FORMATION OF TRAPPED SURFACES II

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1. INTRODUCTION

2. Geometry of a null hypersurface

As in [?] we consider a region $\mathcal{D} = \mathcal{D}(u_*, \underline{u}_*)$ of a vacuum spacetime (M, g) spanned by a double null foliation generated by the optical functions (u, \underline{u}) increasing towards the future, $0 \leq u \leq u_*$ and $0 \leq \underline{u} \leq \underline{u}_*$. We denote by H_u the outgoing null hypersurfaces generated by the level surfaces of u and by $\underline{H}_{\underline{u}}$ the incoming null hypersurfaces generated level hypersurfaces of \underline{u} . We write $S_{u,\underline{u}} = H_u \cap \underline{H}_{\underline{u}}$ and denote by $H_u^{(\underline{u}_1,\underline{u}_2)}$, and $\underline{H}_{\underline{u}}^{(u_1,u_2)}$ the regions of these null hypersurfaces defined by $\underline{u}_1 \leq \underline{u} \leq \underline{u}_2$ and respectively $u_1 \leq u \leq u_2$. Let $L = -g^{\alpha\beta}\partial_{\alpha}u\partial_{\beta}$, $\underline{L} = -g^{\alpha\beta}\partial_{\alpha}\underline{u}\partial_{\beta}$, \underline{L} be the geodesic vectorfields associated to the two foliations and define,

$$g(L,\underline{L}) := -2\Omega^{-2} = g^{\alpha\beta}\partial_{\alpha}u\partial_{\beta}\underline{u}$$
(1)

Observe that the flat value¹ of Ω is 1. As well known, our space-time slab $\mathcal{D}(u_*, \underline{u}_*)$ is completely determined (for small values of u_*, \underline{u}_*) by data along the null, characteristic, hypersurfaces H_0, \underline{H}_0 corresponding to $\underline{u} = 0$, respectively u = 0. Following [?] we assume that our data is trivial along \underline{H}_0 , i.e. assume that H_0 extends for $\underline{u} < 0$ and the spacetime (M, g) is Minkowskian for $\underline{u} < 0$ and all values of $u \ge 0$. Moreover we can construct our double null foliation such that $\Omega = 1$ along H_0 , i.e.,

$$\Omega(0,\underline{u}) = 1, \qquad 0 \le \underline{u} \le \underline{u}_*. \tag{2}$$

We denote by $r = r(u, \underline{u})$ the radius of the 2-surfaces $S = S(u, \underline{u})$, i.e. $|S(u, \underline{u})| = 4\pi r^2$. We denote by r_0 the value of r for S(0, 0), i.e. $r_0 = r(0, 0)$. For simplicity we assume $r_0 = 1$.

Throughout this paper we work with the normalized null pair (e_3, e_4) ,

 $e_3 = \Omega \underline{L}, \quad e_4 = \Omega L, \qquad g(e_3, e_4) = -2.$

¹Note that our normalization for Ω differ from that of [?]

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Given a 2-surfaces $S(u, \underline{u})$ and $(e_a)_{a=1,2}$ an arbitrary frame tangent to it we define the Ricci coefficients,

$$\Gamma_{(\lambda)(\mu)(\nu)} = g(e_{(\lambda)}, D_{e_{(\nu)}}e_{(\mu)}), \quad \lambda, \mu, \nu = 1, 2, 3, 4$$
(3)

These coefficients are completely determined by the following components,

$$\chi_{ab} = g(D_a e_4, e_b), \qquad \underline{\chi}_{ab} = g(D_a e_3, e_b),$$

$$\eta_a = -\frac{1}{2}g(D_3 e_a, e_4), \qquad \underline{\eta}_a = -\frac{1}{2}g(D_4 e_a, e_3)$$

$$\omega = -\frac{1}{4}g(D_4 e_3, e_4), \qquad \underline{\omega} = -\frac{1}{4}g(D_3 e_4, e_3),$$

$$\zeta_a = \frac{1}{2}g(D_a e_4, e_3)$$
(4)

where $D_a = D_{e_{(a)}}$. We also introduce the null curvature components,

$$\begin{aligned}
\alpha_{ab} &= R(e_a, e_4, e_b, e_4), \quad \underline{\alpha}_{ab} = R(e_a, e_3, e_b, e_3), \\
\beta_a &= \frac{1}{2}R(e_a, e_4, e_3, e_4), \quad \underline{\beta}_a = \frac{1}{2}R(e_a, e_3, e_3, e_4), \\
\rho &= \frac{1}{4}R(Le_4, e_3, e_4, e_3), \quad \sigma = \frac{1}{4}*R(e_4, e_3, e_4, e_3)
\end{aligned}$$
(5)

