psi\left(\frac{t}{\tau}\right) t^{-1-\alpha} d t \int_{\Omega} H_{D}(t, x, y)(f(x)-f(y))^{2} d y \tag{22}
\end{equation*}
$$

and open brackets in 22):

$$
\begin{align*}
& {\left[f \Lambda_{D}^{2 \alpha} f-\frac{1}{2} \Lambda_{D}^{2 \alpha} f^{2}\right](x)} \\
& \geq \frac{1}{2} f^{2}(x) c_{\alpha} \int_{0}^{T} \psi\left(\frac{t}{\tau}\right) t^{-1-\alpha} d t \int_{\Omega} H_{D}(t, x, y) d y-f(x) c_{\alpha} \int_{0}^{T} \psi\left(\frac{t}{\tau}\right) t^{-1-\alpha} d t \int_{\Omega} H_{D}(t, x, y) f(y) d y \\
& \geq|f(x)|\left[\frac{1}{2}|f(x)| I(x)-J(x)\right] \tag{23}
\end{align*}
$$

with

$$
\begin{equation*}
I(x)=c_{\alpha} \int_{0}^{T} \psi\left(\frac{t}{\tau}\right) t^{-1-\alpha} d t \int_{\Omega} H_{D}(t, x, y) d y \tag{24}
\end{equation*}
$$

and

$$
\begin{align*}
& J(x)=c_{\alpha}\left|\int_{0}^{T} \psi\left(\frac{t}{\tau}\right) t^{-1-\alpha} d t \int_{\Omega} H_{D}(t, x, y) f(y) d y\right| \\
& =c_{\alpha}\left|\int_{0}^{T} \psi\left(\frac{t}{\tau}\right) t^{-1-\alpha} d t \int_{\Omega} \partial_{y} H_{D}(t, x, y) q(y) d y\right| . \tag{25}
\end{align*}
$$

We proceed with a lower bound on $I$ and an upper bound on $J$. For the lower bound on $I$ we note that

$$
\theta(x, t)=\int_{\Omega} H_{D}(t, x, y) d y \geq \int_{|x-y| \leq \frac{d(x)}{2}} H_{D}(t, x, y) d y
$$

because $H_{D}$ is positive. Using the lower bound in $\sqrt[2]{ }$ we have that $|x-y| \leq \frac{d(x)}{2}$ implies

$$
\frac{w_{1}(x)}{|x-y|} \geq 2 c_{0}, \quad \frac{w_{1}(y)}{|x-y|} \geq c_{0}
$$

and then, using the lower bound in (10) we obtain

$$
H_{D}(t, x, y) \geq 2 c c_{0}^{2} t^{-\frac{d}{2}} e^{-\frac{|x-y|^{2}}{k t}} .
$$

Integrating it follows that

$$
\theta(x, t) \geq 2 c c_{0}^{2} \omega_{d-1} k^{\frac{d}{2}} \int_{0}^{\frac{d(x)}{2 \sqrt{k t}}} \rho^{d-1} e^{-\rho^{2}} d \rho
$$

If $\frac{d(x)}{2 \sqrt{k t}} \geq 1$ then the integral is bounded below by $\int_{0}^{1} \rho^{d-1} e^{-\rho^{2}} d \rho$. If $\frac{d(x)}{2 \sqrt{k t}} \leq 1$ then $\rho \leq 1$ implies that the exponential is bounded below by $e^{-1}$ and so

$$
\begin{equation*}
\theta(x, t) \geq c_{1} \min \left\{1,\left(\frac{d(x)}{\sqrt{t}}\right)^{d}\right\} \tag{26}
\end{equation*}
$$

for all $0 \leq t \leq T$ where $c_{1}$ is a positive constant, depending on $\Omega$. Because

$$
I(x)=\int_{0}^{T} \psi\left(\frac{t}{\tau}\right) t^{-1-\alpha} \theta(x, t) d t
$$

we have

$$
\begin{aligned}
& I(x) \geq c_{1} \int_{0}^{\min \left(T, d^{2}(x)\right)} \psi\left(\frac{t}{\tau}\right) t^{-1-\alpha} d t \\
& =c_{1} \tau^{-\alpha} \int_{1}^{\tau^{-1}\left(\min \left(T, d^{2}(x)\right)\right)} \psi(s) s^{-1-\alpha} d s
\end{aligned}
$$

Therefore we have that

$$
\begin{equation*}
I(x) \geq c_{2} \tau^{-\alpha} \tag{27}
\end{equation*}
$$

with $c_{2}=c_{1} \int_{1}^{2} \psi(s) s^{-1-\alpha} d s$, a positive constant depending only on $\Omega$ and $\alpha$, provided $\tau$ is small enough,

$$
\begin{equation*}
\tau \leq \frac{1}{2} \min \left(T, d^{2}(x)\right) \tag{28}
\end{equation*}
$$

