

UNIQUENESS OF SMOOTH STATIONARY BLACK HOLES IN VACUUM: SMALL PERTURBATIONS OF THE KERR SPACES

S. ALEXAKIS, A. D. IONESCU, AND S. KLAINERMAN

ABSTRACT. Following the program started in [24], we attempt to remove the analyticity assumption in the the well known Hawking-Carter-Robinson uniqueness result for regular stationary vacuum black holes. Unlike [24], which was based on a tensorial characterization of the Kerr solutions, due to Mars [29], we rely here on Hawking's original strategy, which is to reduce the case of general stationary space-times to that of stationary and axi-symmetric spacetimes for which the Carter-Robinson uniqueness result holds. In this reduction Hawking had to appeal to analyticity. Using a variant of the geometric Carleman estimates developed in [24], in this paper we show how to bypass analyticity in the case when the stationary vacuum space-time is a small perturbation of a given Kerr solution. Our perturbation assumption is expressed as a uniform smallness condition on the Mars-Simon tensor. The starting point of our proof is the new local rigidity theorem established in [2].

CONTENTS

1. Introduction	2
1.1. Precise assumptions and the main theorem	4
2. Preliminaries	6
2.1. A system of coordinates along Σ^0	6
2.2. Optical functions in a neighborhood of S_0	7
2.3. Definitions and asymptotic formulas	8
3. Analysis on the hypersurface Σ_1	10
3.1. A lemma of Mars	13
3.2. Conclusions	15
4. Properties of the function y	16
4.1. Control of y in a neighborhood of S_0	16
4.2. Regularity properties of the function y away from S_0	18
4.3. \mathbf{T} -conditional pseudo-convexity	20
5. Construction of the Hawking Killing vector-field \mathbf{K}	23
5.1. Proof of Proposition 5.4	26
5.2. Proof of Lemma 5.5	30

The first author was partially supported by a Clay research fellowship. The second author was partially supported by a Packard Fellowship. The third author was partially supported by NSF grant DMS-0070696.

6. Construction of the rotational Killing vector-field \mathbf{Z}	33
6.1. The time-like span of the two Killing fields.	34
Appendix A. Asymptotic identities	35
References	37

1. INTRODUCTION

It is widely expected¹ that the domains of outer communication of regular, stationary, four dimensional, vacuum black hole solutions are isometrically diffeomorphic to those of the Kerr black holes. Due to gravitational radiation, general, asymptotically flat, dynamic, solutions of the Einstein-vacuum equations ought to settle down, asymptotically, into a stationary regime. Thus the conjecture, if true, would characterize all possible asymptotic states of the general vacuum evolution. A similar scenario is supposed to hold true in the presence of matter.

So far the conjecture is known to be true² if, besides reasonable geometric and physical conditions, one assumes that the space-time metric in the domain of outer communication is *real analytic*. This last assumption is particularly restrictive, since there is no reason whatsoever that general stationary solutions of the Einstein field equations are analytic in the ergoregion, i.e. the region where the stationary Killing vector-field becomes space-like. Hawking's proof starts with the observation that the event horizon of a general stationary metric is non-expanding and the stationary Killing field must be tangent to it. Specializing to the future event horizon \mathcal{H}^+ , Hawking [21] (see also [26]) proved the existence of a non-vanishing vector-field \mathbf{K} tangent to the null generators of \mathcal{H}^+ and Killing to any order along \mathcal{H}^+ . Under the assumption of real analyticity of the space-time metric one can prove, by a Cauchy-Kowalewski type argument (see [21] and the rigorous argument in [13]), that the Hawking Killing vector-field \mathbf{K} can be extended to a neighborhood of the entire domain of outer communication. Thus, it follows, that the spacetime (\mathbf{M}, \mathbf{g}) is not just stationary but also axi-symmetric. To derive uniqueness, we then appeal to the theorem of Carter and Robinson which shows that the exterior region of a non-degenerate, stationary, axi-symmetric, connected, connected vacuum black hole must be isometrically diffeomorphic to a Kerr exterior of mass M and angular momentum $a < M$. The proof of this result originally obtained by Carter [7] and Robinson [32], has been strengthened and extended by many authors, notably Mazur [31], Bunting [5], Weinstein [36]; the most recent and complete account, which fills in various gaps in the previous literature is the recent paper of Chrusciel and Costa [17], see also [18]. A clear and complete exposition of the ideas that come into the proof can be found in Heusler's book, [22]. We remark the Carter Robinson theorem does not require analyticity.

¹See reviews by B. Carter [9] and P. Chrusciel [12] for a history and review of the current status of the conjecture.

²By combining results of Hawking [21], Carter [7], and Robinson [32], see also the recent work of Chrusciel-Costa [17].

In [24] a different strategy was followed based on the tensorial characterization of the Kerr spaces, due to Mars [29] and Simon [34], and a new analytic framework based on Carleman estimates. Uniqueness of Kerr was proved for a general class of regular stationary vacuum space-times which verify a complex scalar identity along the bifurcation sphere of the horizon. Unfortunately, to eliminate this local assumption, one needs a global argument which has alluded us so far.

In this paper we return to Hawking's original strategy and show how to extend his Killing vector-field, and thus axial symmetry, from the horizon to the entire domain of outer communication without appealing to analyticity. As noted above, once one has extended axial symmetry to the entire exterior region, the Carter-Robinson theorem implies that (\mathbf{M}, \mathbf{g}) must be isometric to a Kerr solution. Our argument, which relies on the Carleman estimates developed in [24] and [25], and their extensions in [1] and [2], require a smallness assumption which is expressed, geometrically, by assuming that the Mars-Simon tensor of our stationary metric is uniformly bounded by a sufficiently small constant. Our main result is therefore perturbative; we show that any regular stationary vacuum solution which is sufficiently close to a Kerr solution $\mathcal{K}(a, m)$, $0 \leq a < m$ must in fact coincide with it.

The first step of our approach has already been presented by us in [2]. There we show, under very general assumptions, how to construct the Hawking Killing vector-field in a neighborhood of a non-expanding, smooth, bifurcate horizon. The main idea, which also plays an essential role in this paper, is to turn the problem of extension into one of unique continuation, relying on Carleman estimates for systems of wave equations coupled to ordinary differential equations, see the introduction in [2] for an informal discussion.

To further extend these vector-fields to the entire domain of outer communication we make use of the foliation given by the level hypersurfaces of the function y , the real part of $(1 - \sigma)^{-1}$ where σ is the complex Ernst potential associated to the stationary vector-field \mathbf{T} , see subsection 2.3. The Carleman estimates on which our extension argument is based, depend on a crucial *\mathbf{T} -conditional pseudo-convexity* property for the function y (see Lemma 4.3) which was previously shown to hold true (see [24] and [25]) if the Mars-Simon tensor SS vanishes identically. Here we show that the the same property holds true if our space-time verifies our small perturbation assumption, i.e. SS sufficiently small. Thus, the main ideas of the paper are

- (1) A robust argument by which the problem of extension of Killing vector-fields is turned into a uniqueness problem for an ill-posed system of covariant wave equations coupled to ODE's.
- (2) A local extension argument of Hawking's Killing vector-field in a neighborhood of the bifurcate horizon. This step, which was accomplished in [2], is unconditional, i.e. it does not require the smallness assumption for SS .

- (3) An extension of the global argument of [24], by which the Hawking vector-field constructed in [2] in a neighborhood of the bifurcate horizon can be globally extended. This step, which rests on the \mathbf{T} -conditional pseudo-convexity property, requires our global smallness assumption for the Mars-Simon tensor SS .

In the subsection below we give precise assumptions and the statement of our main result.

1.1. Precise assumptions and the main theorem. We assume that (\mathbf{M}, \mathbf{g}) is a smooth³ vacuum Einstein spacetime of dimension $3 + 1$ and $\mathbf{T} \in \mathbf{T}(\mathbf{M})$ is a smooth Killing vector-field on \mathbf{M} . We also assume that we are given an embedded partial Cauchy surface $\Sigma^0 \subseteq \mathbf{M}$ and a diffeomorphism $\Phi_0 : E_{1/2} \rightarrow \Sigma^0$, where $E_r = \{x \in \mathbb{R}^3 : |x| > r\}$.

We group our main assumptions⁴ in three categories. The first one combines a standard asymptotic flatness assumption with a global assumption concerning the orbits of \mathbf{T} . The asymptotic flatness assumption, in particular, defines the asymptotic region $\mathbf{M}^{(end)}$ and the domain of outer communication (exterior region) $\mathbf{E} = \mathcal{I}^-(\mathbf{M}^{(end)}) \cap \mathcal{I}^+(\mathbf{M}^{(end)})$, where $\mathcal{I}^-(\mathbf{M}^{(end)})$, $\mathcal{I}^+(\mathbf{M}^{(end)})$ denote the past and respectively future sets of $\mathbf{M}^{(end)}$. Our second assumption concerns the smoothness of the two achronal boundaries $\delta(\mathcal{I}^-(\mathbf{M}^{(end)}))$ in a small neighborhood of their intersection $S_0 = \delta(\mathcal{I}^-(\mathbf{M}^{(end)})) \cap \delta(\mathcal{I}^+(\mathbf{M}^{(end)}))$. Our third assumption asserts that \mathbf{E} is a small perturbation a fixed Kerr metric, in a suitable sense. We give an invariant form to this assumption by making use of the Mars-Simon tensor SS whose vanishing characterizes Kerr spacetimes, see [29].

GR. (Global regularity assumption) We assume that the restriction of the diffeomorphism Φ_0 to E_{R_0} , for R_0 sufficiently large, extends to a diffeomorphism $\Phi_0 : \mathbb{R} \times E_{R_0} \rightarrow \mathbf{M}^{(end)}$, where $\mathbf{M}^{(end)}$ (asymptotic region) is an open subset of \mathbf{M} . In local coordinates $\{x^0, x^i\}$ defined by this diffeomorphism, we assume that $\mathbf{T} = \partial_0$ and, with $r = \sqrt{(x^1)^2 + (x^2)^2 + (x^3)^2}$, that the components of the spacetime metric verify⁵,

$$\mathbf{g}_{00} = -1 + \frac{2M}{r} + O_6(r^{-2}), \quad \mathbf{g}_{ij} = \delta_{ij} + O_6(r^{-1}), \quad \mathbf{g}_{0i} = -\epsilon_{ijk} \frac{2S^j x^k}{r^3} + O_6(r^{-3}), \quad (1.1)$$

for some $M > 0$, $S^1, S^2, S^3 \in \mathbb{R}$ (see [3]) such that,

$$J = [(S^1)^2 + (S^2)^2 + (S^3)^2]^{1/2} \in [0, M^2]. \quad (1.2)$$

Let

$$\mathbf{E} = \mathcal{I}^-(\mathbf{M}^{(end)}) \cap \mathcal{I}^+(\mathbf{M}^{(end)}).$$

We assume that \mathbf{E} is globally hyperbolic and

$$\Sigma^0 \cap \mathcal{I}^-(\mathbf{M}^{(end)}) = \Sigma^0 \cap \mathcal{I}^+(\mathbf{M}^{(end)}) = \Phi_0(E_1). \quad (1.3)$$

³ \mathbf{M} is a connected, oriented, time oriented, paracompact C^∞ manifold without boundary.

⁴Many of these assumptions can be justified as consequences of more primitive assumptions, see [3], [4], [11], [15], [16], [19], [20], [33]. For the sake of simplicity, we do not attempt to work here under the most general regularity assumptions. See the recent paper [17] for a careful discussion.

⁵We denote by $O_k(r^a)$ any smooth function in $\mathbf{M}^{(end)}$ which verifies $|\partial^i f| = O(r^{a-i})$ for any $0 \leq i \leq k$ with $|\partial^i f| = \sum_{i_0+i_1+i_2+i_3=i} |\partial_0^{i_0} \partial_1^{i_1} \partial_2^{i_2} \partial_3^{i_3} f|$.

We assume that \mathbf{T} does not vanish at any point of \mathbf{E} and that every orbit of \mathbf{T} in \mathbf{E} is complete and intersects the hypersurface Σ^0 .

SBS. (Smooth bifurcation sphere assumption) It follows from (1.3) that

$$\delta(\mathcal{I}^-(\mathbf{M}^{(end)})) \cap \Sigma^0 = \delta(\mathcal{I}^+(\mathbf{M}^{(end)})) \cap \Sigma^0 = S_0,$$

where $S_0 = \Phi_0(\{x \in \mathbb{R}^3 : |x| = 1\})$ is an imbedded 2-sphere (called the bifurcation sphere). We assume that there is a neighborhood \mathbf{O} of S_0 in \mathbf{M} such that the sets

$$\mathcal{H}^+ = \mathbf{O} \cap \delta(\mathcal{I}^-(\mathbf{M}^{(end)})) \quad \text{and} \quad \mathcal{H}^- = \mathbf{O} \cap \delta(\mathcal{I}^+(\mathbf{M}^{(end)}))$$

are smooth imbedded hypersurfaces. We assume that these hypersurfaces are null, non-expanding⁶, and intersect transversally in S_0 . Finally, we assume that the vector-field \mathbf{T} is tangent to both hypersurfaces \mathcal{H}^+ and \mathcal{H}^- , and does not vanish identically on S_0 .

PK. (Perturbation of Kerr assumption). Let σ denote the Ernst potential and SS the Mars-Simon tensor, defined in an open neighborhood of $\Sigma^0 \cap \overline{\mathbf{E}}$ in \mathbf{M} (see section 2 for precise definitions). We assume that

$$|(1 - \sigma)SS(\mathbf{T}, T_\alpha, T_\beta, T_\gamma)| \leq \bar{\varepsilon} \quad \text{on } \Sigma^0 \cap \overline{\mathbf{E}}, \quad (1.4)$$

for some sufficiently small constant $\bar{\varepsilon}$ (depending only on the constant \bar{A} defined in section 2), where T_0 is the future-directed unit vector orthogonal to Σ^0 and T_0, T_1, T_2, T_3 is an orthonormal basis along Σ^0 .

Main Theorem. *Under the assumptions **GR**, **SBS**, and **PK** the domain of outer communication \mathbf{E} of \mathbf{M} is isometric to the domain of outer communication of the Kerr space-time with mass M and angular momentum J .*

In other words, a stationary vacuum black hole, which satisfies suitable regularity assumptions and is sufficiently “close” to a Kerr solution, has to be isometric to that Kerr solution. This can be interpreted as a strong extension of Carter’s original theorem, see [7], [8], on stationary and axi-symmetric perturbations of the Kerr spaces, in which we remove the axi-symmetry assumption and give a geometric, coordinate independent, perturbation condition. We provide below a more detailed outline of the proof of the Main Theorem.

In section 2 we define a system of local coordinates along our reference space-like hypersurface Σ^0 , and define our main constant \bar{A} . The small constant $\bar{\varepsilon}$ in (1.4) is to be taken sufficiently small, depending only on \bar{A} . We review also the construction of two optical functions u and \underline{u} in a neighborhood of the bifurcation sphere S_0 , adapted to the null hypersurfaces \mathcal{H}^+ and \mathcal{H}^- , and recall the definition of the complex Ernst potential σ and the Mars-Simon tensor SS . Finally, we record some asymptotic formulas, which are proved in the appendix.

⁶A null hypersurface is said to be non-expanding if the trace of its null second fundamental form vanishes identically.

In section 3 we develop the main consequences of our smallness assumption (1.4). All of our results in this section are summarized in Proposition 3.4; we prove a lower bound on $|1 - \sigma|$ along Σ_1 , as well as several approximate identities in a small neighborhood of Σ_1 which are used in the rest of the paper.

In section 4 we derive several properties of the function y needed in the continuation argument in section 5. We prove first that y is almost constant on S_0 , as in Lemma 4.1, and increases in a controlled way in a neighborhood of S_0 in Σ_1 . Then we prove that the level sets of the function y away from S_0 are regular, in a suitable sense. Finally, we prove that the function y satisfies the \mathbf{T} -conditional pseudo-convexity property, away from S_0 , see Lemma 4.3.

In section 5, which is the heart of the paper, we construct the Hawking Killing vector-field \mathbf{K} in the domain of outer communication \mathbf{E} . The starting point is the existence of \mathbf{K} in a neighborhood of S_0 , which was proved in [2]. We extend \mathbf{K} to larger and larger regions, as measured by the function y , as the solution of an ordinary differential equation, see Lemma 5.3. We then prove that the resulting vector-field \mathbf{K} is Killing (and satisfies several other bootstrap conditions) as a consequence of a uniqueness property of stationary vacuum solutions, see Proposition 5.4. The proof of this last proposition relies on Carleman estimates and the properties of the function y proved in section 4.

In section 6 we construct a global, rotational Killing vector-field \mathbf{Z} which commutes with \mathbf{T} , as a linear combination of the vector-fields \mathbf{T} and \mathbf{K} . We also give a simple proof, specialized to our setting, that the span of the two Killing fields \mathbf{T}, \mathbf{Z} is time-like in \mathbf{E} .

2. PRELIMINARIES

2.1. A system of coordinates along Σ^0 . Let $\partial_1, \partial_2, \partial_3$ denote the vectors tangent to Σ^0 , induced by the diffeomorphism Φ_0 . Let $\Sigma_r = \Phi_0(E_r)$, where, as before, $E_r = \{x \in \mathbb{R}^3 : |x| > r\}$. In particular, for our original spacelike hypersurface, we have $\Sigma^0 = \Sigma_{1/2}$. Using (1.1) and the assumption that Σ^0 is spacelike, it follows that there are large constants A_1 and $R_1 \geq R_0$, such that $R_1 \geq A_1^4$, with the following properties: on $\Sigma_{3/4}$, for any $X = (X^1, X^2, X^3)$,

$$A_1^{-1}|X|^2 \leq \sum_{\alpha, \beta=1}^3 X^\alpha X^\beta \mathbf{g}_{\alpha\beta} \leq A_1|X|^2 \quad \text{and} \quad \sum_{\alpha=1}^3 |\mathbf{g}(\partial_\alpha, \mathbf{T})| + |\mathbf{g}(T_0, \mathbf{T})| \leq A_1. \quad (2.1)$$

In $\Phi_0(\mathbb{R} \times E_{R_1})$, which we continue to denote by $\mathbf{M}^{(end)}$, $\mathbf{T} = \partial_0$ and (see notation in footnote 5),

$$\begin{aligned} & \sum_{m=0}^6 r^{m+1} \sum_{j,k=1}^3 |\partial^m(\mathbf{g}_{jk} - \delta_{jk})| + \sum_{m=0}^6 r^{m+2} |\partial^m(\mathbf{g}_{00} + 1 - 2M/r)| \\ & + \sum_{m=0}^6 r^{m+3} \sum_{i=1}^3 |\partial^m(\mathbf{g}_{0i} + 2\epsilon_{ijk} S^j x^k r^{-3})| \leq A_1. \end{aligned} \quad (2.2)$$

We construct a system of coordinates in a small neighborhood $\widetilde{\mathbf{M}}$ of $\Sigma^0 \cap \overline{\mathbf{E}}$, which extends both the coordinate system of $\mathbf{M}^{(end)}$ in (2.2) and that of Σ^0 . We do that with the help of a smooth vector-field T' which interpolates between \mathbf{T} and T_0 . More precisely we construct T' in a neighborhood of $\Sigma_{3/4}$ such that $T' = \mathbf{T}$ in $\Phi_0(\mathbb{R} \times E_{2R_1})$ and $T' = \eta(r/R_1)T_0 + (1 - \eta(r/R_1))\mathbf{T}$ on $\Sigma_{3/4}$, where $\eta : \mathbb{R} \rightarrow [0, 1]$ is a smooth function supported in $(-\infty, 2]$ and equal to 1 in $(-\infty, 1]$. Using now the flow induced by T' we extend the original diffeomorphism $\Phi_0 : E_{1/2} \rightarrow \Sigma^0$, to cover a full neighborhood of Σ_1 . Thus there exists $\varepsilon_0 > 0$ sufficiently small and a diffeomorphism $\Phi_1 : (-\varepsilon_0, \varepsilon_0) \times E_{1-\varepsilon_0} \rightarrow \widetilde{\mathbf{M}}$, which agrees with Φ_0 on $\{0\} \times E_{1-\varepsilon_0} \cup (-\varepsilon_0, \varepsilon_0) \times E_{2R_1}$ and such that $\partial_0 = \partial_{x^0} = T'$. By setting ε_0 small enough, we may assume that $\mathcal{O}_{\varepsilon_0} := \Phi_1((-\varepsilon_0, \varepsilon_0) \times \{x \in \mathbb{R}^3 : |x| \in (1 - \varepsilon_0, 1 + \varepsilon_0)\}) \subseteq \mathcal{O}$, where \mathcal{O} is the open set defined in the assumption **SBS**. By construction, using also (2.2) and letting ε_0 sufficiently small depending on R_1 ,

$$\sum_{j=1}^3 |\mathbf{g}_{0j}| + |\mathbf{g}_{00} + 1| \leq A_1/(R_1 + r) \quad \text{in } \widetilde{\mathbf{M}}. \quad (2.3)$$

With $\mathbf{g}_{\alpha\beta} = \mathbf{g}(\partial_\alpha, \partial_\beta)$ and $\mathbf{T} = \mathbf{T}^\alpha \partial_\alpha$, let

$$A_2 = \sup_{p \in \widetilde{\mathbf{M}}} \sum_{m=0}^6 \left[\sum_{\alpha, \beta=0}^3 |\partial^m \mathbf{g}_{\alpha\beta}(p)| + \sum_{\alpha=0}^3 |\partial^m \mathbf{T}^\alpha(p)| \right]. \quad (2.4)$$

Finally, we fix

$$\overline{A} = \max(R_1, A_2, \varepsilon_0^{-1}, (M^2 - J)^{-1}). \quad (2.5)$$

The constant \overline{A} is our main effective constant. The constant $\overline{\varepsilon}$ in (1.4) will be fixed sufficiently small, depending only on \overline{A} . To summarize, we defined a neighborhood $\widetilde{\mathbf{M}}$ of $\Sigma^0 \cap \overline{\mathbf{E}}$ and a diffeomorphism $\Phi_1 : (-\varepsilon_0, \varepsilon_0) \times E_{1-\varepsilon_0} \rightarrow \widetilde{\mathbf{M}}$, $\varepsilon_0 > 0$, such that the bounds (2.1), (2.2), (2.3), (2.4) hold (in coordinates induced by the diffeomorphism Φ_1).