Here **R* denotes the Hodge dual of *R*. We denote by ∇ the induced covariant derivative operator on $S(u, \underline{u})$ and by ∇_3 , ∇_4 the projections to $S(u, \underline{u})$ of the covariant derivatives D_3 , D_4 . Observe that,

$$\omega = -\frac{1}{2} \nabla_4(\log \Omega), \qquad \underline{\omega} = -\frac{1}{2} \nabla_3(\log \Omega), \qquad (6)$$

$$\eta_a = \zeta_a + \nabla_a(\log \Omega), \qquad \underline{\eta}_a = -\zeta_a + \nabla_a(\log \Omega)$$

We recall the integral formulas² for a scalar function f in \mathcal{D} ,

$$\frac{d}{d\underline{u}} \int_{S(u,\underline{u})} f = \int_{S(u,\underline{u})} \left(\frac{df}{d\underline{u}} + \Omega \operatorname{tr}\chi f\right) = \int_{S(u,\underline{u})} \Omega\left(e_4(f) + \operatorname{tr}\chi f\right)
\frac{d}{du} \int_{S(u,\underline{u})} f = \int_{S(u,\underline{u})} \left(\frac{df}{du} + \Omega \operatorname{tr}\chi f\right) = \int_{S(u,\underline{u})} \Omega\left(e_3(f) + \operatorname{tr}\chi f\right)$$
(7)

In particular,

$$\frac{dr}{d\underline{u}} = \frac{1}{8\pi} \int_{S(u,\underline{u})} \Omega \mathrm{tr}\chi, \qquad \frac{dr}{du} = \frac{1}{8\pi} \int_{S(u,\underline{u})} \Omega \mathrm{tr}\underline{\chi}$$
(8)

We also recall the following commutation formulas: We record below commutation formulae between ∇ and ∇_4 , ∇_3 :

 $^{^{2}}$ see for example Lemma 3.1.3 in [?]

Lemma 2.1. For a scalar function f:

$$[\nabla_4, \nabla]f = \frac{1}{2}(\eta + \underline{\eta})D_4f - \chi \cdot \nabla f \tag{9}$$

$$[\nabla_3, \nabla]f = \frac{1}{2}(\eta + \underline{\eta})D_3f - \underline{\chi} \cdot \nabla f, \qquad (10)$$

For a 1-form tangent to S:

$$\begin{split} [\nabla_4, \nabla_a] U_b &= -\chi_{ac} \nabla_c U_b + \in_{ac} {}^*\beta_b U_c + \frac{1}{2} (\eta_a + \underline{\eta}_a) D_4 U_b \\ &- \chi_{ac} \, \underline{\eta}_b \, U_c + \chi_{ab} \, \underline{\eta} \cdot U \\ [\nabla_3, \nabla_a] U_b &= -\underline{\chi}_{ac} \nabla_c U_b + \in_{ac} {}^*\underline{\beta}_b U_c + \frac{1}{2} (\eta_a + \underline{\eta}_a) D_3 U_b \\ &- \underline{\chi}_{ac} \eta_b \, U_c + \underline{\chi}_{ab} \, \eta \cdot U \end{split}$$

In particular,

$$\begin{bmatrix} \nabla_4, \, div \ \end{bmatrix} U = -\frac{1}{2} tr \chi \, div \, U - \hat{\chi} \cdot \nabla U - \beta \cdot U + \frac{1}{2} (\eta + \underline{\eta}) \cdot \nabla_4 U - \underline{\eta} \cdot \hat{\chi} \cdot U \\ \begin{bmatrix} \nabla_3, \, div \ \end{bmatrix} U = -\frac{1}{2} tr \underline{\chi} \, div \, U - \underline{\hat{\chi}} \cdot \nabla U + \underline{\beta} \cdot U + \frac{1}{2} (\eta + \underline{\eta}) \cdot \nabla_3 U - \eta \cdot \underline{\hat{\chi}} \cdot U$$

2.2. Christodoulou's heuristic argument. We recall here the assumptions needed in Christodoulou's heuristic argument for the formation of a trapped surface as described in [?]. As mentioned above we assume that our data is trivial along \underline{H}_0 , i.e. assume that H_0 extends for $\underline{u} < 0$ and the spacetime (M, g) is Minkowskian for $\underline{u} < 0$ and all values of $u \ge 0$. We introduce a small parameter $\delta > 0$ and restrict the values of \underline{u} to $0 \le \underline{u} \le \delta$, i.e. $\underline{u}_* = \delta$.