In order to bound $J$ from above we use the upper bound (14) which yields

$$
\begin{equation*}
\int_{\Omega}\left|\nabla_{y} H_{D}(t, x, y)\right| d y \leq C_{1} t^{-\frac{1}{2}} \tag{29}
\end{equation*}
$$

with $C_{1}$ depending only on $\Omega$. Indeed,

$$
\begin{aligned}
& \int_{d(y) \geq \sqrt{t}}\left|\nabla_{y} H_{D}(t, x, y)\right| d y \\
& \leq C_{2} t^{-\frac{1}{2}} \int_{\mathbb{R}^{d}}\left(1+\frac{|x-y|}{\sqrt{t}}\right) t^{-\frac{d}{2}} e^{-\frac{|x-y|^{2}}{k t}} d y \\
& =C_{3} t^{-\frac{1}{2}}
\end{aligned}
$$

and, in view of the upper bound in $2, \frac{1}{d(y)} w_{1}(y) \leq C_{0}$ and the upper bound in 10 ,

$$
\begin{aligned}
& \int_{d(y) \leq \sqrt{t}}\left|\nabla_{y} H_{D}(t, x, y)\right| d y \\
& \leq C_{4} \int_{\mathbb{R}^{d}} \frac{1}{|x-y|} t^{-\frac{d}{2}} e^{-\frac{|x-y|^{2}}{K t}} d y=C_{5} t^{-\frac{1}{2}}
\end{aligned}
$$

Now

$$
J \leq\|q\|_{L^{\infty}(\Omega)} \int_{0}^{T} \psi\left(\frac{t}{\tau}\right) t^{-1-\alpha} d t \int_{\Omega}\left|\nabla_{y} H_{D}(t, x, y)\right| d y
$$

and therefore, in view of 29

$$
J \leq C_{1}\|q\|_{L^{\infty}(\Omega)} \int_{0}^{T} \psi\left(\frac{t}{\tau}\right) t^{-\frac{3}{2}-\alpha} d t
$$

and therefore

$$
\begin{equation*}
J \leq C_{6}\|q\|_{L^{\infty}(\Omega)} \tau^{-\frac{1}{2}-\alpha} \tag{30}
\end{equation*}
$$

with

$$
C_{6}=C_{1} \int_{1}^{\infty} \psi(s) s^{-\frac{3}{2}-\alpha} d s
$$

a constant depending only on $\Omega$ and $\alpha$. Now, because of the lower bound $(23)$, if we can choose $\tau$ so that

$$
J(x) \leq \frac{1}{4}|f(x)| I(x)
$$

then it follows that

$$
\begin{equation*}
\left[f \Lambda_{D}^{2 \alpha} f-\frac{1}{2} \Lambda_{D}^{2 \alpha} f^{2}\right](x) \geq \frac{1}{4} f^{2}(x) I(x) \tag{31}
\end{equation*}
$$

Because of the bounds (27), (30) the choice

$$
\begin{equation*}
\tau(x)=c_{3} \frac{\|q\|_{L^{\infty}}^{2}}{|f(x)|^{2}} \tag{32}
\end{equation*}
$$

with $c_{3}=16 C_{6}^{2} c_{2}^{-2}$ achieves the desired bound. The requirement limits the possibility of making this choice to the situation

$$
\begin{equation*}
c_{3} \frac{\|q\|_{L^{\infty}}^{2}}{|f(x)|^{2}} \leq \frac{1}{2} \min \left(T, d^{2}(x)\right) \tag{33}
\end{equation*}
$$

which leads to the statement of the theorem. Indeed, if (32) is allowed then the lower bound in (31) becomes

$$
\begin{equation*}
\left[f \Lambda_{D}^{2 \alpha} f-\frac{1}{2} \Lambda_{D}^{2 \alpha} f^{2}\right](x) \geq c\|q\|_{L^{\infty}}^{-2 \alpha}\left|f_{d}\right|^{2+2 \alpha} \tag{34}
\end{equation*}
$$

with $c=\frac{1}{4} c_{2} c_{3}^{-\alpha}$.

## 4. Commutator estimates

We start by considering the commutator $\left[\nabla, \Lambda_{D}\right]$ in $\Omega=\mathbb{R}_{+}^{d}$. The heat kernel with Dirichlet boundary conditions is

$$
H(x, y, t)=c t^{-\frac{d}{2}}\left(e^{-\frac{|x-y|^{2}}{4 t}}-e^{-\frac{|x-\widetilde{y}|^{2}}{4 t}}\right)
$$

where $\widetilde{y}=\left(y_{1}, \ldots, y_{d-1},-y_{d}\right)$. We claim that

$$
\begin{equation*}
\int_{\Omega}\left(\nabla_{x}+\nabla_{y}\right) H(x, y, t) d y \leq C t^{-\frac{1}{2}} e^{-\frac{x_{d}^{2}}{4 t}} \tag{35}
\end{equation*}
$$