2.2. Optical functions in a neighborhood of S_0 . We define two optical functions u, \underline{u} in a neighborhood of S_0 . We fix a smooth future-directed null pair (L, \underline{L}) along S_0 , satisfying

$$\mathbf{g}(L, L) = \mathbf{g}(\underline{L}, \underline{L}) = 0, \quad \mathbf{g}(L, \underline{L}) = -1, \quad (2.6)$$

such that L is tangent to \mathcal{H}^+ and \underline{L} is tangent to \mathcal{H}^- . In a small neighborhood of S_0 , we extend L (resp. \underline{L}) along the null geodesic generators of \mathcal{H}^+ (resp. \mathcal{H}^-) by parallel transport, i.e. $\mathbf{D}_L L = 0$ (resp. $\mathbf{D}_{\underline{L}} \underline{L} = 0$). We define the function \underline{u} (resp. u) along \mathcal{H}^+ (resp. \mathcal{H}^-) by setting $u = \underline{u} = 0$ on S_0 and solving $L(\underline{u}) = 1$ (resp. $\underline{L}(u) = 1$). Let $S_{\underline{u}}$ (resp. S_u) be the level surfaces of \underline{u} (resp. u) along \mathcal{H}^+ (resp. \mathcal{H}^-). We define \underline{L} at every point of \mathcal{H}^+ (resp. L at every point of \mathcal{H}^-) as the unique, future directed null vector-field orthogonal to the surface $S_{\underline{u}}$ (resp. S_u) passing through that point and such that $\mathbf{g}(L, \underline{L}) = -1$. We now define the null hypersurface $\mathcal{H}_{\underline{u}}^-$ to be the congruence of null geodesics initiating on $S_{\underline{u}} \subset \mathcal{H}^+$ in the direction of \underline{L} . Similarly we define \mathcal{H}_u^+ to be the congruence of null geodesics initiating on $S_u \subset \mathcal{H}^-$ in the direction of L . Both

congruences are well defined in a sufficiently small neighborhood of S_0 in \mathcal{O} . The null hypersurfaces $\mathcal{H}_{\underline{u}}^-$ (resp. \mathcal{H}_u^+) are the level sets of a function \underline{u} (resp u) vanishing on \mathcal{H}^- (resp. \mathcal{H}^+). By construction

$$L = -\mathbf{g}^{\mu\nu} \partial_\mu u \partial_\nu, \quad \underline{L} = -\mathbf{g}^{\mu\nu} \partial_\mu \underline{u} \partial_\nu. \quad (2.7)$$

In particular, the functions u, \underline{u} are both null optical functions, i.e.

$$\mathbf{g}^{\mu\nu} \partial_\mu u \partial_\nu u = \mathbf{g}(L, L) = 0 \quad \text{and} \quad \mathbf{g}^{\mu\nu} \partial_\mu \underline{u} \partial_\nu \underline{u} = \mathbf{g}(\underline{L}, \underline{L}) = 0. \quad (2.8)$$

To summarize, there is $c_0 = c_0(\bar{A}) \in (0, \varepsilon_0]$ sufficiently small and smooth optical functions $u, \underline{u} : \mathcal{O}_{c_0} \rightarrow \mathbb{R}$, where $\mathcal{O}_{c_0} = \Phi_1((-c_0, c_0) \times \{x \in \mathbb{R}^3 : |x| \in (1 - c_0, 1 + c_0)\})$. In local coordinates induced by the diffeomorphism Φ_1 we have⁷

$$\sup_{x \in \mathcal{O}_{c_0}} \sum_{j=0}^4 (|\partial^j u(x)| + |\partial^j \underline{u}(x)|) \leq \tilde{C} = \tilde{C}(\bar{A}). \quad (2.9)$$

In addition,

$$\mathcal{H}^+ \cap \mathcal{O}_{c_0} = \{p \in \mathcal{O}_{c_0} : u(p) = 0\}, \quad \mathcal{H}^- \cap \mathcal{O}_{c_0} = \{p \in \mathcal{O}_{c_0} : \underline{u}(p) = 0\}. \quad (2.10)$$

In \mathcal{O}_{c_0} we define

$$\Omega = \mathbf{g}^{\mu\nu} \partial_\mu u \partial_\nu \underline{u} = \mathbf{g}(L, \underline{L}).$$

By construction $\Omega = -1$ on $(\mathcal{H}^+ \cup \mathcal{H}^-) \cap \mathcal{O}_{c_0}$ (we remark, however, that Ω is not necessarily equal to -1 in \mathcal{O}_{c_0}). By taking c_0 small enough, we may assume that

$$\Omega \in [-3/2, -1/2] \quad \text{in } \mathcal{O}_{c_0}. \quad (2.11)$$

Finally, by construction, we may assume that the functions $|u|, |\underline{u}|$ are proportional to $|1 - r|$ on the spacelike hypersurface $\Sigma^0 \cap \mathcal{O}_{c_0}$, i.e.

$$|u/(1 - r)|, |\underline{u}/(1 - r)| \in [\tilde{C}^{-1}, \tilde{C}] \quad \text{on } \Sigma^0 \cap \mathcal{O}_{c_0}, \quad (2.12)$$

where, as in (2.9), \tilde{C} is a constant that depends only on \bar{A} .

2.3. Definitions and asymptotic formulas. We recall now the definitions of the Ernst potential σ and the Mars–Simon tensor SS (see [24, Section 4] for a longer discussion and proofs of all of the identities). In \mathbf{M} we define the 2-form,

$$F_{\alpha\beta} = \mathbf{D}_\alpha \mathbf{T}_\beta$$

and the complex valued 2-form,

$$\mathcal{F}_{\alpha\beta} = F_{\alpha\beta} + i {}^* F_{\alpha\beta} = F_{\alpha\beta} + (i/2) \epsilon_{\alpha\beta}{}^{\mu\nu} F_{\mu\nu}. \quad (2.13)$$

Let $\mathcal{F}^2 = \mathcal{F}_{\alpha\beta} \mathcal{F}^{\alpha\beta}$. We define also the Ernst 1-form

$$\sigma_\mu = 2\mathbf{T}^\alpha \mathcal{F}_{\alpha\mu} = \mathbf{D}_\mu(-\mathbf{T}^\alpha \mathbf{T}_\alpha) - i \epsilon_{\mu\beta\gamma\delta} \mathbf{T}^\beta \mathbf{D}^\gamma \mathbf{T}^\delta. \quad (2.14)$$

⁷Recall the notation $|\partial^j f| = \sum_{j_0+j_1+j_2+j_3=j} |\partial_0^{j_0} \partial_1^{j_1} \partial_2^{j_2} \partial_3^{j_3} f|$, where $\partial_0, \partial_1, \partial_2, \partial_3$ are the derivatives induced by the diffeomorphism Φ_1 . This notation will be used throughout the paper.

It is easy to check that, in \mathbf{M}

$$\begin{cases} \mathbf{D}_\mu \sigma_\nu - \mathbf{D}_\nu \sigma_\mu = 0; \\ \mathbf{D}^\mu \sigma_\mu = -\mathcal{F}^2; \\ \sigma_\mu \sigma^\mu = \mathbf{g}(\mathbf{T}, \mathbf{T}) \mathcal{F}^2. \end{cases} \quad (2.15)$$

Since $\mathbf{D}_\mu \sigma_\nu = \mathbf{D}_\nu \sigma_\mu$ and the sets $\widetilde{\mathbf{M}} = \Phi_1((-\varepsilon_0, \varepsilon_0) \times E_{1-\varepsilon_0})$ and \mathbf{E} are simply connected, we can define the Ernst potential $\sigma : \widetilde{\mathbf{M}} \cup \mathbf{E} \rightarrow \mathbb{C}$ such that $\sigma_\mu = \mathbf{D}_\mu \sigma$, $\Re \sigma = -\mathbf{T}^\alpha \mathbf{T}_\alpha$, and $\sigma \rightarrow 1$ at infinity along Σ^0 .

We define the complex-valued self-dual Weyl tensor

$$\mathcal{R}_{\alpha\beta\mu\nu} = R_{\alpha\beta\mu\nu} + (i/2)\epsilon_{\mu\nu}{}^{\rho\sigma} R_{\alpha\beta\rho\sigma} = R_{\alpha\beta\mu\nu} + i {}^*R_{\alpha\beta\mu\nu}. \quad (2.16)$$

We define the tensor $\mathcal{I} \in \mathbf{T}_4^0(\mathbf{M})$,

$$\mathcal{I}_{\alpha\beta\mu\nu} = (\mathbf{g}_{\alpha\mu}\mathbf{g}_{\beta\nu} - \mathbf{g}_{\alpha\nu}\mathbf{g}_{\beta\mu} + i \epsilon_{\alpha\beta\mu\nu})/4. \quad (2.17)$$

Let $\widetilde{\mathbf{M}}' = \{p \in \widetilde{\mathbf{M}} : \sigma(p) \neq 1\}$ ⁸. We define the tensor-field $\mathcal{Q} \in \mathbf{T}_4^0(\widetilde{\mathbf{M}}')$,

$$\mathcal{Q}_{\alpha\beta\mu\nu} = (1 - \sigma)^{-1} (\mathcal{F}_{\alpha\beta}\mathcal{F}_{\mu\nu} - \frac{1}{3}\mathcal{F}^2\mathcal{I}_{\alpha\beta\mu\nu}). \quad (2.18)$$

It is easy to see that the tensor-field \mathcal{Q} is a self-dual Weyl field, i.e.

$$\begin{cases} \mathcal{Q}_{\alpha\beta\mu\nu} = -\mathcal{Q}_{\beta\alpha\mu\nu} = -\mathcal{Q}_{\alpha\beta\nu\mu} = \mathcal{Q}_{\mu\nu\alpha\beta}; \\ \mathcal{Q}_{\alpha\beta\mu\nu} + \mathcal{Q}_{\alpha\mu\nu\beta} + \mathcal{Q}_{\alpha\nu\beta\mu} = 0; \\ \mathbf{g}^{\beta\nu}\mathcal{Q}_{\alpha\beta\mu\nu} = 0, \end{cases}$$

and

$${}^*\mathcal{Q}_{\alpha\beta\mu\nu} = \frac{1}{2}\epsilon_{\mu\nu\rho\sigma}\mathcal{Q}_{\alpha\beta}{}^{\rho\sigma} = (-i)\mathcal{Q}_{\alpha\beta\mu\nu}.$$

We define now the self-dual Weyl field SS , called the Mars–Simon tensor,

$$SS = \mathcal{R} + 6\mathcal{Q}. \quad (2.19)$$

We observe that $(1 - \sigma)\S$ is a smooth tensor on $\widetilde{\mathbf{M}}$. Using the Ricci identity

$$\mathbf{D}_\mu \mathcal{F}_{\alpha\beta} = \mathbf{T}^\nu \mathcal{R}_{\nu\mu\alpha\beta}, \quad (2.20)$$

and proceeding as in [24, formula 4.33], we deduce that, in $\widetilde{\mathbf{M}}'$,

$$\mathbf{D}_\rho [\mathcal{F}^2(1 - \sigma)^{-4}] = 2(1 - \sigma)^{-4} \mathbf{T}^\nu SS_{\nu\rho\gamma\delta} \mathcal{F}^{\gamma\delta}. \quad (2.21)$$

This identity will play a key role in the analysis in section 3. Finally, we define the functions $y, z : \widetilde{\mathbf{M}}' \rightarrow \mathbb{R}$

$$y + iz = (1 - \sigma)^{-1}.$$

⁸Using the assumption **PK**, we will prove in section 3 that $\Sigma_1 \subseteq \widetilde{\mathbf{M}}'$.

Simple asymptotic computations using the formula (2.2), see Appendix A, show that, for R sufficiently large depending only on \bar{A} ,

$$\mathcal{F}_{\alpha\beta} = O(r^{-2}), \quad SS_{\alpha\beta\gamma\delta} = O(r^{-3}), \quad \alpha, \beta, \gamma, \delta = 0, \dots, 3. \quad (2.22)$$

More precisely,

$$1 - \sigma = 2Mr^{-1} + O(r^{-2}), \quad \mathcal{F}^2 = -4M^2r^{-4} + O(r^{-5}) \quad (2.23)$$

in $\Phi_1((-\varepsilon_0, \varepsilon_0) \times E_R)$. In particular, $\Phi_1((-\varepsilon_0, \varepsilon_0) \times E_R) \subseteq \widetilde{\mathbf{M}}$ and

$$-4M^2\mathcal{F}^2(1 - \sigma)^{-4} = 1 + O(r^{-1}) \quad \text{in} \quad \Phi_1((-\varepsilon_0, \varepsilon_0) \times E_R). \quad (2.24)$$

In addition

$$y = \frac{r}{2M} + O(1), \quad z = \frac{S^1x^1 + S^2x^2 + S^3x^3}{2M^2r} + O(r^{-1}) \quad (2.25)$$

in $\Phi_1((-\varepsilon_0, \varepsilon_0) \times E_R)$. Finally,

$$z^2 + 4M^2(y^2 + z^2)\mathbf{D}_\mu z \mathbf{D}^\mu z = \frac{J^2}{4M^4} + O(r^{-1}) \quad \text{in} \quad \Phi_1((-\varepsilon_0, \varepsilon_0) \times E_R). \quad (2.26)$$

All these asymptotic identities are proved in Appendix A and will be used in section 3.

3. ANALYSIS ON THE HYPERSURFACE Σ_1

In this section we use assumption **PK** to prove several approximate identities on the hypersurface $\Sigma_1 = \Sigma^0 \cap \mathbf{E} = \Phi_0(E_1)$. The general idea is to prove approximate identities such as (2.24) and (2.26) first in the asymptotic region, using the asymptotic flatness assumption (2.2), and then extend them to the entire hypersurface Σ_1 using the fact that the Mars–Simon tensor is assumed to be small. We will prove also that $1 - \sigma$ does not vanish in Σ_1 . All of our results in this section are summarized in Proposition 3.4.

We will use the notation in section 2. We fix first a large constant \bar{R} which depends only on our main constant \bar{A} (see (2.5)). We fix r_0 the smallest number in $[1, \bar{R} - 1]$ with the property that

$$|1 - \sigma| \geq \bar{R}^{-2} \quad \text{on} \quad \Sigma_{r_0} \setminus \Sigma_{\bar{R}}, \quad (3.1)$$

where, as before, $\Sigma_r = \Phi_0(E_r)$, $E_r = \{x \in \mathbf{R}^3 : |x| > r\}$. Such an r_0 exists if \bar{R} is sufficiently large, in view of (2.23) and the continuity of $1 - \sigma$. We will prove, among other things, that $r_0 = 1$. In this section we let \tilde{C} denote various constants in $[1, \infty)$ that may depend only on \bar{R} (thus on \bar{A} once \bar{R} is fixed sufficiently large depending on \bar{A}). The value of $\bar{\varepsilon}$ in (1.4) is assumed to be sufficiently small depending on the constants \tilde{C} . To summarize, $\log(\bar{A}) \ll \log(\bar{R}) \ll \log(\tilde{C}) \ll \log(\bar{\varepsilon}^{-1})$.

We will work in the region $\Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{r_0}]$. Since $|\partial_0(1 - \sigma)| \leq \tilde{C}$, it follows from (3.1) and (2.23) that

$$|1 - \sigma|^{-1} \leq \tilde{C}r \quad \text{in} \quad \Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{r_0}]. \quad (3.2)$$

Using the assumption (1.4) and the asymptotic identities (2.22), we have

$$|(1 - \sigma)\mathbf{T}^\nu SS_{\nu\rho\gamma\delta}| \leq \tilde{C} \min(\bar{\varepsilon}, r^{-4}) \quad \text{in} \quad \Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{r_0}], \quad (3.3)$$

in the coordinate frame $\partial_0, \partial_1, \partial_2, \partial_3$. Using (2.21), (2.22) and the last two inequalities, it follows that

$$|\partial_\rho(\mathcal{F}^2(1-\sigma)^{-4})| \leq \tilde{C}r^3 \min(\bar{\varepsilon}, r^{-4}) \quad \text{in } \Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{r_0}]. \quad (3.4)$$

We prove now that

$$|1 + 4M^2\mathcal{F}^2(1-\sigma)^{-4}| \leq \tilde{C} \min(r^{-1}, \bar{\varepsilon}^{1/5}) \quad \text{in } \Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{r_0}]. \quad (3.5)$$

Indeed, let $H = 1 + 4M^2\mathcal{F}^2(1-\sigma)^{-4}$. Using (2.24) and (3.4),

$$|H| \leq \tilde{C}r^{-1} \quad \text{and} \quad \sum_{\rho=0}^4 |\partial_\rho H| \leq \tilde{C}r^3 \min(\bar{\varepsilon}, r^{-4}) \quad \text{in } \Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{r_0}]. \quad (3.6)$$

The bound (3.5) follows from the first inequality in (3.6) at points p for which $r(p) \geq \varepsilon^{-1/5}$. To prove (3.5) at points p with $r(p) \leq \varepsilon^{-1/5}$ we fix a point $p' \in \Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{r_0}]$ with $r(p') = \varepsilon^{-1/5}$. We integrate along a line joining the points p and p' and use the second inequality in (3.6). The result is $|H(p) - H(p')| \leq \tilde{C}\varepsilon^{-4/5}\bar{\varepsilon}$, which gives (3.5) since $|H(p')| \leq \tilde{C}r(p')^{-1} = \tilde{C}\varepsilon^{-1/5}$.

It follows from (3.4) and (3.5) that there is a smooth function $G_1 : \Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{r_0}] \rightarrow \mathbb{C}$ with the properties

$$-4M^2\mathcal{F}^2 = (1-\sigma)^4(1+G_1)^2, \quad |G_1| + \sum_{\rho=0}^3 |\partial_\rho G_1| \leq \tilde{C} \min(r^{-1}, \bar{\varepsilon}^{1/5}) \quad (3.7)$$

on $\Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{r_0}]$. In particular, using also (3.2),

$$|\mathcal{F}^2| \geq (\tilde{C}r)^{-4} \quad \text{in } \Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{r_0}]. \quad (3.8)$$

We define the smooth function $P = y + iz : \Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{r_0}] \rightarrow \mathbb{C}$,

$$P = y + iz = (1-\sigma)^{-1}. \quad (3.9)$$

We construct now a special null pair, similar to the principal null pair in [29, Section 4].

Lemma 3.1. *There exists a future-directed null pair l, \underline{l} , $\mathbf{g}(l, \underline{l}) = -1$, such that*

$$\mathcal{F}_{\alpha\beta}l^\beta = (1+G_1)(4MP^2)^{-1}l_\alpha, \quad \mathcal{F}_{\alpha\beta}\underline{l}^\beta = -(1+G_1)(4MP^2)^{-1}\underline{l}_\alpha, \quad (3.10)$$

in $\Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{r_0}]$.

Proof of Lemma 3.1. Let Z_α be complex eigenvector $\mathcal{F}_{\alpha\beta}Z^\beta = \lambda Z_\alpha$ with complex eigenvalue λ . Using the relation $\mathcal{F}_{\alpha\sigma}\mathcal{F}_\beta{}^\sigma = (1/4)\mathbf{g}_{\alpha\beta}\mathcal{F}^2$ (see [24, formula 4.2]) we derive,

$$\lambda^2 = -\frac{1}{4}\mathcal{F}^2 = \frac{1}{16M^2}(1-\sigma)^4(1+G_1)^2.$$

Thus, $\lambda = \pm(4MP^2)^{-1}(1+G_1)$. The reality of the corresponding eigenvectors l, \underline{l} is a consequence of the self duality of \mathcal{F} . They must both be null in view of the antisymmetry of \mathcal{F} and can be normalized appropriately. \square

Let $e_{(3)} = \underline{l}$, $e_{(4)} = l$. We fix vector-fields $e_{(1)}, e_{(2)}$ in $\Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{r_0}]$ such that together with $e_{(3)} = \underline{l}$, $e_{(4)} = l$ they form a positively oriented null frame, i.e.,

$$\begin{aligned} \mathbf{g}(l, e_{(1)}) &= \mathbf{g}(l, e_{(2)}) = \mathbf{g}(\underline{l}, e_{(1)}) = \mathbf{g}(\underline{l}, e_{(2)}) = \mathbf{g}(e_{(1)}, e_{(2)}) = 0, \\ \mathbf{g}(e_{(1)}, e_{(1)}) &= \mathbf{g}(e_{(2)}, e_{(2)}) = \epsilon_{(1)(2)(3)(4)} = 1. \end{aligned} \quad (3.11)$$

In view of (3.8), the vector-fields $e_{(\mu)} = e_{(\mu)}^\alpha \partial_\alpha$, $\mu = 1, 2, 3, 4$ can be chosen such that

$$\sum_{\mu=1}^4 \sum_{\alpha=0}^3 |e_{(\mu)}^\alpha| \leq \tilde{C} \quad \text{in } \Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{r_0}]. \quad (3.12)$$

According to (3.10), (3.11) and the self duality of \mathcal{F} , the components of \mathcal{F} are,

$$\mathcal{F}_{(4)(1)} = \mathcal{F}_{(4)(2)} = \mathcal{F}_{(3)(1)} = \mathcal{F}_{(3)(2)} = 0 \text{ and } \mathcal{F}_{(4)(3)} = i\mathcal{F}_{(2)(1)} = (1 + G_1)/(4MP^2). \quad (3.13)$$

This is equivalent to the identity,

$$\mathcal{F}_{\alpha\beta} = \frac{1 + G_1}{4MP^2} (-l_\alpha \underline{l}_\beta + l_\beta \underline{l}_\alpha - i \epsilon_{\alpha\beta\mu\nu} l^\mu \underline{l}^\nu). \quad (3.14)$$

By contracting (3.14) with $2\mathbf{T}^\alpha$ and using $2\mathbf{T}^\alpha \mathcal{F}_{\alpha\beta} = \sigma_\beta = \mathbf{D}_\beta \sigma$ we derive

$$\mathbf{D}_\beta(y + iz) = \frac{1 + G_1}{2M} [- (\mathbf{T}^\alpha l_\alpha) \underline{l}_\beta + (\mathbf{T}^\alpha \underline{l}_\alpha) l_\beta - i \epsilon_{\alpha\beta\mu\nu} \mathbf{T}^\alpha l^\mu \underline{l}^\nu].$$

In particular, if $G_1 = \Re G_1 + i\Im G_1$, we have

$$\begin{aligned} \mathbf{D}_\beta y &= \frac{1 + \Re G_1}{2M} [- (\mathbf{T}^\alpha l_\alpha) \underline{l}_\beta + (\mathbf{T}^\alpha \underline{l}_\alpha) l_\beta] + \frac{\Im G_1}{2M} \epsilon_{\alpha\beta\mu\nu} \mathbf{T}^\alpha l^\mu \underline{l}^\nu, \\ \mathbf{D}_\beta z &= -\frac{1 + \Re G_1}{2M} \epsilon_{\alpha\beta\mu\nu} \mathbf{T}^\alpha l^\mu \underline{l}^\nu + \frac{\Im G_1}{2M} [- (\mathbf{T}^\alpha l_\alpha) \underline{l}_\beta + (\mathbf{T}^\alpha \underline{l}_\alpha) l_\beta]. \end{aligned} \quad (3.15)$$

It follows from (3.15) and (3.7) that

$$|\mathbf{D}_{(1)} y| + |\mathbf{D}_{(2)} y| + |\mathbf{D}_{(3)} z| + |\mathbf{D}_{(4)} z| \leq \tilde{C} \min(r^{-1}, \bar{\varepsilon}^{1/5}) \quad \text{in } \Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{r_0}]. \quad (3.16)$$

A direct computation using the definition of P and (2.15) shows that

$$\mathbf{D}_\alpha P \mathbf{D}^\alpha P = \frac{\mathbf{D}_\alpha \sigma \mathbf{D}^\alpha \sigma}{(1 - \sigma)^4} = -\frac{(1 + G_1)^2 \mathbf{T}^\alpha \mathbf{T}_\alpha}{4M^2}. \quad (3.17)$$

Since $-\mathbf{T}^\alpha \mathbf{T}_\alpha = \Re \sigma = 1 - y/(y^2 + z^2)$ we have

$$\begin{aligned} \mathbf{D}_\alpha y \mathbf{D}^\alpha y - \mathbf{D}_\alpha z \mathbf{D}^\alpha z &= \frac{(1 + \Re G_1)^2 - (\Im G_1)^2}{4M^2} \left(1 - \frac{y}{y^2 + z^2}\right), \\ \mathbf{D}_\alpha y \mathbf{D}^\alpha z &= \frac{(1 + \Re G_1) \Im G_1}{4M^2} \left(1 - \frac{y}{y^2 + z^2}\right). \end{aligned} \quad (3.18)$$

3.1. A lemma of Mars. The following lemma is an adaptation to our situation of an important calculation which first appears in [29].