Main Assumptions. We assume that throughout $\mathcal{D} = \mathcal{D}(u_*, \underline{u}_*)$ we have the following estimates:

MA1. For small δ , Ω is comparable with its standard value in flat space, i.e.

$$\Omega = 1 + O(\delta^{1/2}).$$

MA2. The Ricci coefficients $\chi, \omega, \eta, \chi, \underline{\omega}$ verify

$$|\hat{\chi},\omega| = O(\delta^{-1/2}), \qquad |\mathrm{tr}\chi,\eta| = O(1), \qquad |\underline{\hat{\chi}},\mathrm{tr}\underline{\chi} + \frac{2}{r},\,\underline{\omega}| = O(\delta^{1/2}).$$

MA3. Also for some c > 0,

$$|\nabla \eta| = O(\delta^{-1/2+c}).$$

Note that in view of (8) we also have,

$$\frac{dr}{du} = -1 + O(r\delta^{1/2}), \qquad \frac{dr}{d\underline{u}} = O(r)$$
(11)

Thus, for δ sufficiently small, we infer that r is decreasing along the incoming null hypersurfaces and remains bounded, $0 \le r \le r_0 + 1 = 2$, in \mathcal{D} .

Christodoulou's argument for the formation of trapped surfaces in [?] rests on the equations,

$$\nabla_4 \operatorname{tr} \chi + \frac{1}{2} (\operatorname{tr} \chi)^2 = -|\hat{\chi}|^2 - \frac{1}{2} (\operatorname{tr} \chi)^2 - 2\omega \operatorname{tr} \chi$$
$$\nabla_3 \hat{\chi} + \frac{1}{2} \operatorname{tr} \underline{\chi} \hat{\chi} = \nabla \widehat{\otimes} \eta + 2\underline{\omega} \hat{\chi} - \frac{1}{2} \operatorname{tr} \chi \underline{\hat{\chi}} + \eta \widehat{\otimes} \eta$$

In view of our Ricci coefficients assumptions we can rewrite,

$$\nabla_4 \operatorname{tr} \chi = -|\hat{\chi}|^2 + O(\delta^{-1/2})$$
$$\nabla_3 \hat{\chi} + \frac{1}{2} \operatorname{tr} \underline{\chi} \hat{\chi} = O(\delta^{-1/2+c})$$

Multiplying the second equation by $\hat{\chi}$,

$$\nabla_4 |\hat{\chi}|^2 + \operatorname{tr}\underline{\chi} |\hat{\chi}|^2 = O(\delta^{-1+c})$$

Using also our assumptions for u, \underline{u}, Ω we deduce,

$$\frac{d}{d\underline{u}}\mathrm{tr}\chi = -|\hat{\chi}|^2 + O(\delta^{-1/2})$$
(12)

$$\frac{d}{du}|\hat{\chi}|^2 + \mathrm{tr}\underline{\chi}|\hat{\chi}|^2 = O(\delta^{-1+c})$$
(13)

Integrating (12) we obtain,

$$\operatorname{tr}\chi(u,\underline{u}) = \frac{2}{r(u,0)} - \int_0^{\underline{u}} |\hat{\chi}|(u,\underline{u}')^2 d\underline{u}' + O(\delta^{1/2})$$
(14)

In view of our assumptions for ${\rm tr}\underline{\chi}$ and $\frac{dr}{du}$

$$\begin{aligned} \frac{d}{du}(r^2|\hat{\chi}|^2) &= r^2 \frac{d}{du}|\hat{\chi}|^2 + 2r\frac{dr}{du}|\hat{\chi}|^2 = r^2 \left[-\operatorname{tr}\underline{\chi}|\hat{\chi}|^2 + O(\delta^{-1+c})\right] + 2r\left[-1 + O(r\delta^c)\right]|\hat{\chi}|^2 \\ &= r^2 O(\delta^{-1+c}). \end{aligned}$$

Therefore,

$$r^2|\hat{\chi}|^2(u,\underline{u}) = r^2(0,\underline{u})|\hat{\chi}|^2(0,\underline{u}) + r^2O(\delta^{-1+c})$$

As in [] we freely prescribe $\hat{\chi}$ along the initial hypersurface $H_0^{(0,\delta)},$ i.e.