Indeed, the only nonzero component occurs when the differentiation is with respect to the normal direction, and then

$$
\left(\partial_{x_{d}}+\partial_{y_{d}}\right) H(x, y, t)=c t^{-\frac{d}{2}} e^{-\frac{\left|x^{\prime}-y^{\prime}\right|^{2}}{4 t}}\left(\frac{x_{d}+y_{d}}{t}\right) e^{-\frac{\left(x_{d}+y_{d}\right)^{2}}{4 t}}
$$

where we denoted $x^{\prime}=\left(x_{1}, \ldots, x_{d-1}\right)$ and $y^{\prime}=\left(y_{1}, \ldots, y_{d-1}\right)$. Therefore

$$
\begin{aligned}
& \int_{\Omega}\left(\nabla_{x}+\nabla_{y}\right) H(x, y, t) d y \leq C t^{-\frac{1}{2}} \int_{0}^{\infty}\left(\frac{x_{d}+y_{d}}{t}\right) e^{-\frac{\left(x_{d}+y_{d}\right)^{2}}{4 t}} d y_{d} \\
& =C t^{-\frac{1}{2}} \int_{\frac{x_{d}}{\sqrt{t}} \xi e^{-\frac{\xi^{2}}{4}} d \xi}^{=C t^{-\frac{1}{2}} e^{-\frac{x_{d}^{d}}{4 t}}} .
\end{aligned}
$$

Consequently

$$
K(x, y)=\int_{0}^{\infty} t^{-\frac{3}{2}}\left(\nabla_{x}+\nabla_{y}\right) H(x, y, t) d t
$$

obeys

$$
\int_{\Omega} K(x, y) d y \leq C \int_{0}^{\infty} t^{-2} e^{-\frac{x_{d}^{2}}{4 t}} d t=\frac{C}{x_{d}^{2}}
$$

The commutator $\left[\nabla, \Lambda_{D}\right]$ is computed as follows

$$
\begin{aligned}
& {\left[\nabla, \Lambda_{D}\right] f(x)=\int_{0}^{\infty} t^{-\frac{3}{2}} \int_{\Omega}\left[\nabla_{x} H_{D}(x, y, t) f(y)-H_{D}(x, y, t) \nabla_{y} f(y)\right] d y d t} \\
& =\int_{0}^{\infty} t^{-\frac{3}{2}} \int_{\Omega}\left(\nabla_{x}+\nabla_{y}\right) H_{D}(x, y, t) f(y) d y d t \\
& =\int_{\Omega} K(x, y) f(y) d y .
\end{aligned}
$$

We have proved thus that the kernel $K(x, y)$ of the commutator obeys

$$
\begin{equation*}
\int_{\Omega} K(x, y) d y \leq C d(x)^{-2} \tag{36}
\end{equation*}
$$

and therefore we obtain, for instance, for any $p, q \in[1, \infty]$ with $p^{-1}+q^{-1}=1$

$$
\left|\int_{\Omega} g\left[\nabla, \Lambda_{D}\right] f d x\right| \leq C\left(\int_{\Omega} d(x)^{-2}|f(x)|^{p} d x\right)^{\frac{1}{p}}\left(\int_{\Omega} d(x)^{-2}|g(x)|^{q} d x\right)^{\frac{1}{q}} .
$$

In general domains, the absence of explicit expressions for the heat kernel with Dirichlet boundary conditions requires a less direct approach to commutator estimates.

We take thus an open bounded domain $\Omega \subset \mathbb{R}^{d}$ with smooth boundary and describe the square root of the Dirichlet Laplacian using the harmonic extension. We denote

$$
Q=\Omega \times \mathbb{R}_{+}=\{(x, z) \mid x \in \Omega, z>0\}
$$

and consider the traces of functions in $H_{0, L}^{1}(Q)$,

$$
\begin{gather*}
H_{0, L}^{1}(Q)=\left\{v \in H^{1}(Q) \mid v(x, z)=0, x \in \partial \Omega, z>0\right\} \\
V_{0}(\Omega)=\left\{f \mid \exists v \in H_{0, L}^{1}(Q), f(x)=v(x, 0), x \in \Omega\right\} \tag{37}
\end{gather*}
$$

where we slightly abused notation by referring to the images of $v$ under restriction operators as $v(x, z)$ for $x \in \partial \Omega$, and as $v(x, 0)$ for $x \in \Omega$. We recall from ([1]) that, on one hand,

$$
\begin{equation*}
V_{0}(\Omega)=\left\{f \in H^{\frac{1}{2}}(\Omega) \left\lvert\, \int_{\Omega} \frac{f^{2}(x)}{d(x)} d x<\infty\right.\right\} \tag{38}
\end{equation*}
$$

with norm

$$
\|f\|_{V_{0}}^{2}=\|f\|_{H^{\frac{1}{2}}(\Omega)}^{2}+\int_{\Omega} \frac{f^{2}(x)}{d(x)} d x
$$

and on the other hand $V_{0}(\Omega)=\mathcal{D}\left(\Lambda_{D}^{\frac{1}{2}}\right)$, i.e.