Lemma 3.2. *With $B = J^2/(4M^4) < 1/4$ we have in $\Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{r_0}]$,*

$$|4M^2(y^2 + z^2)\mathbf{D}_\beta z \mathbf{D}^\beta z + z^2 - B| \leq \tilde{C} \min(r^{-1}, \bar{\varepsilon}^{1/40}). \quad (3.19)$$

Proof of Lemma 3.2. We show that the function $H := 4M^2(y^2 + z^2)\mathbf{D}_\beta z \mathbf{D}^\beta z + z^2$ is almost constant by computing its derivatives with respect to our null frame (3.11). In the particular case $SS = 0$, the constancy of H was first proved in [29] using the full Newman-Penrose formalism. A similar proof was later given in [24]. Here we give instead a straightforward proof based only on the formulas we have derived so far.

We will prove that

$$\sum_{\alpha=0}^3 |\partial_\alpha H(p)| \leq \tilde{C} \bar{\varepsilon}^{1/20} \quad \text{if } p \in \Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{r_0}] \text{ and } r(p) \leq \varepsilon^{-1/40}. \quad (3.20)$$

Assuming this, the bound (3.19) follows from the bound $|H - B| \leq \tilde{C}r^{-1}$ in $\Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{r_0}]$, see (2.26), in the same way the bound (3.5) follows from (3.4) and (2.24).

We differentiate H and derive,

$$\mathbf{D}_\alpha H = 8M^2(y^2 + z^2)\mathbf{D}_\alpha \mathbf{D}_\beta z \mathbf{D}^\beta z + 8M^2(y\mathbf{D}_\alpha y + z\mathbf{D}_\alpha z)\mathbf{D}_\beta z \mathbf{D}^\beta z + 2z\mathbf{D}_\alpha z. \quad (3.21)$$

To calculate the main term $8M^2(y^2 + z^2)\mathbf{D}_\alpha \mathbf{D}_\beta z \mathbf{D}^\beta z$ we first calculate the second covariant derivatives of $P = (y + iz)$, using the definition of SS and (2.20),

$$\begin{aligned} \mathbf{D}_\alpha \mathbf{D}_\beta P &= 2(1 - \sigma)^{-3} \mathbf{D}_\alpha \sigma \mathbf{D}_\beta \sigma + (1 - \sigma)^{-2} \mathbf{D}_\alpha \mathbf{D}_\beta \sigma \\ &= 2(1 - \sigma)^{-3} \mathbf{D}_\alpha \sigma \mathbf{D}_\beta \sigma + 2(1 - \sigma)^{-2} (F_\alpha{}^\rho \mathcal{F}_{\rho\beta} + \mathbf{T}^\rho \mathbf{T}^\nu \mathcal{R}_{\nu\alpha\rho\beta}) \\ &= 2(1 - \sigma)^{-3} \mathbf{D}_\alpha \sigma \mathbf{D}_\beta \sigma + 2(1 - \sigma)^{-2} F_\alpha{}^\rho \mathcal{F}_{\rho\beta} \\ &\quad - 12(1 - \sigma)^{-2} \mathbf{T}^\rho \mathbf{T}^\nu \mathcal{Q}_{\nu\alpha\rho\beta} + 2(1 - \sigma)^{-2} \mathbf{T}^\rho \mathbf{T}^\nu SS_{\nu\alpha\rho\beta} \\ &= 2(1 - \sigma)^{-2} F_\alpha{}^\rho \mathcal{F}_{\rho\beta} + 2(1 - \sigma)^{-2} \mathbf{T}^\rho \mathbf{T}^\nu SS_{\nu\alpha\rho\beta} \\ &\quad - (1 - \sigma)^{-3} \sigma_\alpha \sigma_\beta + (1 - \sigma)^{-3} \mathcal{F}^2 [\mathbf{g}_{\alpha\beta} (\mathbf{T}^\rho \mathbf{T}_\rho) - \mathbf{T}_\alpha \mathbf{T}_\beta] \\ &= 2P^2 F_\alpha{}^\rho \mathcal{F}_{\rho\beta} + P^{-1} [(\mathbf{D}_\rho P \mathbf{D}^\rho P) \mathbf{g}_{\alpha\beta} - \mathbf{D}_\alpha P \mathbf{D}_\beta P] \\ &\quad + 2P^2 \mathbf{T}^\rho \mathbf{T}^\nu SS_{\nu\alpha\rho\beta} - P^3 \mathcal{F}^2 \mathbf{T}_\alpha \mathbf{T}_\beta. \end{aligned}$$

Thus, we have the identity

$$\begin{aligned} \mathbf{D}_\alpha \mathbf{D}_\beta P &= -P^{-1} \mathbf{D}_\alpha P \mathbf{D}_\beta P + P^{-1} (\mathbf{D}_\rho P \mathbf{D}^\rho P) \mathbf{g}_{\alpha\beta} \\ &\quad - 2P^2 F_\alpha{}^\rho \mathcal{F}_{\rho\beta} - P^3 \mathcal{F}^2 \mathbf{T}_\alpha \mathbf{T}_\beta + 2P^2 \mathbf{T}^\rho \mathbf{T}^\nu SS_{\nu\alpha\rho\beta}. \end{aligned} \quad (3.22)$$

Since $\mathbf{T}(z) = 0$ we deduce,

$$\begin{aligned} \mathbf{D}_\alpha \mathbf{D}_\beta P \mathbf{D}^\beta z &= P^{-1} (\mathbf{D}_\rho P \mathbf{D}^\rho P) \mathbf{D}_\alpha z - 2P^2 F_\alpha{}^\rho \mathcal{F}_{\rho\beta} \mathbf{D}^\beta z \\ &\quad - P^{-1} \mathbf{D}_\alpha P \mathbf{D}_\beta P \mathbf{D}^\beta z + 2P^2 \mathbf{T}^\rho \mathbf{T}^\nu SS_{\nu\alpha\rho\beta} \mathbf{D}^\beta z. \end{aligned} \quad (3.23)$$

Observe that $\mathbf{D}_\alpha \mathbf{D}_\beta z \mathbf{D}^\beta z = \Im[\mathbf{D}_\alpha \mathbf{D}_\beta P \mathbf{D}^\beta z]$. Thus, in view of (3.23)

$$\begin{aligned} \mathbf{D}_\alpha \mathbf{D}_\beta z \mathbf{D}^\beta z &= \Im[-2P^2 F_\alpha^\rho \mathcal{F}_{\beta\rho} \mathbf{D}^\beta z + 2P^2 \mathbf{T}^\rho \mathbf{T}^\nu S S_{\nu\alpha\rho\beta} \mathbf{D}^\beta z] \\ &\quad - \Im[P^{-1} \mathbf{D}_\alpha P \mathbf{D}_\beta P \mathbf{D}^\beta z] + \Im[P^{-1} (\mathbf{D}_\rho P \mathbf{D}^\rho P) \mathbf{D}_\alpha z]. \end{aligned} \quad (3.24)$$

Now,

$$\begin{aligned} (y^2 + z^2) \Im[P^{-1} \mathbf{D}_\alpha P \mathbf{D}_\beta P \mathbf{D}^\beta z] &= \mathbf{D}^\beta z \Im[(y - iz) \mathbf{D}_\alpha (y + iz) \mathbf{D}_\beta (y + iz)] \\ &= (y \mathbf{D}_\alpha y + z \mathbf{D}_\alpha z) \mathbf{D}^\beta z \mathbf{D}_\beta z + (y \mathbf{D}_\alpha z - z \mathbf{D}_\alpha y) \mathbf{D}^\beta y \mathbf{D}_\beta z \end{aligned}$$

and,

$$\begin{aligned} (y^2 + z^2) \Im[P^{-1} \mathbf{D}_\rho P \mathbf{D}^\rho P \mathbf{D}_\alpha z] &= \mathbf{D}_\alpha z \Im[(y - iz) \mathbf{D}_\rho (y + iz) \mathbf{D}^\rho (y + iz)] \\ &= 2y \mathbf{D}_\alpha z \mathbf{D}_\rho y \mathbf{D}^\rho z - z \mathbf{D}_\alpha z (\mathbf{D}_\rho y \mathbf{D}^\rho y - \mathbf{D}_\rho z \mathbf{D}^\rho z). \end{aligned}$$

Therefore, back to (3.24),

$$\begin{aligned} (y^2 + z^2) \mathbf{D}_\alpha \mathbf{D}_\beta z \mathbf{D}^\beta z &= (y^2 + z^2) \Im[-2P^2 F_\alpha^\rho \mathcal{F}_{\beta\rho} \mathbf{D}^\beta z + 2P^2 \mathbf{T}^\rho \mathbf{T}^\nu S S_{\nu\alpha\rho\beta} \mathbf{D}^\beta z] \\ &\quad - y \mathbf{D}_\alpha y \mathbf{D}_\rho z \mathbf{D}^\rho z + (y \mathbf{D}_\alpha z + z \mathbf{D}_\alpha y) \mathbf{D}_\rho y \mathbf{D}^\rho z - z \mathbf{D}_\alpha z \mathbf{D}_\rho y \mathbf{D}^\rho y. \end{aligned}$$

Going back to (3.21) we derive,

$$\begin{aligned} \mathbf{D}_\alpha H &= 8M^2 (y^2 + z^2) \Im[-2P^2 F_\alpha^\rho \mathcal{F}_{\beta\rho} \mathbf{D}^\beta z + 2P^2 \mathbf{T}^\rho \mathbf{T}^\nu S S_{\nu\alpha\rho\beta} \mathbf{D}^\beta z] \\ &\quad + 8M^2 z \mathbf{D}_\alpha z (\mathbf{D}_\rho z \mathbf{D}^\rho z - \mathbf{D}_\rho y \mathbf{D}^\rho y) + 2z \mathbf{D}_\alpha z + 8M^2 (y \mathbf{D}_\alpha z + z \mathbf{D}_\alpha y) \mathbf{D}_\rho y \mathbf{D}^\rho z. \end{aligned}$$

Recall that we are looking to prove (3.20) at points p with $r(p) \leq \bar{\varepsilon}^{-1/40}$. In view of (3.2) and (3.3), at such points we have

$$16M^2 (y^2 + z^2) \mathbf{D}^\beta z P^2 \mathbf{T}^\rho \mathbf{T}^\nu S S_{\nu\alpha\rho\beta} = O_1(\bar{\varepsilon}),$$

where, for simplicity of notation, in this lemma we let $O_1(\bar{\varepsilon})$ denote any quantity bounded by $\tilde{C}\bar{\varepsilon}^{1/20}$. According to (3.7) and (3.18) we also have,

$$|\mathbf{D}_\rho y \mathbf{D}^\rho z| + \left| \mathbf{D}_\rho z \mathbf{D}^\rho z - \mathbf{D}_\rho y \mathbf{D}^\rho y + \frac{1}{4M^2} \left(1 - \frac{y}{y^2 + z^2}\right) \right| \leq \tilde{C}\bar{\varepsilon}^{1/5}.$$

Thus, using again (3.2),

$$8M^2 z \mathbf{D}_\alpha z (\mathbf{D}_\rho z \mathbf{D}^\rho z - \mathbf{D}_\rho y \mathbf{D}^\rho y) + 2z \mathbf{D}_\alpha z = \frac{2yz \mathbf{D}_\alpha z}{y^2 + z^2} + O_1(\bar{\varepsilon}).$$

Consequently,

$$\mathbf{D}_\alpha H = -16M^2 (y^2 + z^2) \Im[P^2 F_\alpha^\rho \mathcal{F}_{\beta\rho} \mathbf{D}^\beta z] + \frac{2yz \mathbf{D}_\alpha z}{y^2 + z^2} + O_1(\bar{\varepsilon}).$$

For (3.20) it only remains to check that,

$$-16M^2 (y^2 + z^2) \Im[P^2 F_\alpha^\rho \mathcal{F}_{\beta\rho} \mathbf{D}^\beta z] + \frac{2yz \mathbf{D}_\alpha z}{y^2 + z^2} = O_1(\bar{\varepsilon}). \quad (3.25)$$

We prove this in the null frame $e_{(1)}, e_{(2)}, e_{(3)}, e_{(4)}$, see (3.11). Recalling (3.13) and (3.16) we easily see that both terms on the left are bounded by $\widetilde{C}\bar{\varepsilon}^{1/20}$ for $\alpha = 3, 4$. For $\alpha = 1$, using (3.13) and (3.7),

$$\begin{aligned} -16M^2(y^2 + z^2)\Im[P^2 F_{(1)}^{(\rho)} \mathcal{F}_{(\beta)(\rho)} \mathbf{D}^{(\beta)} z] &= -16M^2(y^2 + z^2)\Im[P^2 F_{(1)(2)} \mathcal{F}_{(1)(2)} \mathbf{D}_{(1)} z] \\ &= -16M^2(y^2 + z^2)\mathbf{D}_{(1)} z \Im\left[P^2 \frac{i}{4MP^2} \frac{2yz}{4M(y^2 + z^2)^2}\right] + O_1(\bar{\varepsilon}). \end{aligned}$$

The approximate identity (3.25) follows for $\alpha = 1$. The proof of (3.25) for $\alpha = 2$ is similar, which completes the proof of the lemma. \square

3.2. Conclusions. It follows from (3.18) and Lemma 3.2, that

$$\mathbf{D}_\beta z \mathbf{D}^\beta z = \frac{B - z^2}{4M^2(y^2 + z^2)} + O(\bar{\varepsilon}), \quad \mathbf{D}_\beta y \mathbf{D}^\beta y = \frac{y^2 - y + B}{4M^2(y^2 + z^2)} + O(\bar{\varepsilon}) \quad (3.26)$$

in $\Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{r_0}]$, where $O(\bar{\varepsilon})$ denotes functions on $\Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{r_0}]$ dominated by $\widetilde{C} \min(r^{-1}, \bar{\varepsilon}^{1/40})$. Using (3.15) we deduce that $\mathbf{D}^\beta y \mathbf{D}_\beta y = \frac{1}{2M^2}(\mathbf{T}^\alpha l_\alpha)(\mathbf{T}^\beta l_\beta) + O(\bar{\varepsilon})$. Hence,

$$(\mathbf{T}^\alpha l_\alpha)(\mathbf{T}^\beta l_\beta) = \frac{y^2 - y + B}{2(y^2 + z^2)} + O(\bar{\varepsilon}) \quad \text{in } \Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{r_0}]. \quad (3.27)$$

We prove now that the value of r_0 in (3.1) can be taken to be equal to 1. In view of the definition of r_0 , it suffices to prove the following lemma:

Lemma 3.3. *Assuming \bar{R} is chosen sufficiently large, we have*

$$|1 - \sigma| \geq 2\bar{R}^{-2} \quad \text{on } \Sigma_{r_0} \setminus \Sigma_{\bar{R}}.$$

Proof of Lemma 3.3. The conclusion of the lemma is equivalent to

$$|P| \leq \bar{R}^2/2 \quad \text{on } \Sigma_{r_0} \setminus \Sigma_{\bar{R}}. \quad (3.28)$$

To prove this, we recall that we still have the flexibility to fix \bar{R} sufficiently large depending on \bar{A} . In view of (2.23), for (3.28) it suffices to prove that

$$|\partial_\alpha P| \leq C(\bar{A}) \quad \text{on } \Sigma_{r_0}, \quad (3.29)$$

for $\alpha = 1, 2, 3$ and some constant $C(\bar{A})$ that depends only on \bar{A} . The bound (3.29) follows from (2.22) and (2.23) at points p for which $r(p) \geq R(\bar{A})$. Since $P = (1 - \sigma)^{-1}$ and $|1 - \sigma| \geq |\Re(1 - \sigma)| = |1 + \mathbf{T}^\alpha \mathbf{T}_\alpha|$, the bound (3.29) also follows at points p for which $r(p) \leq R(\bar{A})$ and $\mathbf{g}_p(\mathbf{T}, \mathbf{T}) \notin [-3/2, -1/2]$.

It remains to prove the bound (3.29) at points $p \in \Sigma_{r_0}$ for which $r(p) \leq R(\bar{A})$ and $\mathbf{g}_p(\mathbf{T}, \mathbf{T}) \in [-3/2, -1/2]$. Since $|1 - \sigma| \leq C(\bar{A})$ on Σ_1 , we have $|y| + |z| \geq C(\bar{A})^{-1}$ on Σ_1 . It follows from (3.26) that

$$|\mathbf{D}_\beta z \mathbf{D}^\beta z| + |\mathbf{D}_\beta y \mathbf{D}^\beta y| \leq C(\bar{A}) \quad \text{on } \Sigma_{r_0}. \quad (3.30)$$

In addition, $\mathbf{T}(\sigma) = 0$ therefore $\mathbf{T}^\alpha \mathbf{D}_\alpha z = \mathbf{T}^\alpha \mathbf{D}_\alpha y = 0$. Since $\mathbf{g}_p(\mathbf{T}, \mathbf{T}) \in [-3/2, -1/2]$ it follows that \mathbf{T}_p is timelike, thus the vectors $Y^\alpha = \mathbf{D}^\alpha y$ and $Z^\alpha = \mathbf{D}^\alpha z$ are spacelike at

the point p . The elliptic bounds (2.1) show, in fact, that $\sum_{\beta=1}^3 |\partial_\alpha y|^2 \leq C(\bar{A}) |\mathbf{D}_\beta y \mathbf{D}^\beta y|$ and $\sum_{\beta=1}^3 |\partial_\alpha z|^2 \leq C(\bar{A}) |\mathbf{D}_\beta z \mathbf{D}^\beta z|$, so (3.29) follows from (3.30). \square

We summarize the main conclusions of our analysis so far in the following proposition:

Proposition 3.4. *There is a constant $\tilde{C} = \tilde{C}(\bar{A})$ sufficiently large such that*

$$|1 - \sigma| \geq (\tilde{C}r)^{-1} \quad \text{on } \Sigma_{1-\bar{\varepsilon}},$$

provided that $\bar{\varepsilon}$ is sufficiently small (depending on \bar{A}). Therefore the frame $e_{(\alpha)}$, $\alpha = 1, \dots, 4$, the Mars–Simon tensor SS , and the functions P, y, z, G_1 are well defined in $\Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{1-\bar{\varepsilon}}]$. In addition, the identities and inequalities (3.3), (3.7), (3.12), (3.13), (3.15), (3.16), (3.18), (3.22), (3.26), (3.27) hold in $\Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{1-\bar{\varepsilon}}]$.

In view of the assumption **GR** on the orbits of **T**, it follows that the functions $y = \Re[(1 - \sigma)^{-1}]$ and $z = \Im[(1 - \sigma)^{-1}]$ are well defined smooth functions on **E**.

4. PROPERTIES OF THE FUNCTION y

Our next goal is to understand the behaviour of the function y defined in (3.9) on Σ_1 . Most of our analysis in the next section depends on having sufficiently good information on y , both in a small neighborhood of the bifurcation sphere S_0 and away from this small neighborhood.⁹ In this section we use the notation \tilde{C} to denote various constants in $[1, \infty)$ that may depend only on the main constant \bar{A} . We assume implicitly that $\bar{\varepsilon}^{-1}$ is sufficiently large compared to all such constants \tilde{C} .

4.1. Control of y in a neighborhood of S_0 . We analyze first the function of y in a neighborhood of the bifurcation sphere S_0 .

Lemma 4.1. *On the bifurcation sphere S_0 ,*

$$|y - (1 + \sqrt{1 - 4B})/2| + \sum_{\alpha=0}^3 |\partial_\alpha y| \leq \tilde{C} \bar{\varepsilon}^{1/40}. \quad (4.1)$$

Moreover, there are constants $r_1 = r_1(\bar{A}) > 1$ and $\tilde{C}_1 = \tilde{C}_1(\bar{A}) \gg 1$ such that

$$\tilde{C}_1(r-1)^2 + \tilde{C}_1 \bar{\varepsilon}^{1/40} \geq y - (1 + \sqrt{1 - 4B})/2 \geq \tilde{C}_1^{-1}(r-1)^2 - \tilde{C}_1 \bar{\varepsilon}^{1/40} \quad \text{on } \Sigma_1 \setminus \Sigma_{r_1}. \quad (4.2)$$

Proof of Lemma 4.1. Recall the vector-fields L, \underline{L} defined in a neighborhood of S_0 in section 2. It is easy to prove, see for example [24, Section 5], that

$$\mathcal{F}_{\alpha\beta} L^\beta = \mathcal{F}(L, \underline{L}) L_\alpha \quad \text{and} \quad \mathcal{F}_{\alpha\beta} \underline{L}^\beta = \mathcal{F}(\underline{L}, L) \underline{L}_\alpha \quad \text{on } S_0.$$

Since the vectors l and \underline{l} constructed in Lemma 3.1 are the unique solutions of the systems of equations $(\mathcal{F}_{\alpha\beta} \pm f \mathbf{g}_{\alpha\beta}) V^\beta = 0$, up to rescaling and relabeling, we may assume that

⁹For comparison $y = r/(2M)$, in the Kerr space of mass M and angular momentum J , in standard Boyer–Lindquist coordinates.