$$\hat{\chi}(0,\underline{u}) = \hat{\chi}_0(\underline{u}) = O(\delta^{-1/2}) \tag{15}$$

for some traceless 2 tensor $\hat{\chi}_0$. We deduce, (need $0 < c \leq \frac{1}{2}$),

$$|\hat{\chi}|^2(u,\underline{u}) = \frac{r^2(0,\underline{u})}{r^2(u,\underline{u})}|\hat{\chi}_0|^2(\underline{u}) + O(\delta^{-1+c})$$

or, since $|\underline{u}| \leq \delta$ and $r(u, \underline{u}) = r_0 + \underline{u} - u + O(\delta^c)$,

$$|\hat{\chi}|^2(u,\underline{u}) = \frac{r_0^2}{r^2(u,0)} |\hat{\chi}_0|^2(\underline{u}) + O(\delta^{-1+c})$$

Thus, returning to (14),

$$\operatorname{tr}\chi(u,\delta) = \frac{2}{r(u,0)} - \frac{r_0^2}{r^2(u,0)} \int_0^{\underline{u}} |\hat{\chi}_0|^2(\underline{u}')d\underline{u}' + O(\delta^c)$$

$$= \frac{2}{r(u,0)} - \frac{r_0^2}{r^2(u,0)} \int_0^{\underline{u}} |\hat{\chi}_0|^2(\underline{u}')d\underline{u}' + O(\delta^c)$$

We have thus proved the following.

Proposition 2.3. Under the assumptions MA1- MA3 we have, for sufficiently small $\delta > 0$ and fixed c > 0,

$$tr\chi(u,\delta) = \frac{2}{r(u,0)} - \frac{r_0^2}{r^2(u,0)} \int_0^\delta |\hat{\chi}_0|^2(\underline{u}')d\underline{u}' + O(\delta^c)$$
(16)

Since $r(u, \underline{u}) = r_0 - u + \underline{u} + O(\delta^c)$ formula (16) can also be written in the form,

$$tr\chi(u,\delta) = \frac{2}{r(u,\delta)} - \frac{r_0^2}{r^2(u,\delta)} \int_0^\delta |\hat{\chi}_0|^2(\underline{u}')d\underline{u}' + O(\delta^c)$$
(17)

Corollary 2.4. The necessary condition to have $tr\chi(u, \underline{u} = \delta) < 0$

$$\frac{2r(u,0)}{r_0^2} < \int_0^\delta |\hat{\chi}_0|^2 + O(\delta^c) \tag{18}$$

for sufficiently small $\delta > 0$. Since $r(u, 0) = r_0 - u + O(\delta^c)$, condition (18) can also be written in the form,

$$\frac{2(r_0 - u)}{r_0^2} < \int_0^\delta |\hat{\chi}_0|^2 + O(\delta^c) \tag{19}$$

3. Change of foliation

3.1. Main transformation formula. To improve on (18) we plan to change the u foliation along $\underline{u} = \delta$ and compute the corresponding incoming expansion $\operatorname{tr} \chi'$. More precisely, given the foliation induced by u, we look for a new foliation $v = v(u, \omega)$ defined by the equations

$$\nabla_{u}v = e^{f}, \qquad v|_{S_{0}} = u|_{S_{0}} = 0
\nabla_{u}f = 0, \qquad f|_{S_{*}} = f_{0}$$
(20)

with f_0 a function on $S_0 = S(0, \delta)$ to be carefully chosen later.

NOTE CHANGE: BEFORE WE HAD $\nabla_3 v = e^f$ WHICH LEADS TO THE UNDESIRED TERM $e^- f \nabla \log \Omega$ IN THE EQUATION FOR G.

We introduce the new null frame adapted to the v-foliation,

$$e'_{3} = e_{3}, \qquad e'_{a} = e_{a} - e^{-f}\Omega e_{a}(v)e_{3}, \qquad e'_{4} = e_{4} - 2e^{-f}\Omega e_{a}(v)e_{a} + e^{-2f}\Omega^{2}|\nabla v|^{2}e_{3}$$
 (21)

Indeed since $\nabla_u = \Omega \nabla_3$ we have, $e'_a(v) = e_a(v) - e^{-f} \Omega e_a(v) e_3(v) = e_a(v) - e^{-f} e_a(v) \nabla_u(v) = 0$. Also, ince e_3 is orthogonal to any vector tangent to \underline{H} we easily check that

$$g(e'_a, e'_b) = g(e_a, e_b) = \delta_{ab}, \quad g(e'_4, e'_a) = g(e'_4, e'_4) = 0, \quad g(e'_3, e'_4) = -2.$$

We prove the following.