$$
\begin{equation*}
V_{0}(\Omega)=\left\{f \in L^{2}(\Omega) \mid f=\sum_{j} f_{j} w_{j}, \sum_{j} \lambda_{j}^{\frac{1}{2}} f_{j}^{2}<\infty\right\} \tag{39}
\end{equation*}
$$

with equivalent norm

$$
\|f\|_{\frac{1}{2}, D}^{2}=\sum_{j=1}^{\infty} \lambda_{j}^{\frac{1}{2}} f_{j}^{2}=\left\|\Lambda_{D}^{\frac{1}{2}} f\right\|_{L^{2}(\Omega)}^{2}
$$

The harmonic extension of $f$ will be denoted $v_{f}$. It is given by

$$
\begin{equation*}
v_{f}(x, z)=\sum_{j=1}^{\infty} f_{j} e^{-z \sqrt{\lambda_{j}}} w_{j}(x) \tag{40}
\end{equation*}
$$

and the operator $\Lambda_{D}$ is then identified with

$$
\begin{equation*}
\Lambda_{D} f=-\left(\partial_{z} v_{f}\right)_{\mid z=0} \tag{41}
\end{equation*}
$$

Note that if $f \in V_{0}(\Omega)$ then $v_{f} \in H^{1}(Q)$. Note also, that $v_{f}$ decays exponentially in the sense that

$$
\begin{equation*}
\left\|v_{f}\right\|_{e^{z l} H^{1}(Q)}=\left\|e^{z l} \nabla v_{f}\right\|_{L^{2}(Q)}+\left\|e^{z l} v_{f}\right\|_{L^{2}(Q)} \leq C\|f\|_{V_{0}} \tag{42}
\end{equation*}
$$

holds with $\ell=\frac{\lambda_{1}}{4}$. We use a lemma in $Q$ :
Lemma 1. Let $F \in H^{-1}(Q)$ (the dual of $H_{0}^{1}(Q)$ ). Then the problem

$$
\left\{\begin{array}{l}
-\Delta u=F, \quad \text { in } Q  \tag{43}\\
u=0, \quad \text { on } \partial Q
\end{array}\right.
$$

has a unique weak solution $u \in H_{0}^{1}(Q)$. If $F \in L^{2}(Q)$ and if there exists $l>0$ so that

$$
\left\|e^{z l} F\right\|_{L^{2}(Q)}^{2}=\int e^{2 z l}|F(x, z)|^{2} d x d z<\infty
$$

then $u \in H_{0}^{1}(Q) \cap H^{2}(Q)$ and it satisfies

$$
\|u\|_{H^{2}(Q)} \leq C\left\|e^{z l} F\right\|_{L^{2}(Q)}
$$

with $C$ a constant depending only on $\Omega$ and $l$.
Proof. We consider the domain $U=\Omega \times \mathbb{R}$ and take the odd extension of $F$ to $U, F(x,-z)=-F(x, z)$. The existence of a weak solution in $H_{0}^{1}(U)$ follows by variational methods, by minimizing

$$
I(v)=\int_{U}\left(\frac{1}{2}|\nabla v|^{2}+v F\right) d x d z
$$

among all odd functions $v \in H_{0}^{1}(U)$. The domain $U$ has finite width, so the Poincaré inequality

$$
\|\nabla v\|_{L^{2}(U)}^{2} \geq c\|v\|_{L^{2}(U)}^{2}
$$

is valid for functions in $H_{0}^{1}(U)$. This allows to show existence and uniqueness of weak solutions. If $F \in$ $L^{2}(U)$ we obtain locally uniform elliptic estimates

$$
\|u\|_{H^{2}\left(U_{j}\right)} \leq C\|F\|_{L^{2}\left(V_{j}\right)}
$$

where $U_{j}=\{(x, z) \mid x \in \Omega, z \in(j-1, j+1)\}, V_{j}=\{(x, z) \mid x \in \Omega, z \in(j-2, j+2)\}$, and $j= \pm \frac{1}{2}, \pm 1, \pm \frac{3}{2}, \ldots$, i.e. $j \in \frac{1}{2} \mathbb{Z}$. The constant $C$ does not depend on $j$. Because of the decay assumption on $F$, the estimates can be summed.