$L = l$ and $\underline{L} = \underline{l}$ on S_0 . Thus, we may also assume that $e_{(1)}, e_{(2)}$ are tangent to S_0 . Since \mathbf{T} is tangent to S_0 ,

$$L(\sigma) = L^\beta \sigma_\beta = 2L^\beta \mathbf{T}^\alpha \mathcal{F}_{\alpha\beta} = 0 \quad \text{on } S_0.$$

Similarly, $\underline{L}(\sigma) = 0$ on S_0 . Using also (3.16), we conclude that

$$e_{(3)}(y) = e_{(4)}(y) = 0 \quad \text{and} \quad |e_{(1)}(y)| + |e_{(2)}(y)| \leq \tilde{C}\tilde{\varepsilon}^{1/5} \quad \text{on } S_0. \quad (4.3)$$

The inequality on the gradient of y in (4.1) follows from (4.3). For the remaining inequality we use first (3.26). It follows from (4.3) that $|\mathbf{D}_\beta y \mathbf{D}^\beta y| \leq \tilde{C}\tilde{\varepsilon}^{2/5}$ on S_0 , thus

$$|y^2 - y + B| \leq \tilde{C}\tilde{\varepsilon}^{1/40} \quad \text{on } S_0.$$

Since $B = J^2/(4M^4) \in [0, 1/4)$ (see (1.2) and (2.5)), it follows that

$$|y - (1 + \sqrt{1 - 4B})/2| \leq \tilde{C}\tilde{\varepsilon}^{1/40} \quad \text{on } S_0 \quad \text{or} \quad |y - (1 - \sqrt{1 - 4B})/2| \leq \tilde{C}\tilde{\varepsilon}^{1/40} \quad \text{on } S_0. \quad (4.4)$$

To eliminate the second alternative we start by deriving a wave equation for y . Since $\mathbf{D}^\mu \mathbf{D}_\mu \sigma = -\mathcal{F}^2$, $\mathbf{D}^\mu \sigma \mathbf{D}_\mu \sigma = -\mathcal{F}^2 \mathfrak{R}\sigma$ (see (2.15)), and $-\mathcal{F}^2 = (1 - \sigma)^4(1 + G_1)^2/(4M^2)$ we derive

$$\begin{aligned} \mathbf{D}^\mu \mathbf{D}_\mu P &= (1 - \sigma)^{-2} \mathbf{D}^\mu \mathbf{D}_\mu \sigma + 2(1 - \sigma)^{-3} \mathbf{D}^\mu \sigma \mathbf{D}_\mu \sigma \\ &= \frac{(1 + G_1)^2}{4M^2} (1 - \sigma)(1 + \bar{\sigma}) = \frac{2\bar{P} - 1}{4M^2 P \bar{P}} (1 + G_1)^2. \end{aligned}$$

Thus, using (3.7)

$$\mathbf{D}^\mu \mathbf{D}_\mu y = \frac{2y - 1}{4M^2(y^2 + z^2)} + E, \quad |E| \leq \tilde{C}\tilde{\varepsilon}^{1/5}, \quad \text{on } \Sigma_{1-\tilde{\varepsilon}}. \quad (4.5)$$

We now compare y with a function y' which coincides with y on \mathcal{H}^+ and verifies $\underline{L}(y) = 0$. We use the notation in section 2. For $\varepsilon_1 = \varepsilon_1(\bar{A}) \in (0, c_0]$ sufficiently small we define the function

$$y' : \mathcal{O}_{\varepsilon_1} \rightarrow \mathbb{R}, \quad y' = y \quad \text{on } \mathcal{H}^+ \cap \mathcal{O}_{\varepsilon_1}, \quad \underline{L}(y') = 0 \quad \text{in } \mathcal{O}_{\varepsilon_1}. \quad (4.6)$$

The functions y and y' are smooth on $\mathcal{O}_{\varepsilon_1}$, and, using (4.3) and the definition of y'

$$y - y' = 0 \quad \text{on } (\mathcal{H}^+ \cup \mathcal{H}^-) \cap \mathcal{O}_{\varepsilon_1}. \quad (4.7)$$

In addition, using again (4.3), we infer that $|e_{(\alpha)}(y')| \leq \tilde{C}\tilde{\varepsilon}^{1/5}$ on S_0 , for all $\alpha = 1, 2, 3, 4$. Using (3.15) $e_{(a)}(y') = (2M)^{-1} \mathfrak{S} G_1 \in_{(\alpha)(a)(\mu)(\nu)} \mathbf{T}^{\alpha\mu} \underline{l}^\nu$ on S_0 , $a = 1, 2$. It follows from (3.7) and the inequality $|e_{(\alpha)}(y')| \leq \tilde{C}\tilde{\varepsilon}^{1/5}$ that $|\mathbf{D}_{(a)} \mathbf{D}_{(a)} y'| \leq \tilde{C}\tilde{\varepsilon}$ on S_0 , $a = 1, 2$. Using $\underline{L}(y') = 0$ and $|e_{(\alpha)}(y')| \leq \tilde{C}\tilde{\varepsilon}^{1/5}$, we have $|\mathbf{D}_{(3)} \mathbf{D}_{(4)} y'| + |\mathbf{D}_{(4)} \mathbf{D}_{(3)} y'| \leq \tilde{C}\tilde{\varepsilon}$ on S_0 . Therefore,

$$|\square_{\mathbf{g}} y'| \leq \tilde{C}\tilde{\varepsilon}^{1/5} \quad \text{on } S_0. \quad (4.8)$$

In view of (4.7), there is $\varepsilon_2 = \varepsilon_2(\bar{A}) \in (0, \varepsilon_1)$ such that $y - y' = u \underline{u} f$ in $\mathcal{O}_{\varepsilon_2}$, where $f : \mathcal{O}_{\varepsilon_2} \rightarrow \mathbb{R}$ is smooth. Since $u = \underline{u} = 0$ and $2\mathbf{D}^\alpha u \mathbf{D}_\alpha \underline{u} = -2$ on S_0 , it follows from (4.5)

and (4.8) that

$$f = -(1/2)\mathbf{D}^\alpha \mathbf{D}_\alpha(y - y') = \frac{1 - 2y}{8M^2(y^2 + z^2)} + E', \quad |E'| \leq \tilde{C}\bar{\varepsilon}^{1/5}, \quad \text{on } S_0. \quad (4.9)$$

To summarize, $y = y' + \underline{u}f$ in $\mathcal{O}_{\varepsilon_2}$, where f satisfies (4.9) on S_0 .

We eliminate now the second alternative in (4.4). The main point is that if y is close to $(1 - \sqrt{1 - 4B})/2 < 1/2$ on S_0 then f is strictly positive on S_0 (see (4.9)). In quantitative terms, there is $\varepsilon_3 = \varepsilon_3(\bar{A}) \in (0, \varepsilon_2)$ such that $f \geq \tilde{C}^{-1}$ in $\mathcal{O}_{\varepsilon_3}$. Since $\underline{u} \leq 0$ on $\Sigma_1 \cap \mathcal{O}_{\varepsilon_3}$ and $y' \leq (1 - \sqrt{1 - 4B})/2 + \tilde{C}\bar{\varepsilon}^{1/40}$ on $\mathcal{O}_{\varepsilon_3}$ (using the second alternative in (4.4) and the construction of y'), it follows that

$$y \leq (1 - \sqrt{1 - 4B})/2 - \tilde{C}^{-1}|\underline{u}| + \tilde{C}\bar{\varepsilon}^{1/40} \quad \text{on } \Sigma_1 \cap \mathcal{O}_{\varepsilon_3}.$$

In particular, using (2.12), $y \leq (1 - \sqrt{1 - 4B})/2 - \tilde{C}^{-1}$ at some point in Σ_1 (provided, of course, that $\bar{\varepsilon}$ is sufficiently small depending on \bar{A}). Using also (2.25), it follows that function $y : \Sigma_1 \rightarrow \mathbb{R}$ attains its minimum at some point $p \in \Sigma_1$, and $y(p) \leq (1 - \sqrt{1 - 4B})/2 - \tilde{C}^{-1}$. Thus $T_1(y) = T_2(y) = T_3(y) = 0$ at p (where T_0, T_1, T_2, T_3 is the orthonormal frame along Σ_1 defined in assumption **PK**), and

$$\mathbf{D}_\alpha y \mathbf{D}^\alpha y = -(T_0(y))^2 \leq 0$$

at p . This is in contradiction, however, with the identity (3.26) and the inequality $y(p) \leq (1 - \sqrt{1 - 4B})/2 - \tilde{C}^{-1}$. We conclude that the first alternative in (4.1) holds.

We prove now the second statement of the lemma: since y is close to $(1 + \sqrt{1 - 4B})/2 > 1/2$ on S_0 , it follows from (4.9) there is $\varepsilon_3 = \varepsilon_3(\bar{A}) \in (0, \varepsilon_2)$ such that $f \in [-\tilde{C}, -\tilde{C}^{-1}]$ in $\mathcal{O}_{\varepsilon_3}$. Also $|y' - (1 + \sqrt{1 - 4B})/2| \leq \tilde{C}\bar{\varepsilon}^{1/40}$ in $\mathcal{O}_{\varepsilon_3}$ and $\underline{u}/(r-1)^2 \in [-\tilde{C}, -\tilde{C}^{-1}]$ (see (2.12)). The inequalities in (4.2) follow since $y = y' + f\underline{u}$. \square

4.2. Regularity properties of the function y away from S_0 . We derive now the main properties of the level sets of the function y . Recall first the main inequality proved in Lemma 4.1: there are constants $r_1 = r_1(\bar{A}) > 1$ and $\tilde{C}_1 = \tilde{C}_1(\bar{A}) \gg 1$ such that

$$\tilde{C}_1(r-1)^2 + \tilde{C}_1\bar{\varepsilon}^{1/40} \geq y - (1 + \sqrt{1 - 4B})/2 \geq \tilde{C}_1^{-1}(r-1)^2 - \tilde{C}_1\bar{\varepsilon}^{1/40} \quad \text{on } \Sigma_1 \setminus \Sigma_{r_1}. \quad (4.10)$$

We define

$$y_0 = (1 + \sqrt{1 - 4B})/2 + \tilde{C}_2^{-1}, \quad (4.11)$$

where we fix $\tilde{C}_2 = \tilde{C}_2(\bar{A})$ a sufficiently large constant depending on the constants \tilde{C}_1, r_1 in (4.10) and $\bar{\varepsilon}$ in Proposition 5.1. As in [24, Section 8], for $R \in [y_0, \infty)$ we define

$$\begin{aligned} \mathcal{V}_R &= \{p \in \Sigma_1 : y(p) < R\}; \\ \mathcal{U}_R &= \text{the connected component of } \mathcal{V}_R \text{ whose closure in } \Sigma^0 \text{ contains } S_0. \end{aligned} \quad (4.12)$$

In view of (4.10),

$$\Sigma_1 \setminus \Sigma_{1+(4\tilde{C}_1\tilde{C}_2)^{-1/2}} \subseteq \mathcal{V}_{y_0} \cap (\Sigma_1 \setminus \Sigma_{r_1}) \subseteq \mathcal{V}_{y_0+\tilde{C}_2^{-1}} \cap (\Sigma_1 \setminus \Sigma_{r_1}) \subseteq \Sigma_1 \setminus \Sigma_{1+(4\tilde{C}_1\tilde{C}_2^{-1})^{1/2}},$$

provided that \tilde{C}_2 is sufficiently large and $\bar{\varepsilon}$ is sufficiently small. In particular, we deduce,

$$\Sigma_1 \setminus \Sigma_{1+(4\tilde{C}_1\tilde{C}_2)^{-1/2}} \subseteq \mathcal{U}_{y_0} \subseteq \mathcal{U}_{y_0+\tilde{C}_2^{-1}} \subseteq \Sigma_1 \setminus \Sigma_{1+(4\tilde{C}_1\tilde{C}_2^{-1})^{1/2}}. \quad (4.13)$$

For $p = \Phi_1(0, q) \in \Sigma_1$ and $r \leq \varepsilon_0$ we define,

$$B_r(p) = \Phi_1(\{(t, q') \in (-\varepsilon_0, \varepsilon_0) \times E_{1-\varepsilon_0} : t^2 + |q - q'|^2 < r^2\}).$$

For any set $U \subseteq \Sigma_1$ let $\delta_{\Sigma_1}(U)$ denote its boundary in Σ_1 . Clearly, if $p \in \delta_{\Sigma_1}(\mathcal{U}_R)$ for some $R \geq y_0$ then $y(p) = R$.

We define the vector-field $Y = \mathbf{D}^\alpha y \mathbf{D}_\alpha$ in $\Phi_1[(-\bar{\varepsilon}, \bar{\varepsilon}) \times E_{1-\bar{\varepsilon}}]$ and its projection Y' along the hypersurface $\Sigma_{1-\bar{\varepsilon}}$,

$$Y' = Y + \mathbf{g}(Y, T_0)T_0 = \sum_{\alpha=1}^3 (Y')^\alpha \partial_\alpha. \quad (4.14)$$

The vector-field Y' is smooth, tangent to the hypersurface $\Sigma_{1-\bar{\varepsilon}}$, and

$$\sum_{\alpha=1}^3 |(Y')^\alpha| \leq \tilde{C} \delta_0^{-1} \quad \text{on } \Sigma_{1-\bar{\varepsilon}}.$$

In addition,

$$Y'(y) = \mathbf{g}(Y', Y) = \mathbf{g}(Y, Y) + \mathbf{g}(Y, T_0)^2 \geq \mathbf{g}(Y, Y) = \mathbf{D}_\alpha y \mathbf{D}^\alpha y. \quad (4.15)$$

In particular, if $p \in \delta_{\Sigma_1}(\mathcal{U}_R)$ for some $R \geq y_0$ then $y(p) = R$ thus, using (3.26), $Y'(y)(p) \geq \tilde{C}^{-1}$. Therefore if $p \in \delta_{\Sigma_1}(\mathcal{U}_R)$ then

$$\{x \in B_\delta(p) \cap \Sigma_1 : y(x) < R\} = B_\delta(p) \cap \mathcal{U}_R, \quad (4.16)$$

for any $\delta \leq \delta_1 = \delta_1(\bar{A}) > 0$.

We prove now that the regions \mathcal{U}_R , $R \geq y_0$, increase in a controlled way.

Lemma 4.2. *There is $\delta_2 = \delta_2(\bar{A}) > \varepsilon \in (0, \delta_1)$ such that, for any $\delta \leq \delta_2$ and $R \in [y_0, \infty)$,*

$$\cup_{p \in \mathcal{U}_R} (B_{\delta^3}(p) \cap \Sigma_1) \subseteq \mathcal{U}_{R+\delta^2} \subseteq \cup_{p \in \mathcal{U}_R} (B_\delta(p) \cap \Sigma_1). \quad (4.17)$$

In addition

$$\cup_{R \geq y_0} \mathcal{U}_R = \Sigma_1 \quad (4.18)$$

and

$$\mathcal{U}_R = \mathcal{V}_R \quad \text{for any } R \geq y_0. \quad (4.19)$$

Proof of Lemma 4.2. The first inclusion in (4.17) is clear: since y is a smooth function in a neighborhood of $\bar{\Sigma}_1$ (see Proposition 3.4), it follows that $y(q) < R + \delta^2$ for any $p \in \mathcal{U}_R$ and $q \in B_{\delta^3}(p) \cap \Sigma_1$, provided that δ is sufficiently small.

To prove the second inclusion, it suffices to prove that

$$\mathcal{U}_{R+\delta^2} \subseteq \mathcal{U}_R \cup [\cup_{p \in \delta_{\Sigma_1}(\mathcal{U}_R)} (B_{\delta/4}(p) \cap \Sigma_1)], \quad (4.20)$$

for δ sufficiently small, $R \geq y_0$. Assume, for contradiction, that q is a point in $\mathcal{U}_{R+\delta^2}$ which does not belong to the open set in the right-hand side of (4.20). Let $\gamma : [0, 1] \rightarrow \mathcal{U}_{R+\delta^2} \cup S_0$

be a continuous curve such that $\gamma(0) \in S_0$ and $\gamma(1) = q$ (see definition (4.12)). Let $q' = \gamma(t')$, $t' \in (0, 1]$, denote the first point on this curve which does not belong to the open set in the right-hand side of (4.20). Clearly, q' does not belong to the closure of \mathcal{U}_R in Σ_1 , thus q' belongs to the closure of the set $\cup_{p \in \delta_{\Sigma_1}(\mathcal{U}_R)} (B_{\delta/4}(p) \cap \Sigma_1)$ in Σ_1 . Since $\delta_{\Sigma_1}(\mathcal{U}_R)$ is a compact set (see (2.25) and (4.13)), it follows that

$$q' \in B_{\delta/2}(p_0) \cap \Sigma_1 \quad \text{for some } p_0 \in \delta_{\Sigma_1}(\mathcal{U}_R). \quad (4.21)$$

For $p \in \Sigma_{1+(4\tilde{C}_1\tilde{C}_2)^{-1/2}}$ and $|t| \leq \delta'$, $\delta' > 0$ sufficiently small, let $\gamma_p(t) \subseteq \Sigma_1$ denote the integral curves of the vector-field Y' defined in (4.14), starting at p . Using (4.15), the fact that $y(p_0) = R \geq y_0$, and (3.26), it follows that

$$Y'(y) \geq \tilde{C}^{-1} \quad \text{in } B_\delta(p_0) \cap \Sigma_1, \quad (4.22)$$

provided that δ is sufficiently small. With $q' \in B_{\delta/2}(p_0)$ being the point constructed earlier, we look at the curve $\gamma_{q'}(t)$, $t \in [-\delta^{3/2}, \delta^{3/2}]$. Clearly, this curve is included in $B_\delta(p_0) \cap \Sigma_1$, assuming δ sufficiently small. Using (4.22) and the fact that $y(q') < R + \delta^2$ (since $q' \in \mathcal{U}_{R+\delta^2}$), we derive that there is a point q'' on the curve $\gamma_{q'}(t)$, $t \in [-\delta^{3/2}, \delta^{3/2}]$, such that $y(q'') < R$. It follows from (4.16) that $q'' \in \mathcal{U}_R$. Since $q' \notin \mathcal{U}_R$ (by construction), there is a point $q''' = \gamma_{q'}(t''')$, $t''' \in [-\delta^{3/2}, \delta^{3/2}]$, such that $q''' \in \delta_{\Sigma_1}(\mathcal{U}_R)$. It follows that $q' \in B_{\delta/8}(q''')$, in contradiction with the fact that q' does not belong to the set in the right-hand side of (4.20). This completes the proof of (4.20).

The completeness property (4.18) follows easily from the asymptotic formula (2.25) and the fact that y is a smooth function on Σ_1 .

To prove (4.19) we notice that, in view of (4.13), it suffices to prove that $\mathcal{V}_R \cap \Sigma_{1+(4\tilde{C}_1\tilde{C}_2)^{-1/2}} \subseteq \mathcal{U}_R$, for any $R \geq y_0$. Assume, for contradiction, that

$$\text{there is } R_0 > y_0 \text{ and } q \in \Sigma_{1+(4\tilde{C}_1\tilde{C}_2)^{-1/2}} \text{ such that } y(q) < R_0 \text{ and } q \notin \mathcal{U}_{R_0}. \quad (4.23)$$

Let $I = \{R \in [R_0, \infty) : q \notin \mathcal{U}_R\}$. Since I is bounded, due to (4.18), we can take R' its least upper bound. We analyze two possibilities: $q \in \mathcal{U}_{R'}$ and $q \notin \mathcal{U}_{R'}$.

If $q \in \mathcal{U}_{R'}$ then, using (4.23), $R' > R_0$. For $\delta > 0$ sufficiently small (depending on $R' - R_0$ and \bar{A}), it follows from (4.17) that there is $R'' = R' - \delta^2 \geq R_0 + \delta^{1/2}$ and a point $q' \in \mathcal{U}_{R''}$ such that $|q - q'| < \delta$. However, $y(q) < R_0$, see (4.23), thus $y(x) < R_0 + \delta^{1/2} \leq R''$ for any $x \in B_\delta(q)$. Since $B_\delta(q) \cap \mathcal{U}_{R''} \neq \emptyset$, it follows that $q \in \mathcal{U}_{R''}$, in contradiction with the definition of R' .

Finally, assume that $q \notin \mathcal{U}_{R'}$. Then $q \notin \delta_{\Sigma_1}(\mathcal{U}_{R'})$, in view of (4.16) and (4.23). For δ sufficiently small (smaller than the distance between q and the compact set $\delta_{\Sigma_1}(\mathcal{U}_{R'})$), it follows from (4.20) that $q \notin \mathcal{U}_{R'+\delta^2}$. This is in contradiction with the definition of R' , which completes the proof of (4.19). \square

4.3. T-conditional pseudo-convexity. In this subsection we prove a **T**-conditional pseudo-convexity property of the function y away from the bifurcation sphere S_0 . This pseudo-convexity property, which was first observed in [25] in the case of the Kerr spaces and used in [24], plays a key role in the Carleman estimates and the uniqueness arguments

in the next section. We remark that the main condition for pseudo-convexity is the assumption (4.24) below.