Lemma 3.2. The new incoming expansion $tr\chi'$ verifies the transformation formula,

$$tr\chi' = tr\chi - 2e^{f} div \ (e^{-f}F) - tr\underline{\chi}|F|^{2} - 4\underline{\hat{\chi}}_{bc}F^{b}F^{c} - 2(\eta + \zeta) \cdot F$$

$$\tag{22}$$

where $F_a = e^{-f}\Omega \nabla_a v$ and $tr\chi, \zeta, tr\underline{\chi}, \underline{\hat{\chi}}, \underline{\omega}$ are connection coefficients for the given double null foliation (u, \underline{u}) .

Proof. We have,

$$\chi'(e'_a, e'_b) := g(D'_a e'_4, e'_b) = g(D_a e'_4, e'_b) - e^{-f} \Omega^{-1} e_a(v) g(D_3 e'_4, e'_b)$$

Now, writing $e'_4 = e_4 - 2F + |F|^2 e_3$ with $F = F_c e_c$ and $e'_b = e_b - F_b e_3$,

$$g(D_{a}e'_{4}, e'_{b}) = g(D_{a}(e_{4} - 2F + |F|^{2}e_{3}), e_{b} - F_{b}e_{3})$$

$$= \chi(e_{a}, e_{b}) - 2F_{b}\zeta_{a} - 2\nabla_{a}F_{b} + 2F_{b}g(D_{a}F, e_{3}) + |F|^{2}g(D_{a}e_{3}, e_{b} - F_{b}e_{3})$$

$$= \chi_{ab} - 2\zeta_{a}F_{b} - 2\nabla_{a}F_{b} - 2F_{b}\underline{\chi}(F, e_{a}) + |F|^{2}\underline{\chi}_{ab}$$

$$= \chi_{ab} - 2\zeta_{a}F_{b} - 2\nabla_{a}F_{b} - 2F_{b}F_{c}\underline{\chi}_{ac} + |F|^{2}\underline{\chi}_{ab}$$

Also,

$$g(D_3e'_4, e'_b) = g(D_3(e_4 - 2F + |F|^2 e_3), e_b - F_b e_3)$$

= $g(D_3e_4, e_b) - F_b g(D_3e_4, e_3) - 2\nabla_3 F_b$
= $2\eta_b + 4F_b \underline{\omega} - 2\nabla_3 F_b$

Hence,

$$\chi_{ab}' = \chi_{ab} - 2\zeta_b F_a - 2\nabla_a F_b - 2F_b \underline{\chi}(F, e_b) + |F|^2 \underline{\chi}_{ab} - F_a (2\eta_b + 4F_b \underline{\omega} - 2\nabla_3 F_b)$$

$$= \chi_{ab} - 2\nabla_a F_b + 2F_a \nabla_3 F_b - 2\zeta_b F_a - 2F_a \eta_b + (|F|^2 \underline{\chi}_{ab} - 2F_b F_c \underline{\chi}_{ac}) - 4\underline{\omega} F_a F_b$$

By symmetry in a, b we deduce the formula,

$$\chi'_{ab} = \chi_{ab} - (\nabla_a F_b + \nabla_b F_a) + \nabla_3 (F_a F_b) - (\zeta_b + \eta_b) F_a + (\zeta_a + \eta_a) F_b$$

$$+ (|F|^2 \underline{\chi}_{ab} - F_b F_c \underline{\chi}_{ac} - F_a F_c \underline{\chi}_{bc}) - 4\underline{\omega} F_a F_b$$
(23)

and, taking the trace,

$$\operatorname{tr}\chi' = \operatorname{tr}\chi - 2\operatorname{div} F + \nabla_3 |F|^2 - 2(\eta + \zeta) \cdot F + (|F|^2 \operatorname{tr}\underline{\chi} - 2\underline{\chi}_{bc} F^b F^c) - 4\underline{\omega} |F|^2$$
$$= \operatorname{tr}\chi - 2\operatorname{div} F + \nabla_3 |F|^2 - 2(\eta + \zeta) \cdot F - 2\underline{\hat{\chi}}_{bc} F^b F^c - 4\underline{\omega} |F|^2$$