THEOREM 2. Let $a \in B(\Omega)$ where $B(\Omega)=W^{2, d}(\Omega) \cap W^{1, \infty}(\Omega)$, if $d \geq 3$, and $B(\Omega)=W^{2, p}(\Omega)$ with $p>2$, if $d=2$. There exists a constant $C$, depending only on $\Omega$, such that

$$
\begin{equation*}
\left\|\left[a, \Lambda_{D}\right] f\right\|_{\frac{1}{2}, D} \leq C\|a\|_{B(\Omega)}\|f\|_{\frac{1}{2}, D} \tag{44}
\end{equation*}
$$

holds for any $f \in V_{0}(\Omega)$, with

$$
\|a\|_{B(\Omega)}=\|a\|_{W^{2, d}(\Omega)}+\|a\|_{W^{1, \infty}(\Omega)}
$$

if $d \geq 3$ and

$$
\|a\|_{B(\Omega)}=\|a\|_{W^{2, p}(\Omega)}
$$

with $p>2$, if $d=2$.
Proof. In order to compute $v_{a f}$, let us note that $a v_{f} \in H_{0, L}^{1}(Q)$, and

$$
\Delta\left(a v_{f}\right)=v_{f} \Delta_{x} a+2 \nabla_{x} a \cdot \nabla v_{f}
$$

and, because $v_{f} \in e^{z l} H^{1}(Q)$ and $a \in B(\Omega)$ we have that

$$
\left\|\Delta\left(a v_{f}\right)\right\|_{L^{2}\left(e^{z l} d z d x\right)} \leq C\|a\|_{B(\Omega)}\left\|v_{f}\right\|_{e^{z l} H^{1}(Q)} .
$$

Solving

$$
\left\{\begin{array}{l}
\Delta u=\Delta\left(a v_{f}\right) \quad \text { in } Q \\
u=0 \text { on } \partial Q
\end{array}\right.
$$

we obtain $u \in H_{0}^{1}(Q) \cap H^{2}(Q)$. This follows from Lemma 1 above. Note that $\partial_{z} u \in H_{0, L}^{1}(Q)$. Then

$$
v_{a f}=a v_{f}-u
$$

and

$$
a \Lambda_{D} f-\Lambda_{D}(a f)=-a\left(\partial_{z} v_{f}\right)_{\mid z=0}+\partial_{z}\left(a v_{f}-u\right)_{\mid z=0}=-\partial_{z} u_{\mid z=0} .
$$

The estimate follows from elliptic estimates and restriction estimates

$$
\left\|\partial_{z} u_{\mid z=0}\right\|_{V_{0}} \leq C\left\|\partial_{z} u\right\|_{H^{1}(Q)} \leq C\|a\|_{B(\Omega)}\left\|v_{f}\right\|_{e^{z} H^{1}(Q)} \leq C\|a\|_{B(\Omega)}\|f\|_{V_{0}}
$$

THEOREM 3. Let a vector field a have components in $B(\Omega)$ defined above, $a \in(B(\Omega))^{d}$. Assume that the normal component of the trace of $a$ on the boundary vanishes,

$$
a_{\mid \partial \Omega} \cdot n=0
$$

(i.e the vector field is tangent to the boundary). There exists a constant $C$ such that

$$
\begin{equation*}
\left\|\left[a \cdot \nabla, \Lambda_{D}\right] f\right\|_{\frac{1}{2}, D} \leq C\|a\|_{B(\Omega)}\|f\|_{\frac{3}{2}, D} \tag{45}
\end{equation*}
$$

holds for any $f$ such that $f \in \mathcal{D}\left(\Lambda_{D}^{\frac{3}{2}}\right)$.
Proof. In order to compute $v_{a \cdot \nabla f}$ we note that

$$
\Delta\left(a \cdot \nabla v_{f}\right)=\Delta a \cdot \nabla v_{f}+\nabla a \cdot \nabla \nabla v_{f}
$$

and because $v_{f} \in e^{z l} H^{2}(Q)$ and $a \in B(\Omega)$ we have that

$$
\left\|\Delta\left(a \cdot \nabla v_{f}\right)\right\|_{L^{2}\left(e^{z} l d z d x\right)} \leq C\|a\|_{B(\Omega)}\left\|v_{f}\right\|_{e^{z} H^{2}(Q)} .
$$

Then solving

$$
\left\{\begin{array}{l}
\Delta u=\Delta\left(a \cdot \nabla v_{f}\right) \quad \text { in } Q, \\
u=0 \text { on } \partial Q,
\end{array}\right.
$$

we obtain $u \in H^{2}(Q)$ (by Lemma 11 and therefore $\partial_{z} u \in H_{0, L}^{1}(Q)$. Consequently $-\partial_{z} u_{\mid z=0} \in V_{0}(\Omega)$. Because $v_{f}$ vanishes on the boundary and $a \cdot \nabla$ is tangent to the boundary, it follows that $a \cdot \nabla v_{f} \in H_{0, L}^{1}(Q)$ (vanishes on the lateral boundary of $Q$ and is in $H^{1}(Q)$ ) and therefore

$$
v_{a \cdot \nabla f}=a \cdot \nabla v_{f}-u
$$

Consequently

$$
\left[a \cdot \nabla, \Lambda_{D}\right] f=-\partial_{z} u_{\mid z=0}
$$

The estimate (45) follows from the elliptic estimates and restriction estimates on $u$, as above:

$$
\left\|\partial_{z} u_{\mid z=0}\right\|_{V_{0}} \leq C\left\|\partial_{z} u\right\|_{H^{1}(Q)} \leq C\|a\|_{B(\Omega)}\left\|v_{f}\right\|_{e^{z l} H^{2}(Q)} \leq C\|a\|_{B(\Omega)}\|f\|_{\frac{3}{2}, D}
$$