Since $\mathcal{U}_{y_0} = \{p \in \Sigma_1 : y(p) < y_0\}$, see (4.19) and the definition (4.12), it follows from (4.13) that $y \geq (1 + \sqrt{1 - 4B})/2 + \tilde{C}_2^{-1}$ in $\Sigma_{1+(4\tilde{C}_1\tilde{C}_2^{-1})^{1/2}}$. Using also (4.10), it follows that

$$y \geq (1 + \sqrt{1 - 4B})/2 + \tilde{C}_2^{-2} \quad \text{in } \Sigma_{1+(8\tilde{C}_1\tilde{C}_2)^{-1/2}}.$$

Lemma 4.3. *Assume $p \in \Sigma_{1+(8\tilde{C}_1\tilde{C}_2)^{-1/2}}$, thus*

$$y(p) \geq (1 + \sqrt{1 - 4B})/2 + \tilde{C}_2^{-2}. \quad (4.24)$$

There there is a constant $c_2 = c_2(\bar{A}) > 0$ and $\mu = \mu(p) \in \mathbb{R}$ such that

$$X^\alpha X^\beta (\mu \mathbf{g}_{\alpha\beta}(p) - \mathbf{D}_\alpha \mathbf{D}_\beta y(p)) \geq c_2 |X|^2 \quad (4.25)$$

for any real vector X with the property that

$$|X^\alpha \mathbf{T}_\alpha(p)| + |X^\alpha \mathbf{D}_\alpha y(p)| \leq c_2 |X|. \quad (4.26)$$

Proof of Lemma 4.3. The bound (4.25) follows easily with $\mu = 1$ if $r(p) \geq \tilde{C}$ is sufficiently large (see (2.3) and (2.25)). Assume that $r(p) \leq \tilde{C}$. We shall make use of the null frame $e_{(\alpha)}$ defined in section 3.

Using (3.22), we write

$$\begin{aligned} X^\alpha X^\beta \mathbf{D}_\alpha \mathbf{D}_\beta y &= X^\alpha X^\beta \Re[-P^{-1} \mathbf{D}_\alpha P \mathbf{D}_\beta P] + \mathbf{g}(X, X) \Re[P^{-1} (\mathbf{D}_\rho P \mathbf{D}^\rho P)] \\ &\quad - 2X^\alpha X^\beta \Re[P^2 F_\alpha{}^\rho \mathcal{F}_{\beta\rho}] - (X^\alpha \mathbf{T}_\alpha)^2 \Re(P^3 \mathcal{F}^2) + |X|^2 O(\bar{\varepsilon}), \end{aligned}$$

where, in this proof, $O(\bar{\varepsilon})$ denotes quantities bounded by $\tilde{C}\bar{\varepsilon}^{1/40}$. Since $X(y) = |X|O(c_2)$,

$$X^\alpha X^\beta \Re[-P^{-1} \mathbf{D}_\alpha P \mathbf{D}_\beta P] = \frac{y}{y^2 + z^2} X(z)^2 + |X|^2 O(c_2), \quad (4.27)$$

where, in this proof, $O(c_2)$ denotes quantities bounded by $\tilde{C}c_2$. Using (3.17) and (3.7),

$$\Re[P^{-1} (\mathbf{D}_\rho P \mathbf{D}^\rho P)] = \frac{y}{y^2 + z^2} \frac{1}{4M^2} \left(1 - \frac{y}{y^2 + z^2}\right) + O(\bar{\varepsilon}),$$

thus

$$X^\alpha X^\beta \Re[P^{-1} (\mathbf{D}_\rho P \mathbf{D}^\rho P)] \mathbf{g}_{\alpha\beta} = \mathbf{g}(X, X) \frac{y(y^2 + z^2 - y)}{4M^2(y^2 + z^2)^2} + |X|^2 O(\bar{\varepsilon}). \quad (4.28)$$

To calculate $X^\alpha X^\beta \Re[P^2 F_\alpha{}^\rho \mathcal{F}_{\beta\rho}]$ we recall, see (3.13) that all components of \mathcal{F} vanish, with the exception of $\mathcal{F}_{34} = -\mathcal{F}_{43} = -\frac{1}{4MP^2} + O(\bar{\varepsilon})$ and $\mathcal{F}_{12} = -\mathcal{F}_{21} = \frac{i}{4MP^2} + O(\bar{\varepsilon})$, $a, b = 1, 2$. Since $F = \Re(\mathcal{F})$ we also have,

$$F_{34} = -F_{43} = -(4M)^{-1} \Re[P^{-2}] + O(\bar{\varepsilon}), \quad F_{12} = -F_{21} = -(4M)^{-1} \Im[P^{-2}] + O(\bar{\varepsilon}).$$

Therefore,

$$\begin{aligned} X^\alpha X^\beta F_\alpha{}^\rho \mathcal{F}_{\beta\rho} &= 2X^3 X^4 F_{34} \mathcal{F}_{34} + ((X^1)^2 + (X^2)^2) F_{12} \mathcal{F}_{12} + |X|^2 O(\bar{\varepsilon}) \\ &= \frac{1}{16M^2 P^2} \left(2X^3 X^4 \Re[P^{-2}] - i((X^1)^2 + (X^2)^2) \Im[P^{-2}] \right) + |X|^2 O(\bar{\varepsilon}). \end{aligned}$$

Thus,

$$-2X^\alpha X^\beta \Re[P^2 F_\alpha{}^\rho \mathcal{F}_{\beta\rho}] = -X^3 X^4 \frac{y^2 - z^2}{4M^2(y^2 + z^2)^2} + |X|^2 O(\bar{\varepsilon}). \quad (4.29)$$

Therefore, denoting $E(X, X) := X^\alpha X^\beta (\mu \mathbf{g}_{\alpha\beta} - \mathbf{D}_\alpha \mathbf{D}_\beta y)$, we write

$$\begin{aligned} E(X, X) &= \mathbf{g}(X, X) \left(\mu - \frac{y(y^2 + z^2 - y)}{4M^2(y^2 + z^2)^2} \right) - \frac{y}{y^2 + z^2} X(z)^2 \\ &\quad + X^3 X^4 \frac{y^2 - z^2}{4M^2(y^2 + z^2)^2} + |X|^2 O(\bar{\varepsilon}) + |X|^2 O(c_2), \end{aligned}$$

or, since $\mathbf{g}(X, X) = -2X^3 X^4 + (X^1)^2 + (X^2)^2$,

$$\begin{aligned} E(X, X) &= 2X^3 X^4 \left[\frac{y(y^2 + z^2 - y)}{4M^2(y^2 + z^2)^2} + \frac{y^2 - z^2}{8M^2(y^2 + z^2)^2} - \mu \right] - \frac{y}{y^2 + z^2} X(z)^2 \\ &\quad + ((X^1)^2 + (X^2)^2) \left(\mu - \frac{y(y^2 + z^2 - y)}{4M^2(y^2 + z^2)^2} \right) + |X|^2 O(\bar{\varepsilon}) + |X|^2 O(c_2) \\ &= 2X^3 X^4 \left(\frac{2y - 1}{8M^2(y^2 + z^2)} - \mu \right) - \frac{y}{y^2 + z^2} X(z)^2 \\ &\quad + ((X^1)^2 + (X^2)^2) \left(\mu - \frac{y(y^2 + z^2 - y)}{4M^2(y^2 + z^2)^2} \right) + |X|^2 O(\bar{\varepsilon}) + |X|^2 O(c_2). \end{aligned}$$

We now make use of our main identity (3.19) as well as (3.16), and derive,

$$(\mathbf{D}_1 z)^2 + (\mathbf{D}_2 z)^2 = \mathbf{D}_\beta z \mathbf{D}^\beta z + O(\bar{\varepsilon}) = \frac{B - z^2}{4M^2(y^2 + z^2)} + O_1(\bar{\varepsilon}).$$

Thus, using also $\mathbf{D}_3 z = O(\bar{\varepsilon})$ and $\mathbf{D}_4 z = O(\bar{\varepsilon})$, by Cauchy-Schwartz,

$$\begin{aligned} X(z)^2 &\leq ((X^1)^2 + (X^2)^2) ((\mathbf{D}_1 z)^2 + (\mathbf{D}_2 z)^2) + O(\bar{\varepsilon}) \\ &\leq ((X^1)^2 + (X^2)^2) \frac{B - z^2}{4M^2(y^2 + z^2)} + O(\bar{\varepsilon}). \end{aligned}$$

We deduce,

$$\begin{aligned} E(X, X) &\geq |X|^2 O(\bar{\varepsilon}) + |X|^2 O(c_2) + 2X^3 X^4 \left[\frac{2y - 1}{8M^2(y^2 + z^2)} - \mu \right] \\ &\quad + ((X^1)^2 + (X^2)^2) \left[\mu - \frac{y(y^2 + z^2 - y)}{4M^2(y^2 + z^2)^2} - \frac{y(B - z^2)}{4M^2(y^2 + z^2)^2} \right], \end{aligned}$$

or,

$$\begin{aligned}
 E(X, X) \geq & |X|^2 O(\bar{\varepsilon}) + |X|^2 O(c_2) + 2X^3 X^4 \left[\frac{2y-1}{8M^2(y^2+z^2)} - \mu \right] \\
 & + ((X^1)^2 + (X^2)^2) \left[\mu - \frac{y(y^2-y+B)}{4M^2(y^2+z^2)^2} \right].
 \end{aligned} \tag{4.30}$$

Since $X(y) = X^\alpha \mathbf{D}_\alpha y = |X|O(c_2)$, it follows from (3.15) that $X^4(\mathbf{T}^\alpha l_\alpha) - X^3(\mathbf{T}^\alpha \underline{l}_\alpha) = |X|O(\bar{\varepsilon}) + |X|O(c_2)$. On the other hand, according to (3.27),

$$(\mathbf{T}^\alpha l_\alpha)(\mathbf{T}^\beta \underline{l}_\beta) = \frac{y^2 - y + B}{2(y^2 + z^2)} + O(\bar{\varepsilon})$$

and therefore, in view of (4.24) and $B < 1/4$, $(\mathbf{T}^\alpha l_\alpha)(\mathbf{T}^\beta \underline{l}_\beta) \geq c' = c'(\bar{A}) > 0$ (recall $r(p) \leq \tilde{C}$). We infer that,

$$2X^3 X^4 \geq \tilde{C}^{-1}[(X^3)^2 + (X^4)^2] - \tilde{C}\bar{\varepsilon}|X| - \tilde{C}c_2|X|.$$

Thus the expression in (4.30) is bounded from below by $c_2|X|^2$ if c_2 is sufficiently small and the coefficients of $((X^1)^2 + (X^2)^2)$ and $2X^3 X^4$ are both positive, for a suitable choice of μ . This holds if and only if,

$$\frac{y(y^2 - y + B)}{4M^2(y^2 + z^2)^2} < \mu < \frac{2y - 1}{8M^2(y^2 + z^2)}.$$

Such a choice exists since,

$$\frac{2y - 1}{8M^2(y^2 + z^2)} - \frac{y(y^2 - y + B)}{4M^2(y^2 + z^2)^2} = \frac{z^2(2y - 1) + y(y - 2B)}{8M^2(y^2 + z^2)^2} \geq \tilde{C}^{-1}.$$

This last inequality holds because $B < 1/4$, $y \geq 1/2 + c_1$, and $r(p) \leq \tilde{C}$. \square

5. CONSTRUCTION OF THE HAWKING KILLING VECTOR-FIELD \mathbf{K}

In this section we construct a second Killing vector-field \mathbf{K} in $\mathbf{E} \cup \mathcal{O}_{\bar{c}}$, for some small constant $\bar{c} = \bar{c}(\bar{A}) \in (0, c_0)$. The first step, the existence of \mathbf{K} in a neighborhood of S_0 , was proved by the authors in [2]. We summarize first the main results in [2], see Theorem 1.1, Proposition 4.5, Proposition 5.1, and Proposition 5.2, in a suitable quantitative form.

Proposition 5.1. *There is a neighborhood \mathcal{O}' of the bifurcation sphere S_0 , a constant $\bar{c} = \bar{c}(\bar{A}) > 0$ such that $\mathcal{O}_{\bar{c}} \subseteq \mathcal{O}'$, and a smooth vector-field \mathbf{K} in \mathcal{O}' such that $\mathbf{K} = \underline{u}L - u\underline{L}$ on $(\mathcal{H}^+ \cup \mathcal{H}^-) \cap \mathcal{O}'$,*

$$\mathcal{L}_{\mathbf{K}}\mathbf{g} = 0, \quad [\mathbf{T}, \mathbf{K}] = 0, \quad \mathbf{K}^\mu \sigma_\mu = 0 \quad \text{in } \mathcal{O}', \tag{5.1}$$

and

$$\mathbf{g}(\mathbf{K}, \mathbf{K}) \leq -\bar{c}(r-1)^2 \quad \text{on } \Sigma_1 \cap \mathcal{O}'. \tag{5.2}$$

In addition, there is $\lambda_0 \in \mathbb{R}$ such that the vector-field

$$\mathbf{Z} = \mathbf{T} + \lambda_0 \mathbf{K}$$

has complete periodic orbits in \mathcal{O}' .

The inequality (5.2) follows from [2, Proposition 4.5] and (2.12). In this section we extend \mathbf{K} to the exterior region \mathbf{E} . The main result is the following:

Theorem 5.2. *The vector-field \mathbf{K} constructed in $\mathcal{O}_{\bar{\epsilon}}$ can be extended to a smooth vector-field in the exterior region \mathbf{E} such that*

$$\mathcal{L}_{\mathbf{K}}\mathbf{g} = 0, \quad [\mathbf{T}, \mathbf{K}] = 0, \quad \mathbf{K}^\mu \sigma_\mu = 0 \quad \text{in } \mathbf{E} \cup \mathcal{O}_{\bar{\epsilon}}. \quad (5.3)$$

The rest of this section is concerned with the proof of Theorem 5.2. We construct the vector-field \mathbf{K} recursively, in increasingly larger regions defined in terms of the level sets of the function y . We rely on Carleman estimates to prove, by an uniqueness argument similar to that of [2], that the extended \mathbf{K} remains Killing at every step in the process. The initial step is, of course, that given by Proposition 5.1.

Recall the definitions (4.11) and (4.12), and the identity $\mathcal{U}_R = \mathcal{V}_R$, see (4.19). Using the flow $\Psi_{t, \mathbf{T}}$ associated to \mathbf{T} and the assumption \mathbf{GR} on the orbits of \mathbf{T} , we define the connected open space-time regions,

$$\mathbf{E}_R = \{p \in \mathbf{E} : y(p) < R\} = \cup_{t \in \mathbb{R}} \Psi_{t, \mathbf{T}}(\mathcal{U}_R) \subseteq \mathbf{E}, \quad R \geq y_0. \quad (5.4)$$

Clearly, $\mathbf{E} = \cup_{R \geq y_0} \mathbf{E}_R$. The main step in the proof of the theorem is the following:

Main Claim: For any $R \geq y_0$ there is a smooth vector-field \mathbf{K} defined in the connected open set \mathbf{E}_R , which agrees with the vector-field \mathbf{K} defined in Proposition 5.1 in a neighborhood of \mathcal{U}_{y_0} in \mathbf{E} , such that

$$\mathcal{L}_{\mathbf{K}}\mathbf{g} = 0, \quad [\mathbf{T}, \mathbf{K}] = 0, \quad \mathbf{K}^\mu \sigma_\mu = 0 \quad \text{in } \mathbf{E}_R. \quad (5.5)$$

The Main Claim follows for $R = y_0$ from Proposition 5.1: we define \mathbf{K} in a small neighborhood of \mathcal{U}_{y_0} in \mathbf{E} as in Proposition 5.1 and extend it to \mathbf{E}_{y_0} by solving the ordinary differential equation $[\mathbf{T}, \mathbf{K}] = 0$ (recall that \mathbf{T} does not vanish in \mathbf{E}). The remaining identities in (5.5) hold on \mathbf{E}_{y_0} since they hold in a small neighborhood of \mathcal{U}_{y_0} in \mathbf{E} and \mathbf{T} is non-vanishing Killing vector-field.

Assume now that the Main Claim holds for some value $R_0 \geq y_0$. We would like to prove the Main Claim for some value $R = R_0 + \delta'$, for some $\delta' = \delta'(\bar{A}, \delta_0) > 0$. We will use the results and the notation in section 4.

Recall that y, z, σ are smooth well-defined functions in \mathbf{E} and $y + iz = (1 - \sigma)^{-1}$. As in the proof of Lemma 4.2 let $Y^\alpha = \mathbf{D}^\alpha y$, which is a smooth vector-field in \mathbf{E} . Using the last identity in (5.5), $\mathbf{K}^\mu Y_\mu = 0$ in \mathbf{E}_{R_0} . We compute in \mathbf{E}_{R_0}

$$[\mathbf{K}, Y]_\beta = \mathbf{K}^\alpha \mathbf{D}_\alpha Y_\beta - Y^\alpha \mathbf{D}_\alpha \mathbf{K}_\beta = \mathbf{K}^\alpha \mathbf{D}_\beta \mathbf{D}_\alpha y + \mathbf{D}^\alpha y \mathbf{D}_\beta \mathbf{K}_\alpha = \mathbf{D}_\beta (\mathbf{K}^\alpha \mathbf{D}_\alpha y) = 0.$$

Thus

$$[\mathbf{K}, Y] = 0 \quad \text{in } \mathbf{E}_{R_0}. \quad (5.6)$$

For $R \geq y_0$ and $\delta > 0$ small we define

$$\tilde{\mathcal{O}}_{\delta, R} = \cup_{p \in \delta_{\Sigma_1}(\mathcal{U}_R)} B_\delta(p).$$

Clearly, for δ sufficiently small and $R \geq y_0$

$$\mathbf{E}_R \cap \tilde{\mathcal{O}}_{\delta,R} = \{p \in \tilde{\mathcal{O}}_{\delta,R} : y(p) < R\}. \quad (5.7)$$

The vector-field \mathbf{K} is defined in $\mathbf{E}_{R_0} \cap \tilde{\mathcal{O}}_{\delta,R_0}$, by the induction hypothesis. We would like to extend it to the full open set $\tilde{\mathcal{O}}_{\delta,R_0}$ as the solution of an ordinary differential equation of the form $[\mathbf{K}, \bar{Y}] = 0$, where \bar{Y} is a suitable vector-field in $\tilde{\mathcal{O}}_{\delta,R_0}$. We summarize this construction in Lemma 5.3 below.

Lemma 5.3. *There is a constant $\delta_3 = \delta_3(\bar{A}) > 0$, a smooth vector-field $\bar{Y} = \bar{Y}^\alpha \partial_\alpha$ in $\tilde{\mathcal{O}}_{\delta_3,R_0}$, $\sum_{\alpha=0}^3 |\bar{Y}^\alpha| \leq \delta_3^{-1}$ in $\tilde{\mathcal{O}}_{\delta_3,R_0}$, and a smooth extension of the vector-field \mathbf{K} (originally defined in $\mathcal{O}_{\delta_3,R_0} \cap \mathbf{E}_{R_0}$) to $\tilde{\mathcal{O}}_{\delta_3,R_0}$ such that*

$$\mathbf{D}_{\bar{Y}}\bar{Y} = 0, \quad [\mathbf{K}, \bar{Y}] = 0, \quad \bar{Y}(y) \geq \delta_3 \quad \text{in } \tilde{\mathcal{O}}_{\delta_3,R_0}. \quad (5.8)$$

Proof of Lemma 5.3. For δ sufficiently small we define

$$S_{\delta,R_0} = \{x \in \tilde{\mathcal{O}}_{\delta,R_0} : y(x) = R_0\}.$$

Clearly, $\delta_{\Sigma_1}(\mathcal{U}_{R_0}) \subseteq S_{\delta,R_0}$. Since y is a smooth function and $\mathbf{D}^\alpha y \mathbf{D}_\alpha y \geq \tilde{C}^{-1}$ in $\tilde{\mathcal{O}}_{\delta,R_0}$, the set S_{δ,R_0} is a smooth imbedded hypersurface. We define $\bar{Y} = Y$ on S_{δ,R_0} , and extend \bar{Y} to an open set of the form $\tilde{\mathcal{O}}_{\delta',R_0}$, $\delta' \leq \delta$ by solving the geodesic equation $\mathbf{D}_{\bar{Y}}\bar{Y} = 0$.

We first show that $[\mathbf{K}, \bar{Y}] = 0$ in $\tilde{\mathcal{O}}_{\delta'',R_0} \cap \mathbf{E}_{R_0}$, $\delta'' \in (0, \delta']$. Since \mathbf{K} is tangent to S_{δ,R_0} , $\mathbf{K}(y) = 0$, and $\bar{Y} = Y$ we deduce that $[\mathbf{K}, \bar{Y}] = 0$ along S_{δ,R_0} . On the other hand, we have in $\tilde{\mathcal{O}}_{\delta',R_0} \cap \mathbf{E}_{R_0}$ (where \mathbf{K} is Killing),

$$\mathbf{D}_{\bar{Y}}(\mathcal{L}_{\mathbf{K}}\bar{Y}) = \mathcal{L}_{\mathbf{K}}(\mathbf{D}_{\bar{Y}}\bar{Y}) - \mathbf{D}_{\mathcal{L}_{\mathbf{K}}\bar{Y}}\bar{Y} = -\mathbf{D}_{\mathcal{L}_{\mathbf{K}}\bar{Y}}\bar{Y}.$$

Thus, $[\mathbf{K}, \bar{Y}] = 0$ in $\tilde{\mathcal{O}}_{\delta'',R_0} \cap \mathbf{E}_{R_0}$, $\delta'' \in (0, \delta']$. We can now extend \mathbf{K} to $\tilde{\mathcal{O}}_{\delta_3,R_0}$, $\delta_3 \leq \delta''$, by solving the ordinary differential equation $[\mathbf{K}, \bar{Y}] = 0$. This completes the proof of the lemma. \square

We prove now that the vector field \mathbf{K} is indeed a Killing vector-field (and verifies the other identities in (5.5)) in a small open set $\tilde{\mathcal{O}}_{\delta,R_0}$. An argument of this type was used in [2, Section 4]. For $|t|$ sufficiently small and $p_0 \in \delta_{\Sigma_1}(\mathcal{U}_{R_0})$ we define, in a small neighborhood of p_0 , the map $\Psi_{t,\mathbf{K}}$ obtained by flowing a parameter distance t along the integral curves of \mathbf{K} . Let

$$\mathbf{g}^t = \Psi_{t,\mathbf{K}}^*(\mathbf{g}) \quad \text{and} \quad \mathbf{T}^t = \Psi_{t,\mathbf{K}}^*(\mathbf{T}).$$

The tensor \mathbf{g}^t is a smooth Lorentz metric that satisfies the Einstein vacuum equations, and \mathbf{T}^t is a smooth Killing vector-field for \mathbf{g}^t , in a small neighborhood of p_0 and for $|t|$ sufficiently small. In addition, since \mathbf{K} is tangent to the hypersurface $\{y = R_0\}$, it follows from the induction hypothesis that $\mathbf{g}^t = \mathbf{g}$ and $\mathbf{T}^t = \mathbf{T}$ in a small neighborhood of p_0 intersected with \mathbf{E}_{R_0} . In addition, using the second identity in (5.8), with $\Psi_t = \Psi_{t,\mathbf{K}}$,

$$\frac{d}{dt}\Psi_t^*\bar{Y} = \lim_{h \rightarrow 0} \frac{\Psi_{t-h}^*\bar{Y} - \Psi_t^*\bar{Y}}{-h} = -\Psi_t^* \left(\lim_{h \rightarrow 0} \frac{\Psi_{-h}^*\bar{Y} - \Psi_0^*\bar{Y}}{-h} \right) = -\Psi_t^*(\mathcal{L}_{\mathbf{K}}\bar{Y}) = 0.$$

Thus $\Psi_t^* \bar{Y} = \bar{Y}$ and we infer that $\mathbf{D}^t_{\bar{Y}} \bar{Y} = 0$ in a small neighborhood of p_0 , for $|t|$ sufficiently small, where \mathbf{D}^t denotes the covariant derivative with respect to \mathbf{g}^t . The main step in proving the Main Claim is the following proposition:

Proposition 5.4. *Assume $p_0 \in \delta_{\Sigma_1}(\mathcal{U}_{R_0})$, \mathbf{g}' is a smooth Lorentz metric in $B_{\delta_4}(p_0)$, $\delta_4 \in (0, \delta_3]$, such that $(B_{\delta_4}(p_0), \mathbf{g}')$ is a smooth Einstein vacuum spacetime, and \mathbf{T}' is a smooth Killing vector-field for the metric \mathbf{g}' in $B_{\delta_4}(p_0)$. In addition, assume that*

$$\left\{ \begin{array}{l} \mathbf{g}' = \mathbf{g} \quad \text{and} \quad \mathbf{T}' = \mathbf{T} \quad \text{in } \mathbf{E}_{R_0} \cap B_{\delta_4}(p_0); \\ \mathbf{D}'_{\bar{Y}} \bar{Y} = 0 \quad \text{in } B_{\delta_4}(p_0), \end{array} \right.$$

where \mathbf{D}' denotes the covariant derivative induced by the metric \mathbf{g}' . Then $\mathbf{g}' = \mathbf{g}$ and $\mathbf{T}' = \mathbf{T}$ in $B_{\delta_5}(p_0)$ for some $\delta_5 \in (0, \delta_4]$.