We next calculate $\nabla_3 |F|^2$ using (20) and the commutation formula

$$[\nabla_3, \nabla]h = (\nabla \log \Omega)\nabla_3 h - \underline{\chi} \cdot \nabla h$$

or,

$$[\nabla_u, \nabla]h = -\Omega \chi \cdot \nabla h$$

Since $\nabla_u f = 0$ and $F = \Omega^{-1} e^f \nabla v$ we deduce, $\nabla_v F = -\nabla_v (\Omega e^{-f} \nabla v)$

$$\nabla_{u}F_{a} = \nabla_{u}(\Omega e^{-f}\nabla v) = \Omega e^{-f}\nabla_{u}\nabla v + \nabla_{u}\Omega e^{-f}\nabla v$$

$$= \Omega e^{-f}\nabla\nabla_{u}v - \Omega e^{-f}\Omega\underline{\chi}\cdot\nabla v + \nabla_{u}\Omega e^{-f}\nabla v$$

$$= \Omega\nabla f - \Omega^{2}e^{-f}\underline{\chi}\cdot\nabla v + \nabla_{u}\Omega e^{-f}\nabla v$$

$$= \Omega\nabla f - \Omega\underline{\chi}\cdot F - \Omega^{-1}\nabla_{u}\Omega F$$

or,

$$\nabla_3 F = \nabla F - \underline{\chi} \cdot F - \Omega^{-1} \nabla_3 \Omega F$$
$$= \nabla F - \underline{\chi} \cdot F + 2\underline{\omega} F$$

i.e.,

$$\nabla_3 F + \frac{1}{2} \text{tr} \underline{\chi} F = \nabla f - \underline{\hat{\chi}} \cdot F + 2\underline{\omega} F$$
(24)

from which,

$$\nabla_3 |F|^2 = -\mathrm{tr}\underline{\chi}|F|^2 + 2F \cdot \nabla f - 2\underline{\hat{\chi}}_{bc} F^b F^c + 4\underline{\omega}|F|^2$$

Therefore,

$$\operatorname{tr} \chi' = \operatorname{tr} \chi - 2\operatorname{div} F - 2(\eta + \zeta) \cdot F - 2\underline{\hat{\chi}}_{bc} F^b F^c - 4\underline{\omega} |F|^2 - \operatorname{tr} \underline{\chi} |F|^2 + 2F \cdot \nabla f - 2\underline{\hat{\chi}}_{bc} F^b F^c + 4\underline{\omega} |F|^2 = \operatorname{tr} \chi - 2\operatorname{div} F + 2F \cdot \nabla f - \operatorname{tr} \underline{\chi} |F|^2 - 4\underline{\hat{\chi}}_{bc} F^b F^c - 2(\eta + \zeta) \cdot F = \operatorname{tr} \chi - 2e^f \operatorname{div} (e^{-f} F) + 2F \cdot \nabla f - \operatorname{tr} \underline{\chi} |F|^2 - 4\underline{\hat{\chi}}_{bc} F^b F^c - 2(\eta + \zeta) \cdot F$$

as desired.

Remark. Note that we can eliminate ζ from the formula (22) by writing the term $2(\eta + \zeta) \cdot F = 4\eta \cdot F - 2\Omega^{-1} \nabla \Omega \cdot F$ Thus,

$$\operatorname{tr}\chi' = \operatorname{tr}\chi - 2e^{f}\Omega\operatorname{div}\left(\Omega^{-1}e^{-f}F\right) - \operatorname{tr}\underline{\chi}|F|^{2} - 4\underline{\hat{\chi}}_{bc}F^{b}F^{c} - 4\eta \cdot F$$
(25)

To understand how $\text{tr}\chi'$ differs from $\text{tr}\chi$ it only remains to derive a transport equation for div G with $G = e^{-f}F$.

3.3. Transport equation for div G. In view of (24) and $e_3(f) = 0$ we have for $G := e^{-f}F$.

$$\nabla_3 G + \frac{1}{2} \text{tr} \underline{\chi} G = e^{-f} \nabla f - \underline{\hat{\chi}} \cdot G + 2\underline{\omega} G$$
(26)

To derive a transport equation for div G we make us of the following

Lemma 3.4. Assume that the S-tangent vectorfield V verifies an equation of the form,

$$\nabla_3 V + \frac{1}{2} tr \underline{\chi} V = -\underline{\hat{\chi}} \cdot V + W$$