## 5. Linear transport and nonlocal diffusion

We study the equation

$$
\begin{equation*}
\partial_{t} \theta+u \cdot \nabla \theta+\Lambda_{D} \theta=0 \tag{46}
\end{equation*}
$$

with initial data

$$
\begin{equation*}
\theta(x, 0)=\theta_{0} \tag{47}
\end{equation*}
$$

in the bounded open domain $\Omega \subset \mathbb{R}^{d}$ with smooth boundary. We assume that $u=u(x, t)$ is divergence-free

$$
\begin{equation*}
\nabla \cdot u=0 \tag{48}
\end{equation*}
$$

that $u$ is smooth

$$
\begin{equation*}
u \in L^{2}\left(0, T ; B(\Omega)^{d}\right), \tag{49}
\end{equation*}
$$

and that $u$ is parallel to the boundary

$$
\begin{equation*}
u_{\mid \partial \Omega} \cdot n=0 . \tag{50}
\end{equation*}
$$

We consider zero boundary conditions for $\theta$. Strictly speaking, because this is a first order equation, it is better to think of these as a constraint on the evolution equation. We satrt with initial data $\theta_{0}$ which vanish on the boundary, and maintain this property in time. The transport evolution

$$
\partial_{t} \theta+u \cdot \nabla \theta=0
$$

and, separately, the nonlocal diffusion

$$
\partial_{t} \theta+\Lambda_{D} \theta=0
$$

keep the constraint of $\theta_{\mid \partial \Omega}=0$. Because the operators $u \cdot \nabla$ and $\Lambda_{D}$ have the same differential order, neither dominates the other, and the linear evolution needs to be treated carefully. We start by considering Galerkin approximations. Let

$$
\begin{equation*}
P_{m} f=\sum_{j=1}^{m} f_{j} w_{j}, \quad \text { for } f=\sum_{j=1}^{\infty} f_{j} w_{j}, \tag{51}
\end{equation*}
$$

and let

$$
\begin{equation*}
\theta_{m}(x, t)=\sum_{j=1}^{m} \theta_{j}^{(m)}(t) w_{j}(x) \tag{52}
\end{equation*}
$$

obey

$$
\begin{equation*}
\partial_{t} \theta_{m}+P_{m}\left(u \cdot \nabla \theta_{m}\right)+\Lambda_{D} \theta_{m}=0 \tag{53}
\end{equation*}
$$

with initial data

$$
\begin{equation*}
\theta_{m}(x, 0)=\left(P_{m} \theta_{0}\right)(x) . \tag{54}
\end{equation*}
$$

These are ODEs for the coefficients $\theta_{j}^{(m)}(t)$, written conveniently. We prove bounds that are independent of $m$ and pass to the limit. Note that by construction

$$
\theta_{m} \in \mathcal{D}\left(\Lambda_{D}^{r}\right), \quad \forall r \geq 0
$$

We start with

$$
\begin{equation*}
\frac{1}{2} \frac{d}{d t}\left\|\theta_{m}\right\|_{L^{2}(\Omega)}^{2}+\left\|\theta_{m}\right\|_{V_{0}}^{2}=0 \tag{55}
\end{equation*}
$$

which implies

$$
\begin{equation*}
\sup _{0 \leq t \leq T} \frac{1}{2}\left\|\theta_{m}(\cdot, t)\right\|_{L^{2}(\Omega)}^{2}+\int_{0}^{T}\left\|\theta_{m}\right\|_{V_{0}}^{2} d t \leq \frac{1}{2}\left\|\theta_{0}\right\|_{L^{2}(\Omega)}^{2} \tag{56}
\end{equation*}
$$

This follows because of the divergence-free condition and the fact that $u_{\mid \partial \Omega}$ is parallel to the boundary. Next, we apply $\Lambda_{D}$ to (53). For convenience, we denote

$$
\begin{equation*}
\left[\Lambda_{D}, u \cdot \nabla\right] f=\Gamma f \tag{57}
\end{equation*}
$$

because $u$ is fixed throughout this section. Because $P_{m}$ and $\Lambda_{D}$ commute, we have thus

$$
\begin{equation*}
\partial_{t} \Lambda_{D} \theta_{m}+P_{m}\left(u \cdot \nabla \Lambda_{D} \theta_{m}+\Gamma \theta_{m}\right)+\Lambda_{D}^{2} \theta_{m}=0 . \tag{58}
\end{equation*}
$$