Assuming the proposition and Lemma 5.5, which we prove below, we complete now the proof of the Main Claim. It follows from Proposition 5.4 that \mathbf{K} is a Killing vector-field in $B_{\delta_5}(p_0)$, for any $p_0 \in \delta_{\Sigma_1}(\mathcal{U}_{R_0})$. In addition, since $\Psi_{t, \mathbf{K}}^*(\mathbf{T}) = \mathbf{T}$ for $|t|$ sufficiently small, it follows that $[\mathbf{T}, \mathbf{K}] = \mathcal{L}_{\mathbf{K}} \mathbf{T} = 0$ in $B_{\delta_5}(p_0)$. Finally, in $B_{\delta_5}(p_0)$,

$$\square_{\mathbf{g}}(\mathbf{K}^\mu \sigma_\mu) = \mathbf{K}^\mu \mathbf{D}^\alpha \mathbf{D}_\alpha \sigma_\mu = \mathbf{K}^\mu \mathbf{D}_\mu (\mathbf{D}^\alpha \sigma_\alpha) = -\mathcal{L}_{\mathbf{K}}(\mathcal{F}^2) = 0,$$

(using $\square_{\mathbf{g}} \mathbf{K} = 0$, $\mathbf{D}\mathbf{K}$ is antisymmetric, $\mathbf{D}\sigma$ is symmetric, $\mathbf{D}^\alpha \sigma_\alpha = -\mathcal{F}^2$, see (2.15)), and

$$\mathbf{T}(\mathbf{K}^\mu \sigma_\mu) = \mathbf{K}(\mathbf{T}(\sigma)) = 0.$$

Since $\mathbf{K}^\mu \sigma_\mu = 0$ in $B_{\delta_5}(p_0) \cap \mathbf{E}_{R_0}$ (the induction hypothesis), it follows from Lemma 5.5 below, with $H = 0$, that $\mathbf{K}^\mu \sigma_\mu = 0$ in $B_{\delta_6}(p_0)$, $\delta_6 \in (0, \delta_5]$.

To summarize, we proved that \mathbf{K} extends to the open set $\tilde{\mathcal{O}}_{\delta_6, R_0} = \cup_{p_0 \in \delta_{\Sigma_1}(\mathcal{U}_{R_0})} B_{\delta_6}(p_0)$, $\delta_6 = \delta_6(\bar{A}, \delta_0) > 0$, as a smooth vector, and the identities in (5.5) hold in this set. Using the inclusion (4.20), it follows that \mathbf{K} is well defined and satisfies the identities (5.5) in a small neighborhood of $\mathcal{U}_{R_0 + \delta_6^2}$. Thus we can extend \mathbf{K} to the region $\mathbf{E}_{R_0 + \delta_6^2}$, by solving the ordinary differential equation $[\mathbf{T}, \mathbf{K}] = 0$. The Main Claim follows.

5.1. Proof of Proposition 5.4. We prove proposition 5.4 following the same scheme as in the proof of [2, Proposition 4.3]. We first fix some smooth frames $v_{(1)}, v_{(2)}, v_{(3)}, v_{(4)} = \bar{Y}$ and $v'_{(1)}, v'_{(2)}, v'_{(3)}, v'_{(4)} = \bar{Y}$ in a small neighborhood $B_{\delta'}(p_0)$, such that, for $a = 1, 2, 3, 4$,

$$\begin{aligned} \mathbf{D}_{\bar{Y}} v_{(a)} &= 0 \quad \text{and} \quad \mathbf{D}'_{\bar{Y}} v'_{(a)} = 0 \quad \text{in } B_{\delta'}(p_0); \\ v_{(a)} &= v'_{(a)} \quad \text{in } \mathbf{E}_{R_0} \cap B_{\delta'}(p_0). \end{aligned}$$

The idea of the proof is to derive ODE's for the differences $dv = v' - v$, $d\Gamma = \Gamma' - \Gamma$, $dT = \mathbf{T}' - \mathbf{T}$ and $dF = F' - F$, with source terms in $dR = \mathbf{R}' - \mathbf{R}$. We combine these ODE's with an equation for $\square_{\mathbf{g}}(dR)$ and equation for $\mathbf{T}(dR)$. Finally, we prove uniqueness of solutions of the resulting coupled system, see Lemma 5.5, using Carleman inequalities as in [24], [25], [1], [2].

As in the proof of [2, Proposition 4.3], we define, for $a, b, c, d = 1, \dots, 4$ and $\alpha, \beta = 0, \dots, 3$,

$$\begin{aligned}
 (d\Gamma)_{(a)(b)(c)} &= \Gamma'_{(a)(b)(c)} - \Gamma_{(a)(b)(c)} = \mathbf{g}'(v'_{(a)}, \mathbf{D}'_{v'_{(c)}} v'_{(b)}) - \mathbf{g}(v_{(a)}, \mathbf{D}_{v_{(c)}} v_{(b)}); \\
 (\partial d\Gamma)_{\alpha(a)(b)(c)} &= \partial_\alpha[(d\Gamma)_{(a)(b)(c)}]; \\
 (dR)_{(a)(b)(c)(d)} &= \mathbf{R}'(v'_{(a)}, v'_{(b)}, v'_{(c)}, v'_{(d)}) - \mathbf{R}(v_{(a)}, v_{(b)}, v_{(c)}, v_{(d)}); \\
 (\partial dR)_{\alpha(a)(b)(c)(d)} &= \partial_\alpha[(dR)_{(a)(b)(c)(d)}]; \\
 (dv)_{(a)}^\beta &= v_{(a)}^{\prime\beta} - v_{(a)}^\beta \quad \text{where } v_{(a)} = v_{(a)}^\beta \partial_\beta \text{ and } v'_{(a)} = v_{(a)}^{\prime\beta} \partial_\beta; \\
 (\partial dv)_{\alpha(a)}^\beta &= \partial_\alpha[(dv)_{(a)}^\beta].
 \end{aligned} \tag{5.9}$$

As before, the coordinate frame $\partial_0, \dots, \partial_3$ is induced by the diffeomorphism Φ_1 . Let $\mathbf{g}_{(a)(b)} = \mathbf{g}(v_{(a)}, v_{(b)})$, $\mathbf{g}'_{(a)(b)} = \mathbf{g}'(v'_{(a)}, v'_{(b)})$. The identities $\mathbf{D}_{\bar{Y}} v_{(a)} = \mathbf{D}'_{\bar{Y}} v'_{(a)} = 0$ show that $\bar{Y}(\mathbf{g}_{(a)(b)}) = \bar{Y}(\mathbf{g}'_{(a)(b)}) = 0$. Since $\mathbf{g}_{(a)(b)} = \mathbf{g}'_{(a)(b)}$ in $\mathbf{E}_{R_0} \cap B_{\delta'(p_0)}$ it follows that

$$\mathbf{g}_{(a)(b)} = \mathbf{g}'_{(a)(b)} := h_{(a)(b)} \quad \text{and} \quad \bar{Y}(h_{(a)(b)}) = 0 \quad \text{in } B_{\delta''(p_0)}, \tag{5.10}$$

for some constant $\delta'' = \delta''(\bar{A}, \delta_0) \in (0, \delta']$. Clearly, $\Gamma_{(a)(b)(4)} = \Gamma'_{(a)(b)(4)} = 0$. We use now the definition of the Riemann curvature tensor to find a system of equations for $\bar{Y}[(d\Gamma)_{(a)(b)(c)}]$. We have

$$\begin{aligned}
 \mathbf{R}_{(a)(b)(c)(d)} &= \mathbf{g}(v_{(a)}, \mathbf{D}_{v_{(c)}}(\mathbf{D}_{v_{(d)}} v_{(b)}) - \mathbf{D}_{v_{(d)}}(\mathbf{D}_{v_{(c)}} v_{(b)}) - \mathbf{D}_{[v_{(c)}, v_{(d)}]} v_{(b)}) \\
 &= \mathbf{g}(v_{(a)}, \mathbf{D}_{v_{(c)}}(\mathbf{g}^{(m)(n)} \Gamma_{(m)(b)(d)} v_{(n)})) - \mathbf{g}(v_{(a)}, \mathbf{D}_{v_{(d)}}(\mathbf{g}^{(m)(n)} \Gamma_{(m)(b)(c)} v_{(n)})) \\
 &+ \mathbf{g}^{(m)(n)} \Gamma_{(a)(b)(n)} (\Gamma_{(m)(c)(d)} - \Gamma_{(m)(d)(c)}) \\
 &= v_{(c)} (\Gamma_{(a)(b)(d)}) - v_{(d)} (\Gamma_{(a)(b)(c)}) + \mathbf{g}^{(m)(n)} \Gamma_{(a)(b)(n)} (\Gamma_{(m)(c)(d)} - \Gamma_{(m)(d)(c)}) \\
 &+ \mathbf{g}_{(a)(n)} [\Gamma_{(m)(b)(d)} v_{(c)} (\mathbf{g}^{(m)(n)}) - \Gamma_{(m)(b)(c)} v_{(d)} (\mathbf{g}^{(m)(n)})] \\
 &+ \mathbf{g}^{(m)(n)} (\Gamma_{(m)(b)(d)} \Gamma_{(a)(n)(c)} - \Gamma_{(m)(b)(c)} \Gamma_{(a)(n)(d)}).
 \end{aligned}$$

We set $d = 4$ and use $\Gamma_{(a)(b)(4)} = v_{(4)}(\mathbf{g}^{(a)(b)}) = 0$ and $\mathbf{g}^{(a)(b)} = h^{(a)(b)}$; the result is

$$\bar{Y}(\Gamma_{(a)(b)(c)}) = -h^{(m)(n)} \Gamma_{(a)(b)(n)} \Gamma_{(m)(4)(c)} - \mathbf{R}_{(a)(b)(c)(4)}.$$

Similarly,

$$\bar{Y}(\Gamma'_{(a)(b)(c)}) = -h^{(m)(n)} \Gamma'_{(a)(b)(n)} \Gamma'_{(m)(4)(c)} - \mathbf{R}'_{(a)(b)(c)(4)}.$$

We subtract these two identities to derive

$$\bar{Y}[(d\Gamma)_{(a)(b)(c)}] = {}^{(1)}F_{(a)(b)(c)}^{(d)(e)(f)} (d\Gamma)_{(d)(e)(f)} - (dR)_{(a)(b)(c)(4)} \tag{5.11}$$

for some smooth function ${}^{(1)}F$. This can be written schematically in the form

$$\bar{Y}(d\Gamma) = \mathcal{M}_\infty(d\Gamma) + \mathcal{M}_\infty(dR). \tag{5.12}$$

We will use such schematic equations for simplicity of notation¹⁰. By differentiating (5.12), we also derive

$$\bar{Y}(\partial d\Gamma) = \mathcal{M}_\infty(d\Gamma) + \mathcal{M}_\infty(\partial d\Gamma) + \mathcal{M}_\infty(dR) + \mathcal{M}_\infty(\partial dR). \quad (5.13)$$

With the notation in (5.9), since $[v_{(4)}, v_{(b)}] = -\mathbf{D}_{v_{(b)}}v_{(4)} = -\Gamma^{(c)}_{(4)(b)}v_{(c)}$, we have

$$v_{(4)}^\alpha \partial_\alpha(v_{(b)}^\beta) - v_{(b)}^\alpha \partial_\alpha(v_{(4)}^\beta) = -\Gamma_{(a)(4)(b)}v_{(c)}^\beta \mathbf{g}^{(a)(c)}.$$

Similarly,

$$v_{(4)}^\alpha \partial_\alpha(v_{(b)}'^\beta) - v_{(b)}'^\alpha \partial_\alpha(v_{(4)}'^\beta) = -\Gamma'_{(a)(4)(b)}v_{(c)}'^\beta \mathbf{g}'^{(a)(c)}.$$

We subtract these two identities to conclude that, schematically,

$$\bar{Y}(dv) = \mathcal{M}_\infty(d\Gamma) + \mathcal{M}_\infty(dv). \quad (5.14)$$

By differentiating (5.14) we also have

$$\bar{Y}(\partial dv) = \mathcal{M}_\infty(d\Gamma) + \mathcal{M}_\infty(\partial d\Gamma) + \mathcal{M}_\infty(dv) + \mathcal{M}_\infty(\partial dv). \quad (5.15)$$

We derive now a wave equation for dR . We start from the identity

$$(\square_{\mathbf{g}}\mathbf{R})_{(a)(b)(c)(d)} - (\square_{\mathbf{g}'}\mathbf{R}')_{(a)(b)(c)(d)} = \mathcal{M}_\infty(dR),$$

which follows from the standard wave equations satisfied by \mathbf{R} and \mathbf{R}' and the fact that $\mathbf{g}^{(m)(n)} = \mathbf{g}'^{(m)(n)} = h^{(m)(n)}$. We also have

$$\begin{aligned} & \mathbf{D}_{(m)}\mathbf{R}_{(a)(b)(c)(d)} - \mathbf{D}'_{(m)}\mathbf{R}'_{(a)(b)(c)(d)} \\ &= \mathcal{M}_\infty(dv) + \mathcal{M}_\infty(d\Gamma) + \mathcal{M}_\infty(dR) + \mathcal{M}_\infty(\partial dR). \end{aligned}$$

It follows from the last two equations that

$$\begin{aligned} & \mathbf{g}^{(m)(n)}v_{(n)}(v_{(m)}(\mathbf{R}_{(a)(b)(c)(d)})) - \mathbf{g}'^{(m)(n)}v'_{(n)}(v'_{(m)}(\mathbf{R}'_{(a)(b)(c)(d)})) \\ &= \mathcal{M}_\infty(dv) + \mathcal{M}_\infty(d\Gamma) + \mathcal{M}_\infty(\partial d\Gamma) + \mathcal{M}_\infty(dR) + \mathcal{M}_\infty(\partial dR). \end{aligned}$$

Since $\mathbf{g}^{(m)(n)} = \mathbf{g}'^{(m)(n)}$ it follows that

$$\begin{aligned} & \mathbf{g}^{(m)(n)}v_{(n)}(v_{(m)}((dR)_{(a)(b)(c)(d)})) \\ &= \mathcal{M}_\infty(dv) + \mathcal{M}_\infty(\partial dv) + \mathcal{M}_\infty(d\Gamma) + \mathcal{M}_\infty(\partial d\Gamma) + \mathcal{M}_\infty(dR) + \mathcal{M}_\infty(\partial dR). \end{aligned}$$

Thus

$$\square_{\mathbf{g}}(dR) = \mathcal{M}_\infty(dv) + \mathcal{M}_\infty(\partial dv) + \mathcal{M}_\infty(d\Gamma) + \mathcal{M}_\infty(\partial d\Gamma) + \mathcal{M}_\infty(dR) + \mathcal{M}_\infty(\partial dR). \quad (5.16)$$

This is our main wave equation.

¹⁰In general, given $H = (H_1, \dots, H_L) : B_{\delta''}(p_0) \rightarrow \mathbb{R}^L$ we let $\mathcal{M}_\infty(H) : B_{\delta''}(p_0) \rightarrow \mathbb{R}^L$ denote vector-valued functions of the form $\mathcal{M}_\infty(H)_{l'} = \sum_{l=1}^L A_{l'}^l H_l$, where the coefficients $A_{l'}^l$ are smooth on $B_{\delta''}(p_0)$.

We collect now equations (5.12), (5.13), (5.14), (5.15), and (5.16):

$$\begin{aligned}
 \bar{Y}(d\Gamma) &= \mathcal{M}_\infty(d\Gamma) + \mathcal{M}_\infty(dR); \\
 \bar{Y}(\partial d\Gamma) &= \mathcal{M}_\infty(d\Gamma) + \mathcal{M}_\infty(\partial d\Gamma) + \mathcal{M}_\infty(dR) + \mathcal{M}_\infty(\partial dR); \\
 \bar{Y}(dv) &= \mathcal{M}_\infty(dv) + \mathcal{M}_\infty(d\Gamma); \\
 \bar{Y}(\partial dv) &= \mathcal{M}_\infty(dv) + \mathcal{M}_\infty(\partial dv) + \mathcal{M}_\infty(d\Gamma) + \mathcal{M}_\infty(\partial d\Gamma); \\
 \square_{\mathbf{g}}(dR) &= \mathcal{M}_\infty(dv) + \mathcal{M}_\infty(\partial dv) + \mathcal{M}_\infty(d\Gamma) + \mathcal{M}_\infty(\partial d\Gamma) + \mathcal{M}_\infty(dR) + \mathcal{M}_\infty(\partial dR).
 \end{aligned} \tag{5.17}$$

This is our first main system of equations.

We derive now an additional system of this type, to exploit the existence of the Killing vector-fields \mathbf{T} and \mathbf{T}' . For $a, b = 1, \dots, 4$ let

$$\begin{aligned}
 (dT)_{(a)} &= \mathbf{T}'_{(a)} - \mathbf{T}_{(a)} = \mathbf{g}'(\mathbf{T}', L'_{(a)}) - \mathbf{g}(\mathbf{T}, L_{(a)}); \\
 (dF)_{(a)(b)} &= F'_{(a)(b)} - F_{(a)(b)} = \mathbf{D}'_{(a)}\mathbf{T}'_{(b)} - \mathbf{D}_{(a)}\mathbf{T}_{(b)}.
 \end{aligned} \tag{5.18}$$

Using the identities $\mathbf{D}_{v_{(4)}}v_{(b)} = 0$ and $\mathbf{D}'_{v_{(4)}}v'_{(b)} = 0$ it follows that $v_{(4)}(\mathbf{T}_{(b)}) = F_{(4)(b)}$ and $v_{(4)}(\mathbf{T}'_{(b)}) = F'_{(4)(b)}$. Thus

$$\bar{Y}(dT) = \mathcal{M}_\infty(dF). \tag{5.19}$$

We also have, using again $\mathbf{D}_{v_{(4)}}v_{(b)} = 0$,

$$v_{(4)}(F_{(a)(b)}) = \mathbf{D}_{(4)}F_{(a)(b)} = \mathbf{g}^{(c)(d)}\mathbf{T}_{(d)}\mathbf{R}_{(c)(4)(a)(b)} = h^{(c)(d)}\mathbf{T}_{(d)}\mathbf{R}_{(c)(4)(a)(b)}.$$

Similarly,

$$v_{(4)}(F'_{(a)(b)}) = h^{(c)(d)}\mathbf{T}'_{(d)}\mathbf{R}'_{(c)(4)(a)(b)}.$$

Thus, in our schematic notation,

$$\bar{Y}(dF) = \mathcal{M}_\infty(\mathbf{T}) + \mathcal{M}_\infty(\mathbf{R}). \tag{5.20}$$

Finally, we use the identities

$$\begin{aligned}
 0 &= (\mathcal{L}_{\mathbf{T}}\mathbf{R})_{(a)(b)(c)(d)} = \mathbf{T}^{(m)}\mathbf{D}_{(m)}\mathbf{R}_{(a)(b)(c)(d)} + \mathbf{D}_{(a)}\mathbf{T}^{(m)}\mathbf{R}_{(m)(b)(c)(d)} + \mathbf{D}_{(b)}\mathbf{T}^{(m)}\mathbf{R}_{(a)(m)(c)(d)} \\
 &\quad + \mathbf{D}_{(c)}\mathbf{T}^{(m)}\mathbf{R}_{(a)(b)(m)(d)} + \mathbf{D}_{(d)}\mathbf{T}^{(m)}\mathbf{R}_{(a)(b)(c)(m)},
 \end{aligned}$$

and

$$\begin{aligned}
 0 &= (\mathcal{L}_{\mathbf{T}'}\mathbf{R}')_{(a)(b)(c)(d)} = \mathbf{T}'^{(m)}\mathbf{D}'_{(m)}\mathbf{R}'_{(a)(b)(c)(d)} + \mathbf{D}'_{(a)}\mathbf{T}'^{(m)}\mathbf{R}'_{(m)(b)(c)(d)} \\
 &\quad + \mathbf{D}'_{(b)}\mathbf{T}'^{(m)}\mathbf{R}'_{(a)(m)(c)(d)} + \mathbf{D}'_{(c)}\mathbf{T}'^{(m)}\mathbf{R}'_{(a)(b)(m)(d)} + \mathbf{D}'_{(d)}\mathbf{T}'^{(m)}\mathbf{R}'_{(a)(b)(c)(m)}.
 \end{aligned}$$

Thus

$$\mathbf{T}'^{(m)}\mathbf{D}'_{(m)}\mathbf{R}'_{(a)(b)(c)(d)} - \mathbf{T}^{(m)}\mathbf{D}_{(m)}\mathbf{R}_{(a)(b)(c)(d)} = \mathcal{M}_\infty(dF) + \mathcal{M}_\infty(dR),$$

which easily gives

$$\mathbf{T}(dR) = \mathcal{M}_\infty(dF) + \mathcal{M}_\infty(dR) + \mathcal{M}_\infty(d\Gamma) + \mathcal{M}_\infty(dT) + \mathcal{M}_\infty(dv). \tag{5.21}$$

We collect now equations (5.19), (5.20), and (5.21), thus

$$\begin{aligned}\bar{Y}(dT) &= \mathcal{M}_\infty(dF); \\ \bar{Y}(dF) &= \mathcal{M}_\infty(dT) + \mathcal{M}_\infty(dR); \\ \mathbf{T}(dR) &= \mathcal{M}_\infty(dF) + \mathcal{M}_\infty(d\Gamma) + \mathcal{M}_\infty(dT) + \mathcal{M}_\infty(dL) + \mathcal{M}_\infty(dR).\end{aligned}\tag{5.22}$$

This is our second main system of differential equations. Since $\mathbf{g}' = \mathbf{g}$ and $\mathbf{T}' = \mathbf{T}$ in $\mathbf{E}_{R_0} \cap B_{\delta'}(p_0)$, the functions $d\Gamma, \partial d\Gamma, dv, \partial dv, dT, dF, dR$ vanish in $\mathbf{E}_{R_0} \cap B_{\delta'}(p_0)$. Therefore, using both systems (5.17) and (5.22), the lemma is a consequence of Lemma 5.5 below.