Then,

$$\nabla_{3}(\operatorname{div} V) + \frac{1}{2}\operatorname{tr}\underline{\chi}\operatorname{div} V = \operatorname{div} W + W \cdot \nabla(\log\Omega) - 2\underline{\hat{\chi}} \cdot \nabla V - \nabla\operatorname{tr}\underline{\chi} \cdot V + \left(\operatorname{tr}\underline{\chi}\zeta - 2\underline{\hat{\chi}}\zeta - 2\underline{\hat{\chi}} \cdot \nabla(\log\Omega)\right) \cdot V$$

Proof.

$$\nabla_{3}(\operatorname{div} V) + \frac{1}{2}\operatorname{tr}\underline{\chi}\operatorname{div} V = \operatorname{div}\left(-\underline{\hat{\chi}}\cdot V + W\right) - \frac{1}{2}\nabla\operatorname{tr}\underline{\chi}\cdot V + [\nabla_{3}, \operatorname{div}]V$$

We make use of the commutation formula, see lemma 2.1,

$$[\nabla_3, \operatorname{div}]V = -\frac{1}{2} \operatorname{tr} \underline{\chi} \operatorname{div} V - \underline{\hat{\chi}} \cdot \nabla V + \left(\underline{\beta} - \eta \cdot \underline{\hat{\chi}}\right) \cdot V + \nabla(\log \Omega) \cdot \nabla_3 V$$

Therefore,

$$\begin{aligned} \nabla_{3}(\operatorname{div} V) + \operatorname{tr}\underline{\chi}\operatorname{div} V &= \operatorname{div} \left(-\underline{\hat{\chi}} \cdot V + W \right) - \underline{\hat{\chi}} \cdot \nabla V + \left(\underline{\beta} - \frac{1}{2} \nabla \operatorname{tr}\underline{\chi} - \eta \cdot \underline{\hat{\chi}} \right) \cdot V \\ &+ \nabla(\log \Omega) \cdot \nabla_{3} V \\ &= \operatorname{div} W - 2\underline{\hat{\chi}} \cdot \nabla V + \left(-\operatorname{div} \underline{\hat{\chi}} + \underline{\beta} - \frac{1}{2} \nabla \operatorname{tr}\underline{\chi} - \eta \cdot \underline{\hat{\chi}} \right) \cdot V \\ &+ \nabla(\log \Omega) \cdot \left(-\frac{1}{2} \operatorname{tr}\underline{\chi} V - \underline{\hat{\chi}} \cdot V + W \right) \\ &= \operatorname{div} W + W \cdot \nabla(\log \Omega) \right) - 2\underline{\hat{\chi}} \cdot \nabla V \\ &+ \left(-\operatorname{div} \underline{\hat{\chi}} - \frac{1}{2} \nabla \operatorname{tr}\underline{\chi} + \underline{\beta} - \eta \cdot \underline{\hat{\chi}} - \frac{1}{2} \operatorname{tr}\underline{\chi} \nabla(\log \Omega) - \underline{\hat{\chi}} \cdot \nabla(\log \Omega) \right) \cdot V \end{aligned}$$

Using the Codazzi equation, div $\underline{\hat{\chi}} = \frac{1}{2}\nabla \text{tr}\underline{\chi} + \underline{\beta} + \zeta \cdot (\underline{\hat{\chi}} - \frac{1}{2}\text{tr}\underline{\chi})$ as well as $\eta = \zeta + \nabla(\log \Omega)$ we derive,

$$\begin{aligned} -\operatorname{div} \, \underline{\hat{\chi}} &- \frac{1}{2} \nabla \operatorname{tr} \underline{\chi} + \underline{\beta} - \eta \cdot \underline{\hat{\chi}} - \frac{1}{2} \operatorname{tr} \underline{\chi} \nabla (\log \Omega) - \underline{\hat{\chi}} \cdot \nabla (\log \Omega)) \\ &= -\nabla \operatorname{tr} \underline{\chi} - \zeta \cdot (\underline{\hat{\chi}} - \frac{1}{2} \operatorname{tr} \underline{\chi} - \eta \cdot \underline{\hat{\chi}} - \frac{1}{2} \operatorname{tr} \underline{\chi} \nabla (\log \Omega) - \underline{\hat{\chi}} \cdot \nabla (\log \Omega)) \\ &= -\nabla \operatorname{tr} \underline{\chi} - \underline{\hat{\chi}} \cdot (\zeta + \eta + \nabla (\log \Omega)) + \frac{1}{2} \operatorname{tr} \underline{\chi} (\zeta + \nabla (\log \Omega))) \\ &= -\nabla \operatorname{tr} \underline{\chi} - 2\underline{\hat{\chi}} \left(\zeta + \nabla (\log \Omega) \right) + \operatorname{tr} \underline{\chi} \eta \end{aligned}$$