Now, we multiply (58) by $\Lambda_{D}^{3} \theta_{m}$ and integrate. Note that

$$
\int_{\Omega} P_{m}\left(u \cdot \nabla \Lambda_{D} \theta_{m}+\Gamma \theta_{m}\right) \Lambda_{D}^{3} \theta_{m} d x=\int_{\Omega}\left(u \cdot \nabla \Lambda_{D} \theta_{m}+\Gamma \theta_{m}\right) \Lambda_{D}^{3} \theta_{m} d x
$$

because $P_{m} \theta_{m}=\theta_{m}$ and $P_{m}$ is selfadjoint. We bound the term

$$
\left|\int_{\Omega} \Gamma \theta_{m} \Lambda_{D}^{3} \theta_{m} d x\right| \leq\left\|\Gamma \theta_{m}\right\|_{V_{0}}\left\|\Lambda_{D}^{2.5} \theta_{m}\right\|_{L^{2}(\Omega)}
$$

and use Theorem 3 (45) to deduce

$$
\left|\int_{\Omega} \Gamma \theta_{m} \Lambda_{D}^{3} \theta_{m} d x\right| \leq C\|u\|_{B(\Omega)}\left\|\Lambda_{D} \theta_{m}\right\|_{V_{0}}\left\|\Lambda_{D}^{2.5} \theta_{m}\right\|_{L^{2}(\Omega)}
$$

We compute

$$
\begin{aligned}
& \int_{\Omega}\left(u \cdot \nabla \Lambda_{D} \theta_{m}\right) \Lambda_{D}^{3} \theta_{m} d x=\int_{\Omega} \Lambda_{D}^{2}\left(u \cdot \nabla \Lambda_{D} \theta_{m}\right) \Lambda_{D} \theta_{m} \\
& =\int_{\Omega}\left[(-\Delta u) \cdot \nabla \Lambda_{D} \theta_{m}-2 \nabla u \cdot \nabla \nabla \Lambda_{D} \theta_{m}\right] \Lambda_{D} \theta_{m} d x+\int_{\Omega}\left(u \cdot \nabla \Lambda_{D}^{3} \theta_{m}\right) \Lambda_{D} \theta_{m} d x \\
& =\int_{\Omega}\left[(-\Delta u) \cdot \nabla \Lambda_{D} \theta_{m}-2 \nabla u \cdot \nabla \nabla \Lambda_{D} \theta_{m}\right] \Lambda_{D} \theta_{m} d x-\int_{\Omega} \Lambda_{D}^{3} \theta_{m}\left(u \cdot \nabla \Lambda_{D} \theta_{m}\right) d x \\
& =\int_{\Omega}\left[\left((-\Delta u) \cdot \nabla \Lambda_{D} \theta_{m}\right) \Lambda_{D} \theta_{m}+2 \nabla u \nabla \Lambda_{D} \theta_{m} \nabla \Lambda_{D} \theta_{m}\right] d x-\int_{\Omega}\left(u \cdot \nabla \Lambda_{D} \theta_{m}\right) \Lambda_{D}^{3} \theta_{m} d x .
\end{aligned}
$$

In the first integration by parts we used the fact that $\Lambda_{D}^{3} \theta_{m}$ is a finite linear combination of eigenfunctions which vanish at the boundary. Then we use the fact that $\Lambda_{D}^{2}=-\Delta$ is local. In the last equality we integrated by parts using the fact that $\Lambda_{D} \theta_{m}$ is a finite linear combination of eigenfunctions which vanish at the boundary and the fact that $u$ is divergence-free. It follows that

$$
\int_{\Omega}\left(u \cdot \nabla \Lambda_{D} \theta_{m}\right) \Lambda_{D}^{3} \theta_{m} d x=\frac{1}{2} \int_{\Omega}\left[\left((-\Delta u) \cdot \nabla \Lambda_{D} \theta_{m}\right) \Lambda_{D} \theta_{m}+2 \nabla u \nabla \Lambda_{D} \theta_{m} \nabla \Lambda_{D} \theta_{m}\right] d x
$$

and consequently

$$
\left|\int_{\Omega}\left(u \cdot \nabla \Lambda_{D} \theta_{m}\right) \Lambda_{D}^{3} \theta_{m} d x\right| \leq C\|u\|_{B(\Omega)}\left\|\Lambda_{D}^{2} \theta_{m}\right\|_{L^{2}(\Omega)}^{2}
$$

We obtain thus

$$
\begin{equation*}
\sup _{0 \leq t \leq T}\left\|\Lambda_{D}^{2} \theta_{m}(\cdot, t)\right\|_{L^{2}(\Omega)}^{2}+\int_{0}^{T}\left\|\Lambda_{D}^{2} \theta_{m}\right\|_{V_{0}}^{2} d t \leq C\left\|\Lambda_{D}^{2} \theta_{0}\right\|_{L^{2}(\Omega)}^{2} e^{C \int_{0}^{T}\|u\|_{B(\Omega)}^{2}{ }^{d t}} \tag{59}
\end{equation*}
$$