Lemma 5.5. *Assume $\delta > 0$, $p_0 \in \delta_{\Sigma_1}(\mathcal{U}_{R_0})$ and $G_i, H_j : B_\delta(p_0) \rightarrow \mathbb{R}$ are smooth functions, $i = 1, \dots, I$, $j = 1, \dots, J$. Let $G = (G_1, \dots, G_I)$, $H = (H_1, \dots, H_J)$, $\partial G = (\partial_0 G_1, \dots, \partial_4 G_I)$ and assume that, in $B_\delta(p_0)$,*

$$\begin{cases} \square_{\mathbf{g}} G = \mathcal{M}_\infty(G) + \mathcal{M}_\infty(\partial G) + \mathcal{M}_\infty(H); \\ \mathbf{T}(G) = \mathcal{M}_\infty(G) + \mathcal{M}_\infty(H); \\ \bar{Y}(H) = \mathcal{M}_\infty(G) + \mathcal{M}_\infty(\partial G) + \mathcal{M}_\infty(H).\end{cases}\tag{5.23}$$

Assume that $G = 0$ and $H = 0$ in $B_\delta(p_0) \cap \mathbf{E}_{R_0} = \{x \in B_\delta(p_0) : y(x) < R_0\}$. Then $G = 0$ and $H = 0$ in $B_{\tilde{\delta}}(p_0)$ for some $\tilde{\delta} \in (0, \delta)$ sufficiently small.

Unique continuation theorems of this type in the case $H = 0$ were proved by two of the authors in [24] and [25], using Carleman estimates. It is not hard to adapt the proofs, using the same Carleman estimates, to the general case. The essential ingredients are the \mathbf{T} -conditional pseudo-convexity property in Lemma 4.3 and the inequality $y(p_0) \geq (1 + \sqrt{1 - 4B})/2 + \tilde{C}^{-1}$, see (4.24). We provide all the details below.

5.2. Proof of Lemma 5.5. We will use a Carleman estimate proved by two of the authors in [24, Section 3], which we recall below. We may assume that the value of δ in Lemma 5.5 is sufficiently small. For $r \leq \delta$ let $B_r = B_r(p_0)$. Notice that, if $\mathbf{T} = \mathbf{T}^\alpha \partial_\alpha$, $\bar{Y} = \bar{Y}^\alpha \partial_\alpha$ in the coordinate frame induced by the diffeomorphism Φ_1 then

$$\sup_{x \in B_\delta} \sum_{j=0}^4 \sum_{\alpha=0}^3 (|\partial^j \mathbf{T}^\alpha(x)| + |\partial^j \bar{Y}^\alpha(x)|) \leq \tilde{C} = \tilde{C}(\bar{A}).\tag{5.24}$$

Definition 5.6. *A family of weights $h_\epsilon : B_{\epsilon^{10}} \rightarrow \mathbb{R}_+$, $\epsilon \in (0, \epsilon_1)$, $\epsilon_1 \leq \delta$ will be called \mathbf{T} -conditional pseudo-convex if for any $\epsilon \in (0, \epsilon_1)$*

$$h_\epsilon(p_0) = \epsilon, \quad \sup_{x \in B_{\epsilon^{10}}} \sum_{j=1}^4 \epsilon^j |\partial^j h_\epsilon(x)| \leq \epsilon/\epsilon_1, \quad |\mathbf{T}(h_\epsilon)(p_0)| \leq \epsilon^{10},\tag{5.25}$$

$$\mathbf{D}^\alpha h_\epsilon(p_0) \mathbf{D}^\beta h_\epsilon(p_0) (\mathbf{D}_\alpha h_\epsilon \mathbf{D}_\beta h_\epsilon - \epsilon \mathbf{D}_\alpha \mathbf{D}_\beta h_\epsilon)(p_0) \geq \epsilon^2,\tag{5.26}$$

and there is $\mu \in [-\epsilon_1^{-1}, \epsilon_1^{-1}]$ such that for all vectors $X = X^\alpha \partial_\alpha$ at p_0

$$\begin{aligned} & \epsilon_1^2 [(X^1)^2 + (X^2)^2 + (X^3)^2 + (X^4)^2] \\ & \leq X^\alpha X^\beta (\mu \mathbf{g}_{\alpha\beta} - \mathbf{D}_\alpha \mathbf{D}_\beta h_\epsilon)(p_0) + \epsilon^{-2} (|X^\alpha \mathbf{T}_\alpha(p_0)|^2 + |X^\alpha \mathbf{D}_\alpha h_\epsilon(x_0)|^2). \end{aligned} \quad (5.27)$$

A function $e_\epsilon : B_{\epsilon^{10}} \rightarrow \mathbb{R}$ will be called a negligible perturbation if

$$\sup_{x \in B_{\epsilon^{10}}} |\partial^j e_\epsilon(x)| \leq \epsilon^{10} \quad \text{for } j = 0, \dots, 4. \quad (5.28)$$

Our main Carleman estimate, see [24, Section 3], is the following:

Lemma 5.7. *Assume $\epsilon_1 \leq \delta$, $\{h_\epsilon\}_{\epsilon \in (0, \epsilon_1)}$ is a \mathbf{T} -conditional pseudo-convex family, and e_ϵ is a negligible perturbation for any $\epsilon \in (0, \epsilon_1]$. Then there is $\epsilon \in (0, \epsilon_1)$ sufficiently small (depending only on ϵ_1) and C sufficiently large such that for any $\lambda \geq C$ and any $\phi \in C_0^\infty(B_{\epsilon^{10}})$*

$$\lambda \|e^{-\lambda f_\epsilon} \phi\|_{L^2} + \|e^{-\lambda f_\epsilon} |\partial \phi|\|_{L^2} \leq C \lambda^{-1/2} \|e^{-\lambda f_\epsilon} \square_{\mathbf{g}} \phi\|_{L^2} + \epsilon^{-6} \|e^{-\lambda f_\epsilon} \mathbf{T}(\phi)\|_{L^2}, \quad (5.29)$$

where $f_\epsilon = \ln(h_\epsilon + e_\epsilon)$.

We also need a Carleman inequality to exploit the last equation in (5.23).

Lemma 5.8. *Assume $\epsilon \leq \delta$ is sufficiently small, e_ϵ is a negligible perturbation, and $h_\epsilon : B_{\epsilon^{10}} \rightarrow \mathbb{R}_+$ satisfies*

$$h_\epsilon(p_0) = \epsilon, \quad \sup_{x \in B_{\epsilon^{10}}} \sum_{j=1}^2 \epsilon^j |\partial^j h_\epsilon(x)| \leq 1, \quad |\bar{Y}(h_\epsilon)(p_0)| \geq \epsilon. \quad (5.30)$$

Then there is C sufficiently large such that for any $\lambda \geq C$ and any $\phi \in C_0^\infty(B_{\epsilon^{10}})$

$$\|e^{-\lambda f_\epsilon} \phi\|_{L^2} \leq 4(\epsilon \lambda)^{-1} \|e^{-\lambda f_\epsilon} \bar{Y}(\phi)\|_{L^2}, \quad (5.31)$$

where $f_\epsilon = \ln(h_\epsilon + e_\epsilon)$.

This inequality was proved in [2, Appendix A]. See also [23, Chapter 28] for much more general Carleman inequalities under suitable pseudo-convexity conditions.

To prove Lemma 5.5 we set

$$h_\epsilon = y - y(p_0) + \epsilon \quad \text{and} \quad e_\epsilon = \epsilon^{12} N^{p_0}, \quad (5.32)$$

where $N^{p_0}(x) = |\Phi_1^{-1}(x) - \Phi_1^{-1}(p_0)|^2$ is the square of the standard euclidean norm.

It is clear that e_ϵ is a negligible perturbation, in the sense of (5.28), for ϵ sufficiently small. Also, it is clear that h_ϵ verifies the condition (5.30), for ϵ sufficiently small, see Lemma 5.3.

We show now that there is $\epsilon_1 = \epsilon_1(\delta)$ sufficiently small such that the family of weights $\{h_\epsilon\}_{\epsilon \in (0, \epsilon_1)}$ is \mathbf{T} -conditional pseudo-convex, in the sense of Definition 5.6. Condition (5.25) is clearly satisfied, since $\mathbf{T}(y) = 0$. Condition 5.26 is also satisfied for ϵ sufficiently small since $\mathbf{D}^\alpha y(p_0) \mathbf{D}_\alpha y(p_0) \geq \tilde{C}^{-1}$, see (3.26). To prove (5.27) for some vector X we apply Lemma 4.3 if $|X^\alpha \mathbf{T}_\alpha| + |X^\alpha \mathbf{D}_\alpha y| \leq c_2 |X|$; if $|X^\alpha \mathbf{T}_\alpha| + |X^\alpha \mathbf{D}_\alpha y| \geq c_2 |X|$ then the second

term in the right-hand side of (5.27) dominates the other terms, provided that ϵ_1 is sufficiently small.

It follows from the Carleman estimates in Lemmas 5.7 and 5.8 that there is $\epsilon = \epsilon(\delta, \bar{A}) > 0$ and a constant $C = C(\delta, \bar{A}) \geq 1$ such that

$$\begin{aligned} \lambda \|e^{-\lambda f_\epsilon} \phi\|_{L^2} + \|e^{-\lambda f_\epsilon} |\partial \phi|\|_{L^2} &\leq C \lambda^{-1/2} \|e^{-\lambda f_\epsilon} \square_{\mathbf{g}} \phi\|_{L^2} + C \|e^{-\lambda f_\epsilon} \mathbf{T}(\phi)\|_{L^2}; \\ \lambda^{1/2} \|e^{-\lambda f_\epsilon} \phi\|_{L^2} &\leq C \lambda^{-1/2} \|e^{-\lambda f_\epsilon} \bar{Y}(\phi)\|_{L^2}, \end{aligned} \quad (5.33)$$

for any $\phi \in C_0^\infty(B_{\epsilon^{10}}(p_0))$ and any $\lambda \geq C$, where $f_\epsilon = \ln(h_\epsilon + e_\epsilon)$. Let $\eta : \mathbb{R} \rightarrow [0, 1]$ denote a smooth function supported in $[1/2, \infty)$ and equal to 1 in $[3/4, \infty)$. For $i = 1, \dots, I$, $j = 1, \dots, J$ we define,

$$\begin{aligned} G_i^\epsilon &= G_i \cdot (1 - \eta(N^{x_0}/\epsilon^{20})) = G_i \cdot \tilde{\eta}_\epsilon \\ H_j^\epsilon &= H_j \cdot (1 - \eta(N^{x_0}/\epsilon^{20})) = H_j \cdot \tilde{\eta}_\epsilon. \end{aligned} \quad (5.34)$$

Clearly, $G_i^\epsilon, H_j^\epsilon \in C_0^\infty(B_{\epsilon^{10}}(p_0))$. We would like to apply the inequalities in (5.33) to the functions $G_i^\epsilon, H_j^\epsilon$, and then let $\lambda \rightarrow \infty$.

Using the definition (5.34), we have

$$\begin{aligned} \square_{\mathbf{g}} G_i^\epsilon &= \tilde{\eta}_\epsilon \square_{\mathbf{g}} G_i + 2\mathbf{D}_\alpha G_i \mathbf{D}^\alpha \tilde{\eta}_\epsilon + G_i \square_{\mathbf{g}} \tilde{\eta}_\epsilon; \\ \mathbf{T}(G_i^\epsilon) &= \tilde{\eta}_\epsilon \mathbf{T}(G_i) + \mathbf{T}(\tilde{\eta}_\epsilon) G_i; \\ \bar{Y}(H_j^\epsilon) &= \tilde{\eta}_\epsilon \cdot \bar{Y}(H_j) + H_j \cdot \bar{Y}(\tilde{\eta}_\epsilon). \end{aligned}$$

Using the Carleman inequalities (5.33), for any $i = 1, \dots, I$, $j = 1, \dots, J$ we have

$$\begin{aligned} \lambda \cdot \|e^{-\lambda f_\epsilon} \cdot \tilde{\eta}_\epsilon G_i\|_{L^2} + \|e^{-\lambda f_\epsilon} \cdot \tilde{\eta}_\epsilon |\partial G_i|\|_{L^2} \\ \leq C \lambda^{-1/2} \cdot \|e^{-\lambda f_\epsilon} \cdot \tilde{\eta}_\epsilon \square_{\mathbf{g}} G_i\|_{L^2} + C \|e^{-\lambda f_\epsilon} \cdot \tilde{\eta}_\epsilon \mathbf{T}(G_i)\|_{L^2} \\ + C' \left[\|e^{-\lambda f_\epsilon} \cdot \mathbf{D}_\alpha G_i \mathbf{D}^\alpha \tilde{\eta}_\epsilon\|_{L^2} + \|e^{-\lambda f_\epsilon} \cdot G_i (|\square_{\mathbf{g}} \tilde{\eta}_\epsilon| + |\partial \tilde{\eta}_\epsilon|)\|_{L^2} \right] \end{aligned} \quad (5.35)$$

and

$$\lambda^{1/2} \|e^{-\lambda f_\epsilon} \cdot \tilde{\eta}_\epsilon H_j\|_{L^2} \leq C \lambda^{-1/2} \|e^{-\lambda f_\epsilon} \cdot \tilde{\eta}_\epsilon \bar{Y}(H_j)\|_{L^2} + C' \lambda^{-1/2} \|e^{-\lambda f_\epsilon} \cdot H_j |\partial \tilde{\eta}_\epsilon|\|_{L^2}, \quad (5.36)$$

for any $\lambda \geq C$ and some constant $C' = C'(\bar{A}, C)$. Using the main identities (5.23), in $B_{\epsilon^{10}}(p_0)$ we estimate pointwise

$$\begin{aligned} |\square_{\mathbf{g}} G_i| &\leq M \sum_{l=1}^I (|\partial G_l| + |G_l|) + M \sum_{m=1}^J |H_m|, \\ |\mathbf{T}(G_i)| &\leq M \sum_{l=1}^I |G_l| + M \sum_{m=1}^J |H_m| \\ |\bar{Y}(H_j)| &\leq M \sum_{l=1}^I (|\partial G_l| + |G_l|) + M \sum_{m=1}^J |H_m|, \end{aligned} \quad (5.37)$$

for some large constant M . We add inequalities (5.35) and (5.36) over i, j . The key observation is that, in view of (5.37), the main terms in the right-hand sides of (5.35) and (5.36) can be absorbed into the left-hand sides for λ sufficiently large. Thus, for any λ sufficiently large,

$$\begin{aligned} & \lambda \sum_{i=1}^I \|e^{-\lambda f_\epsilon} \tilde{\eta}_\epsilon G_i\|_{L^2} + \sum_{i=1}^I \|e^{-\lambda f_\epsilon} \tilde{\eta}_\epsilon |\partial G_i|\|_{L^2} + \lambda^{1/2} \sum_{j=1}^J \|e^{-\lambda f_\epsilon} \tilde{\eta}_\epsilon H_j\|_{L^2} \\ & \leq C'' \sum_{j=1}^J \|e^{-\lambda f_\epsilon} H_j |\partial \tilde{\eta}_\epsilon|\|_{L^2} + C'' \sum_{i=1}^I [\|e^{-\lambda f_\epsilon} \mathbf{D}_\alpha G_i \mathbf{D}^\alpha \tilde{\eta}_\epsilon\|_{L^2} + \|e^{-\lambda f_\epsilon} G_i (|\square_{\mathbf{g}} \tilde{\eta}_\epsilon| + |\partial \tilde{\eta}_\epsilon|)\|_{L^2}]. \end{aligned}$$

We observe that the functions $\square_{\mathbf{g}} \tilde{\eta}_\epsilon$ and $\partial \tilde{\eta}_\epsilon$ are supported in the set $\{x \in B_{\epsilon^{10}}(p_0) : N^{p_0} \geq \epsilon^{20}/2\}$ and $\tilde{\eta}_\epsilon = 1$ in $B_{\epsilon^{100}}(p_0)$. By assumption, the functions $G_i, |\partial G_i|, H_j$ are supported in $\{x \in B_\delta(p_0) : y(x) \geq y(p_0)\}$. In addition,

$$\inf_{B_{\epsilon^{100}}(p_0)} e^{-\lambda f_\epsilon} \geq e^{\lambda/C'''} \sup_{\{x \in B_{\epsilon^{10}}(p_0) : N^{p_0} \geq \epsilon^{20}/2 \text{ and } y(x) \geq y(p_0)\}} e^{-\lambda f_\epsilon},$$

which follows easily from the definition (5.32). We let now $\lambda \rightarrow \infty$, as in [24, Section 8], to conclude that $\mathbf{1}_{B_{\epsilon^{100}}} G_i = 0$ and $\mathbf{1}_{B_{\epsilon^{100}}} H_j = 0$. The lemma follows.

6. CONSTRUCTION OF THE ROTATIONAL KILLING VECTOR-FIELD \mathbf{Z}

In this section we extend the rotational Killing vector-field \mathbf{Z} constructed in a small neighborhood of S_0 , see Proposition 5.1, to the entire exterior region \mathbf{E} . In $\mathbf{E} \cup \mathcal{O}_{\bar{\epsilon}}$ we define

$$\mathbf{Z} = \mathbf{T} + \lambda_0 \mathbf{K},$$

where λ_0 is as in Proposition 5.1. Clearly $\lambda_0 \neq 0$, in view of the assumption **GR** that \mathbf{T} does not vanish in \mathbf{E} , and \mathbf{Z} does not vanish identically in \mathbf{E} , since, by assumption **SBS**, \mathbf{T} does not vanish identically on S_0 . It follows from (5.3) that

$$\mathcal{L}_{\mathbf{Z}} \mathbf{g} = 0, \quad [\mathbf{T}, \mathbf{Z}] = [\mathbf{K}, \mathbf{Z}] = 0, \quad \mathbf{Z}^\mu \sigma_\mu = 0 \quad \text{in } \mathbf{E} \cup \mathcal{O}_{\bar{\epsilon}}. \quad (6.1)$$

As in the proof of (5.6), it follows that

$$[\mathbf{Z}, Y] = 0 \quad \text{in } \mathbf{E} \cup \mathcal{O}_{\bar{\epsilon}}. \quad (6.2)$$

In view of Proposition 5.1, there is $t_0 > 0$ ¹¹ such that $\Psi_{t_0, \mathbf{Z}} = \text{Id}$ in \mathcal{O}' . Clearly

$$\Psi_{s, \mathbf{T}}(p) = \Psi_{s, \mathbf{T}} \Psi_{t_0, \mathbf{Z}}(p) = \Psi_{t_0, \mathbf{Z}} \Psi_{s, \mathbf{T}}(p) \quad \text{for any } p \in \mathcal{O}_{\bar{\epsilon}} \cap \mathbf{E} \quad \text{and } s \in \mathbb{R}, \quad (6.3)$$

using the commutation relation $[\mathbf{T}, \mathbf{Z}] = 0$. It follows that $\Psi_{t_0, \mathbf{Z}}(p) = p$ for any $p \in \mathbf{E}_{y_0}$, recall definition (5.4). To prove this identity for any point $p \in \mathbf{E}$, assume that

$$\Psi_{t_0, \mathbf{Z}}(p) = p \quad \text{for any } p \in \mathbf{E}_{R_0},$$

¹¹Using the assumption that the orbits of \mathbf{T} in \mathbf{E} are complete and intersect Σ^0 , see assumption **GR**, it is easy to see that any smooth vector-field V in $\mathbf{E} \cup \mathcal{O}_{\bar{\epsilon}}$ which commutes with \mathbf{T} and is tangent to $\mathcal{H}^\pm \cap \mathcal{O}_{\bar{\epsilon}}$ has complete orbits in \mathbf{E} .

for some $R_0 \geq y_0$. As before, it follows that $\Psi_{t_0, \mathbf{Z}}(p) = p$ for any $p \in \mathbf{E}_{R_0}$. Using $[Y, \mathbf{Z}] = 0$ and an identity similar to (6.3), it follows that

$$\Psi_{t_0, \mathbf{Z}}(p) = p \text{ for any } p \in \mathbf{E}_{R_0 + \delta'},$$

for some $\delta' = \delta'(\bar{A}) > 0$. To summarize, we proved:

Corollary 6.1. *There is a nontrivial smooth vector-field \mathbf{Z} in $\mathbf{E} \cup \mathcal{O}_{\bar{c}}$, tangent to $\mathcal{H}^+ \cap \mathcal{O}_{\bar{c}}$ and $\mathcal{H}^- \cap \mathcal{O}_{\bar{c}}$, and a real number $t_0 > 0$ such that*

$$\Psi_{t_0, \mathbf{Z}} = \text{Id}, \quad \mathcal{L}_{\mathbf{Z}} \mathbf{g} = 0, \quad [\mathbf{T}, \mathbf{Z}] = 0, \quad \mathbf{Z}^\mu \sigma_\mu = 0 \quad \text{in } \mathbf{E}.$$

6.1. The time-like span of the two Killing fields. We define the area function

$$W = -\mathbf{g}(\mathbf{T}, \mathbf{T})\mathbf{g}(\mathbf{Z}, \mathbf{Z}) + \mathbf{g}(\mathbf{T}, \mathbf{Z})^2.$$

In this subsection we show that $W \geq 0$ in \mathbf{E} . More precisely, we prove the following slightly stronger proposition:

Proposition 6.2. *The vector-field \mathbf{K} constructed in Theorem 5.2 does not vanish at any point in \mathbf{E} . In addition, at any point $p \in \mathbf{E}$ there is a timelike linear combination of the vector-fields \mathbf{T} and \mathbf{K} .*

Proof of Proposition 6.2. In view of (5.2), \mathbf{K} does not vanish at any point in \mathcal{U}_{y_0} . It follows that \mathbf{K} does not vanish at any point in \mathbf{E}_{y_0} , since \mathbf{K} is constructed as the solution of $[\mathbf{T}, \mathbf{K}] = 0$ in \mathbf{E}_{y_0} .

To prove that \mathbf{K} does not vanish at any point $p \in \mathbf{E}$ we use the identity $[\mathbf{K}, Y] = 0$ in \mathbf{E} , see (5.6). Let

$$R_1 = \sup\{R \in [y_0, \infty) : \mathbf{K} \text{ does not vanish at any point in } \mathbf{E}_R\}.$$

If $R_1 < \infty$ then \mathbf{K} has to vanish at some point $p_0 \in \delta_{\Sigma_1}(\mathcal{U}_{R_1})$ (using the assumption that any orbit of \mathbf{T} in \mathbf{E} intersects Σ_1 , and the observation that the set of points in \mathbf{E} where \mathbf{K} vanishes can only be a union of orbits of \mathbf{T}). Since $[\mathbf{K}, Y] = 0$ in \mathbf{E} , \mathbf{K} vanishes on the integral curve $\gamma_{p_0}(t)$, $|t| \ll 1$, of the vector-field Y starting at the point p_0 . However, this integral curve intersects the set $\mathbf{E}_{R'}$ for some $R' < R_1$, in contradiction with the definition of R_1 . Thus \mathbf{K} does not vanish at any point in \mathbf{E} .

We prove now the second part of the proposition. Let

$$N = \{p \in \mathbf{E} : \text{there is no timelike linear combination of } \mathbf{T} \text{ and } \mathbf{K} \text{ at } p\}.$$

Clearly, the set N is closed in \mathbf{E} and consists of orbits of the vector-field \mathbf{T} . In addition, $N \subseteq \mathbf{E} \setminus \mathbf{E}_{y_0}$, since \mathbf{K} itself is timelike in \mathbf{E}_{y_0} (see (5.2)). In view of (4.24) and (4.13) we have $y \geq (1 + \sqrt{1 - 4B})/2 + \tilde{C}_2^{-2}$ in $\mathbf{E} \setminus \mathbf{E}_{y_0}$. On the other hand $\mathbf{g}(\mathbf{T}, \mathbf{T}) = y/(y^2 + z^2) - 1$, hence $z^2 \leq y - y^2 = -(y^2 - y + B) + B$ in N . Consequently, for some constant $\tilde{C} = \tilde{C}(\bar{A}) \gg 1$,

$$y \geq (1 + \sqrt{1 - 4B})/2 + \tilde{C}^{-1} \quad \text{and} \quad B - z^2 \geq \tilde{C}^{-1} \quad \text{in } N, \quad (6.4)$$

Consider now the set of vector-fields \mathbf{T}, \mathbf{K} as well as the gradient vector-fields $Y = \mathbf{D}^\alpha y \mathbf{D}_\alpha$, $Z = \mathbf{D}^\alpha z \mathbf{D}_\alpha$ at some point $p \in N$. Since $\mathbf{T}(\sigma) = \mathbf{K}(\sigma) = 0$ we have

$$\mathbf{g}(\mathbf{T}, Y) = \mathbf{g}(\mathbf{T}, Z) = \mathbf{g}(\mathbf{K}, Y) = \mathbf{g}(\mathbf{K}, Z) = 0.$$

In addition, using (3.26), (3.18), and (6.4)

$$\mathbf{g}(Y, Y) \geq \tilde{C}^{-1}, \quad \mathbf{g}(Z, Z) \geq \tilde{C}^{-1}, \quad |\mathbf{g}(Y, Z)| \leq \tilde{C} \bar{\varepsilon}^{1/5} \quad \text{in } N, \quad (6.5)$$

for some constant $\tilde{C} = \tilde{C}(\bar{A})$. Since the metric \mathbf{g} is Lorentzian, it follows that the vectors $\mathbf{T}, \mathbf{K}, Y, Z$ cannot be linearly independent at any point $p \in N$ (if they were linearly independent then the determinant of the matrix formed by the coefficients $\mathbf{g}(\mathbf{T}, \mathbf{T}), \mathbf{g}(\mathbf{T}, \mathbf{K}), \mathbf{g}(\mathbf{K}, \mathbf{K})$ would have to be negative, in contradiction with $p \in N$). Since the triplets \mathbf{T}, Y, Z and \mathbf{K}, Y, Z are linearly independent it must follow that \mathbf{K}, \mathbf{T} are linearly dependent at points of N . Thus

$$\text{for any } p \in N \text{ there is } a \in \mathbb{R} \text{ such that } \mathbf{K}_p = a\mathbf{T}_p \text{ and } \mathbf{g}(\mathbf{T}, \mathbf{T})|_p \geq 0. \quad (6.6)$$

We prove now that $N = \emptyset$. Assume that $N \neq \emptyset$ and let p_0 denote a point in N such that $y(p_0) = \inf_{p \in N} y(p)$. Such a point exists since $N \cap \Sigma_1 \subseteq \Sigma_{1+(4\tilde{C}_1\tilde{C}_2)^{-1/2}}$ (see (5.2)) is compact (observe that \mathbf{T} is timelike in Σ_R for large R). We may assume that $p_0 \in N \cap \Sigma_1$. In view of (6.6), there is $a_0 \in \mathbb{R}$ such that $\mathbf{K}_{p_0} - a_0\mathbf{T}_{p_0} = 0$. We look at the integral curve $\{\gamma_{p_0}(t) : |t| \ll 1\}$ of the vector field Y passing through p_0 . Since $[Y, \mathbf{K} - a_0\mathbf{T}] = 0$ and $Y_{p_0} \neq 0$, it follows that $\mathbf{K} = a_0\mathbf{T}$ in the set $\gamma_{p_0}(t), |t| \ll 1$. Since $Y(y) = \mathbf{g}(Y, Y)$ is strictly positive at p_0 (see (6.5)), it follows that $y(\gamma_{p_0}(t)) < y(p_0)$ if $t \in (-\tilde{C}^{-1}, 0)$. Since $y(p_0) = \inf_{p \in N} y(p)$ (the definition of p_0), it follows that

$$N \cap \{\gamma_{p_0}(t) : t \in (-\tilde{C}^{-1}, 0)\} = \emptyset.$$

Since $\mathbf{K} = a_0\mathbf{T}$ in $\{\gamma_{p_0}(t) : t \in (-\tilde{C}^{-1}, 0)\}$ it follows that $\mathbf{g}(\mathbf{T}, \mathbf{T}) < 0$ in $\{\gamma_{p_0}(t) : t \in (-\tilde{C}^{-1}, 0)\}$. Using the formula $\mathbf{g}(\mathbf{T}, \mathbf{T}) = y/(y^2 + z^2) - 1$, it follows that the function $y - y^2 - z^2$ vanishes at p_0 and is strictly negative on $\{\gamma_{p_0}(t) : t \in (-\tilde{C}^{-1}, 0)\}$. Thus

$$Y(y - y^2 - z^2) \geq 0 \quad \text{at } p_0.$$

On the other hand, using (6.5) and (6.4),

$$\mathbf{D}^\alpha y \mathbf{D}_\alpha (y - y^2 - z^2) = (1 - 2y)\mathbf{D}^\alpha y \mathbf{D}_\alpha y - 2z\mathbf{D}^\alpha y \mathbf{D}_\alpha z < 0 \quad \text{at } p_0,$$

provided that $\bar{\varepsilon}$ is sufficiently small. This provides a contradiction. \square

APPENDIX A. ASYMPTOTIC IDENTITIES

Recall, see assumption **GR**, that we assumed the existence of an open subset $\mathbf{M}^{(end)}$ of \mathbf{M} which is diffeomorphic to $\mathbb{R} \times (\{x \in \mathbb{R}^3 : |x| > R\})$ for some R sufficiently large. In local coordinates $\{t, x^i\}$ defined by this diffeomorphism, we assume that $\mathbf{T} = \partial_t$ and, with $r = \sqrt{(x^1)^2 + (x^2)^2 + (x^3)^2}$,

$$\mathbf{g}_{00} = -1 + \frac{2M}{r} + O(r^{-2}), \quad \mathbf{g}_{ij} = \delta_{ij} + O(r^{-1}), \quad \mathbf{g}_{0i} = -\epsilon_{ijk} \frac{2S^j x^k}{r^3} + O(r^{-3}), \quad (\text{A.1})$$

for some $M > 0$, $S^1, S^2, S^3 \in \mathbb{R}$. Clearly,

$$\mathbf{g}^{00} = -1 + O(r^{-1}), \quad \mathbf{g}^{ij} = \delta_{ij} + O(r^{-1}), \quad \mathbf{g}^{0i} = O(r^{-2}). \quad (\text{A.2})$$

We compute

$$F_{\alpha\beta} = \mathbf{D}_\alpha \mathbf{T}_\beta = \partial_\alpha(\mathbf{g}_{0\beta}) - \mathbf{g}(\partial_0, \mathbf{D}_{\partial_\alpha} \partial_\beta) = \frac{1}{2}(\partial_\alpha \mathbf{g}_{0\beta} - \partial_\beta \mathbf{g}_{0\alpha}). \quad (\text{A.3})$$

Thus, using (A.1), for $j = 1, 2, 3$,

$$F_{0j} = -(1/2)\partial_j \mathbf{g}_{00} = Mx^j r^{-3} + O(r^{-3}). \quad (\text{A.4})$$

We have

$$\begin{aligned} \mathbf{g}_{01} &= 2r^{-3}(S^3 x^2 - S^2 x^3) + O(r^{-3}) \\ \mathbf{g}_{02} &= 2r^{-3}(S^1 x^3 - S^3 x^1) + O(r^{-3}) \\ \mathbf{g}_{03} &= 2r^{-3}(S^2 x^1 - S^1 x^2) + O(r^{-3}). \end{aligned} \quad (\text{A.5})$$

Thus

$$\begin{aligned} F_{12} &= (1/2)(\partial_1 \mathbf{g}_{02} - \partial_2 \mathbf{g}_{01}) = S^3 r^{-3} - 3r^{-5} x^3 (S^1 x^1 + S^2 x^2 + S^3 x^3) + O(r^{-4}), \\ F_{23} &= (1/2)(\partial_2 \mathbf{g}_{03} - \partial_3 \mathbf{g}_{02}) = S^1 r^{-3} - 3r^{-5} x^1 (S^1 x^1 + S^2 x^2 + S^3 x^3) + O(r^{-4}), \\ F_{31} &= (1/2)(\partial_3 \mathbf{g}_{01} - \partial_1 \mathbf{g}_{03}) = S^2 r^{-3} - 3r^{-5} x^2 (S^1 x^1 + S^2 x^2 + S^3 x^3) + O(r^{-4}). \end{aligned} \quad (\text{A.6})$$

We have

$${}^*F_{\alpha\beta} = (1/2) \epsilon_{\alpha\beta\mu\nu} F_{\rho\sigma} \mathbf{g}^{\mu\rho} \mathbf{g}^{\nu\sigma}.$$

Thus, using (A.2), (A.4), (A.6),

$$\begin{aligned} {}^*F_{01} &= F_{23} + O(r^{-4}) = S^1 r^{-3} - 3r^{-5} x^1 (S^1 x^1 + S^2 x^2 + S^3 x^3) + O(r^{-4}), \\ {}^*F_{02} &= F_{31} + O(r^{-4}) = S^2 r^{-3} - 3r^{-5} x^2 (S^1 x^1 + S^2 x^2 + S^3 x^3) + O(r^{-4}), \\ {}^*F_{03} &= F_{12} + O(r^{-4}) = S^3 r^{-3} - 3r^{-5} x^3 (S^1 x^1 + S^2 x^2 + S^3 x^3) + O(r^{-4}), \\ {}^*F_{12} &= -F_{03} + O(r^{-3}) = -Mx^3 r^{-3} + O(r^{-3}), \\ {}^*F_{23} &= -F_{01} + O(r^{-3}) = -Mx^1 r^{-3} + O(r^{-3}), \\ {}^*F_{31} &= -F_{02} + O(r^{-3}) = -Mx^2 r^{-3} + O(r^{-3}). \end{aligned} \quad (\text{A.7})$$

As a consequence,

$$\mathcal{F}^2 = (F_{\alpha\beta} + i {}^*F_{\alpha\beta})(F^{\alpha\beta} + i {}^*F^{\alpha\beta}) = -4M^2 r^{-4} + O(r^{-5}). \quad (\text{A.8})$$

By definition,

$$\sigma_\mu = 2\mathbf{T}^\alpha (F_{\alpha\mu} + i {}^*F_{\alpha\mu}).$$

Thus

$$\begin{aligned}
 \sigma_0 &= 0; \\
 \sigma_1 &= 2Mx^1r^{-3} + O(r^{-3}) + 2i[S^1r^{-3} - 3r^{-5}x^1(S^1x^1 + S^2x^2 + S^3x^3) + O(r^{-4})]; \\
 \sigma_2 &= 2Mx^2r^{-3} + O(r^{-3}) + 2i[S^2r^{-3} - 3r^{-5}x^2(S^1x^1 + S^2x^2 + S^3x^3) + O(r^{-4})]; \\
 \sigma_3 &= 2Mx^3r^{-3} + O(r^{-3}) + 2i[S^3r^{-3} - 3r^{-5}x^3(S^1x^1 + S^2x^2 + S^3x^3) + O(r^{-4})].
 \end{aligned} \tag{A.9}$$

Thus

$$\sigma = 1 - 2Mr^{-1} + O(r^{-2}) + i[2r^{-3}(S^1x^1 + S^2x^2 + S^3x^3) + O(r^{-3})]. \tag{A.10}$$

Thus

$$y + iz = (1 - \sigma)^{-1} = \frac{r}{2M} + O(1) + i\left[\frac{S^1x^1 + S^2x^2 + S^3x^3}{2M^2r} + O(r^{-1})\right],$$

which gives

$$y = \frac{r}{2M} + O(1), \quad z = \frac{S^1x^1 + S^2x^2 + S^3x^3}{2M^2r} + O(r^{-1}). \tag{A.11}$$

Thus, with $J = [(S^1)^2 + (S^2)^2 + (S^3)^2]^{1/2}$,

$$\begin{aligned}
 \mathbf{D}_\mu z \mathbf{D}^\mu z &= \sum_{j=1}^3 (\partial_j z)^2 + O(r^{-3}) \\
 &= \frac{1}{4M^4} \sum_{j=1}^3 [S^j r^{-1} - x^j r^{-3} (S^1 x^1 + S^2 x^2 + S^3 x^3)]^2 + O(r^{-3}) \\
 &= \frac{1}{4M^4} [J^2 r^{-2} - r^{-4} (S^1 x^1 + S^2 x^2 + S^3 x^3)^2] + O(r^{-3}).
 \end{aligned}$$

It follows that

$$\begin{aligned}
 z^2 + 4M^2(y^2 + z^2) \mathbf{D}_\mu z \mathbf{D}^\mu z &= \frac{1}{4M^4} (S^1 x^1 + S^2 x^2 + S^3 x^3)^2 r^{-2} + r^2 \mathbf{D}_\mu z \mathbf{D}^\mu z + O(r^{-1}) \\
 &= \frac{J^2}{4M^4} + O(r^{-1}).
 \end{aligned} \tag{A.12}$$

REFERENCES

- [1] S. Alexakis, *Unique continuation for the vacuum Einstein equations*, Preprint (2008), gr-qc0902.1131.
- [2] S. Alexakis, A. D. Ionescu, and S. Klainerman, *Hawking's local rigidity theorem without analyticity*, Preprint (2009), gr-qc0902.1173.
- [3] R. Beig and W. Simon, *The stationary gravitational field near spatial infinity*, Gen. Relativity Gravitation **12** (1980), 1003–1013.
- [4] R. Beig and W. Simon, *On the multipole expansion for stationary space-times*, Proc. Roy. Soc. London Ser. A **376** (1981), 333–341.
- [5] G.L. Bunting, *Proof of the Uniqueness Conjecture for Black Holes*, PhD Thesis, (1983) Univ. of New England, Armidale, NSW.

- [6] G. Bunting and A.K.M. Massood-ul-Alam, *Nonexistence of multiple black holes in asymptotically Euclidean static vacuum space-time*, Gen. Relativity Gravitation **19** (1987), 147-154.
- [7] B. Carter, *An axy-symmetric black hole has only two degrees of freedom*, Phys. Rev. Lett. **26** (1971), 331-333.
- [8] B. Carter, *Black hole equilibrium states*, Black holes/Les astres occlus (École d'Été Phys. Théor., Les Houches, 1972), pp. 57-214. Gordon and Breach, New York, 1973.
- [9] B. Carter, *Has the Black Hole Equilibrium Problem Been Solved?*, In: The Eighth Marcel Grossmann meeting, Part A, B (Jerusalem, 1997), pp. 136-155, World Sci. Publ., River Edge, NJ (1999).
- [10] D. Christodoulou and S. Klainerman, *The global nonlinear stability of the Minkowski space*, Princeton Math. Series 41, Princeton University Press (1993).
- [11] P.T. Chrusciel, *On completeness of orbits of Killing vector fields*, Classical Quantum Gravity **10** (1993), 2091-2101, gr-qc/9304029.
- [12] P.T. Chrusciel, *"No Hair" Theorems-Folclore, Conjecture, Results*. Diff. Geom. and Math. Phys.(J. Beem and K.L. Duggal) Cont. Math., **170**, AMS, Providence, (1994), 23-49, gr-qc9402032, (1994).
- [13] P.T. Chrusciel, *On the rigidity of analytic black holes* Comm. Math. Phys. **189** (1997), 1-7.
- [14] P.T. Chrusciel and R.M. Wald, *Maximal hypersurfaces in stationary asymptotically flat spacetimes*, Comm. Math. Phys. **163** (1994), 561-604.
- [15] P.T. Chrusciel and R.M. Wald *On the topology of stationary black holes*, Classical Quantum Gravity **11** (1993), L147-L152.
- [16] P.T. Chrusciel, T. Delay, G. Galloway and R. Howard, *Regularity of horizon and the area theorem* Annales H. Poincaré, **2**, (2001), 109-178, gr-qc000103.
- [17] P. T. Chrusciel and J. L. Costa, *On uniqueness of stationary vacuum black holes*, Preprint (2008), gr-qc0806.0016.
- [18] P.T. Chrusciel, *On higher dimensional black holes with abelian isometry group*, arXiv:0812.3424
- [19] J.L. Friedman, K. Schleich, D.M. Witt, *Topological censorship*, Phys. Rev.. Letters, **71**, 1846-1849 (1993).
- [20] H. Friedrich, I. Rácz, R. Wald, *On the rigidity theorem for spacetimes with a stationary event horizon or a compact Cauchy horizon*, Commun. Math. Phys. **204**, 691-707 (1999).
- [21] S.W. Hawking and G.F.R. Ellis, *The large scale structure of space-time*, Cambridge Univ. Press, 1973.
- [22] M. Heusler, *Black Hole Uniqueness Theorems*, Cambridge Lect. Notes in Phys, 1996.
- [23] L. Hörmander, *The analysis of linear partial differential operators IV. Fourier integral operators*, Grundlehren der Mathematischen Wissenschaften [Fundamental Principles of Mathematical Sciences], 275. Springer-Verlag, Berlin (1985).
- [24] A. D. Ionescu and S. Klainerman, *On the uniqueness of smooth, stationary black holes in vacuum*, Invent. Math. **175** (2009), 35-102.
- [25] A. D. Ionescu and S. Klainerman, *Uniqueness results for ill-posed characteristic problems in curved space-times*, Commun. Math. Phys. **285** (2009), 873-900.
- [26] J. Isenberg and V. Moncrief, *Symmetries of Cosmological Cauchy Horizons*, Commun. Math. Phys. **89** (1983), 387-413.
- [27] W. Israel, *Event horizons in static vacuum space-times*, Phys. Rev. Letters **164** (1967), 1776-1779.
- [28] S. Klainerman and F. Nicolò, *The evolution problem in general relativity*. Progress in Mathematical Physics, 25. Birkhäuser Boston, Inc., Boston, MA, (2003).
- [29] M. Mars, *A spacetime characterization of the Kerr metric*, Classical Quantum Gravity **16** (1999), 2507-2523.
- [30] M. Mars, *Uniqueness properties of the Kerr metric*, Classical Quantum Gravity **17** (2000), 3353-3373.

- [31] P.O. Mazur Proof of Uniqueness for the Kerr-Newman Black Hole Solution. J. Phys A: Math Gen., 15 (1982) 3173-3180.
- [32] D.C. Robinson, *Uniqueness of the Kerr black hole*, Phys. Rev. Lett. **34** (1975), 905-906.
- [33] I. Racz and R. Wald, *Extensions of space-times with Killing horizons*, Class. Quant. Gr., **9** (1992), 2463-2656.
- [34] W. Simon, *Characterization of the Kerr metric*, Gen. Rel. Grav. **16** (1984), 465-476.
- [35] D. Sudarski and R.M. Wald, *Mass formulas for stationary Einstein Yang-Mills black holes and a simple proof of two staticity theorems*, Phys. Rev **D47** (1993), 5209-5213, gr-qc /9305023.
- [36] G. Weinstein, *On rotating black holes in equilibrium in general relativity*, Comm. Pure Appl. Math, **43** (1990), 903-948.

MASSACHUSETTS INSTITUTE OF TECHNOLOGY

E-mail address: alexakis@math.mit.edu

UNIVERSITY OF WISCONSIN – MADISON

E-mail address: ionescu@math.wisc.edu

PRINCETON UNIVERSITY

E-mail address: seri@math.princeton.edu