Passing to the limit $m \rightarrow \infty$ is done using the Aubin-Lions Lemma ([6]). We obtain
Theorem 4. Let $u \in L^{2}\left(0, T ; B(\Omega)^{d}\right)$ be a vector field parallel to the boundary. Then the equation (46) with initial data $\theta_{0} \in H_{0}^{1}(\Omega) \cap H^{2}(\Omega)$ has unique solutions belonging to

$$
\theta \in L^{\infty}\left(0, T ; H^{2}(\Omega) \cap H_{0}^{1}(\Omega)\right) \cap L^{2}\left(0, T ; H^{2.5}(\Omega)\right) .
$$

If the initial data $\theta_{0} \in L^{p}(\Omega), 1 \leq p \leq \infty$, then

$$
\begin{equation*}
\sup _{0 \leq t \leq T}\|\theta(\cdot, t)\|_{L^{p}(\Omega)} \leq\left\|\theta_{0}\right\|_{L^{p}(\Omega)} \tag{60}
\end{equation*}
$$

holds.
The estimate (60) holds because, by use of Proposition 1 for the diffusive part and integration by parts for the transport part, we have for solutions of (46)

$$
\frac{d}{d t}\|\theta\|_{L^{p}(\Omega)}^{p} \leq 0
$$

$1 \leq p<\infty$. The $L^{\infty}$ bound follows by taking the limit $p \rightarrow \infty$ in (60).

## 6. SQG

We consider now the equation

$$
\begin{equation*}
\partial_{t} \theta+u \cdot \nabla \theta+\Lambda_{D} \theta=0 \tag{61}
\end{equation*}
$$

with

$$
\begin{equation*}
u=R_{D}^{\perp} \theta \tag{62}
\end{equation*}
$$

and

$$
\begin{equation*}
R_{D}=\nabla \Lambda_{D}^{-1} \tag{63}
\end{equation*}
$$

in a bounded open domain in $\Omega \subset \mathbb{R}^{2}$ with smooth boundary. Local existence of smooth solutions is possible to prove using methods similar to those developed above for linear drift-diffusion equations. We will consider weak solutions (solutions which satisfy the equations in the sense of distributions).

Theorem 5. Let $\theta_{0} \in L^{2}(\Omega)$ and let $T>0$. There exists a weak solution of (61)

$$
\theta \in L^{\infty}\left(0, T ; L^{2}(\Omega)\right) \cap L^{2}\left(0, T ; V_{0}(\Omega)\right)
$$

satisfying $\lim _{t \rightarrow 0} \theta(t)=\theta_{0}$ weakly in $L^{2}(\Omega)$.
Proof. We consider Galerkin approximations, $\theta_{m}$

$$
\theta_{m}(x, t)=\sum_{j=1}^{m} \theta_{j}(t) w_{j}(x)
$$

obeying the ODEs (written conveniently as PDEs):

$$
\partial_{t} \theta_{m}+P_{m}\left[R_{D}^{\perp}\left(\theta_{m}\right) \cdot \nabla \theta_{m}\right]+\Lambda_{D} \theta_{m}=0
$$

with initial datum

$$
\theta_{m}(0)=P_{m}\left(\theta_{0}\right)
$$

We observe that, multiplying by $\theta_{m}$ and integrating we have

$$
\frac{1}{2} \frac{d}{d t}\left\|\theta_{m}\right\|^{2}+\left\|\theta_{m}\right\|_{\frac{1}{2}, D}^{2}=0
$$

which implies that the sequence $\theta_{m}$ is bounded in

$$
\theta_{m} \in L^{\infty}\left(0, T ; L^{2}(\Omega)\right) \cap L^{2}\left(0, T ; V_{0}(\Omega)\right)
$$

It is known $([\mathbf{1}])$ that $V_{0}(\Omega) \subset L^{4}(\Omega)$ with continuous inclusion. It is also known $([\mathbf{5}])$ that

$$
R_{D}: L^{4}(\Omega) \rightarrow L^{4}(\Omega)
$$

are bounded linear operators. It is then easy to see that $\partial_{t} \theta_{m}$ are bounded in $L^{2}\left(0, T ; H^{-1}(\Omega)\right)$. Applying the Aubin-Lions lemma, we obtain a subsequence, renamed $\theta_{m}$ converging strongly in $L^{2}\left(0, T ; L^{2}(\Omega)\right)$ and weakly in $L^{2}\left(0, T ; V_{0}(\Omega)\right)$ and in $L^{2}\left(0, T ; L^{4}(\Omega)\right)$. The limit solves the equation 61) weakly. Indeed, this follows after integration by parts because the product $\left(R_{D}^{\perp} \theta_{m}\right) \theta_{m}$ is weakly convergent in $L^{2}\left(0, T ; L^{2}(\Omega)\right)$ by weak-times-strong weak continuity. The weak continuity in time at $t=0$ follows by integrating

$$
\left(\theta_{m}(t), \phi\right)-\left(\theta_{m}(0), \phi\right)=\int_{0}^{t} \frac{d}{d s} \theta_{m}(s) d s
$$

and use of the equation and uniform bounds. We omit further details.
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