Hence,

$$\nabla_{3}(\operatorname{div} V) + \operatorname{tr}\underline{\chi}\operatorname{div} V = \operatorname{div} W + W \cdot \nabla(\log \Omega) - 2\underline{\hat{\chi}} \cdot \nabla V - \nabla \operatorname{tr}\underline{\chi} \cdot V + \left(\operatorname{tr}\chi\eta - 2\hat{\chi}\zeta - 2\hat{\chi} \cdot \nabla(\log \Omega)\right) \cdot V$$

as desired.

Applying the lemma to equation (26) we derive,

$$\nabla_{3}(\operatorname{div} G) + \operatorname{tr}\underline{\chi}\operatorname{div} G = \operatorname{div} W + W \cdot \nabla(\log \Omega) - 2\underline{\hat{\chi}} \cdot \nabla G - \nabla \operatorname{tr}\underline{\chi} \cdot G + \left(\operatorname{tr}\underline{\chi}\eta - 2\underline{\hat{\chi}} \zeta - 2\underline{\hat{\chi}} \cdot \nabla(\log \Omega)\right) \cdot G$$

with $W = e^{-f} \nabla f + 2\underline{\omega} G$. Thus,

$$\operatorname{div} W + W \cdot \nabla(\log \Omega) = \operatorname{div} (e^{-f} \nabla f) + e^{-f} \nabla(\log \Omega) \cdot \nabla f + 2\operatorname{div} (\underline{\omega}G) + 2\nabla(\log \Omega) \underline{\omega}G$$

We deduce the following transport equation for div G,

$$\nabla_3(\operatorname{div} G) + \operatorname{tr}\underline{\chi}\operatorname{div} G = \operatorname{div} (e^{-f}\nabla f) + 2\underline{\omega}\operatorname{div} G + \operatorname{Err}_1$$
(27)

with error term,

$$\operatorname{Err}_{1} = e^{-f} \nabla (\log \Omega) \cdot \nabla f - 2\underline{\hat{\chi}} \cdot \nabla G - \nabla \operatorname{tr} \underline{\chi} \cdot G + \left(\operatorname{tr} \underline{\chi} \eta - 2\underline{\hat{\chi}} \zeta - 2\underline{\hat{\chi}} \cdot \nabla (\log \Omega) + 2\nabla \underline{\omega} + 2\underline{\omega} \nabla \log \Omega \right) \cdot G$$

In the same manner we deduce a transport equation for the principal term div $(e^{-f}\nabla f)$ on the right hand side of (27). Indeed, since $\nabla_3 f = 0$ we derive,

$$\nabla_3(\nabla f) + \frac{1}{2} \operatorname{tr} \underline{\chi} \nabla f = -\underline{\hat{\chi}} \nabla f$$

Therefore, using lemma 3.4,

$$\nabla_{3} \operatorname{div} (e^{-f} \nabla f) + \operatorname{tr} \underline{\chi} \operatorname{div} (e^{-f} \nabla f) = -2\underline{\hat{\chi}} \cdot \nabla (e^{-f} \nabla f) - \nabla \operatorname{tr} \underline{\chi} \cdot e^{-f} \nabla f + \left(\operatorname{tr} \underline{\chi} \eta - 2\underline{\hat{\chi}} \zeta - 2\underline{\hat{\chi}} \cdot \nabla (\log \Omega) \right) \cdot e^{-f} \nabla f.$$

We summarize the results of this subsection in the following proposition. We summarize the results of this subsection in the following proposition.

Proposition 3.5. Let v, f be defined according to (20), $F = \Omega^{-1}e^{-f}\nabla v$ and $G = e^{-f}F$. The trace of the null second fundamental form χ' , relative to the new frame (21), is given by the formula (22), *i.e.*,

$$tr\chi' = tr\chi - 2e^f div \ G - tr\underline{\chi}|F|^2 - 4\underline{\hat{\chi}}_{bc}F^bF^c - 2(\eta + \zeta) \cdot F$$
(28)

F verifies the transport equation

$$\nabla_3 F + \frac{1}{2} tr \underline{\chi} F = \nabla f - \underline{\hat{\chi}} \cdot F + 2\underline{\omega} F$$
⁽²⁹⁾

and div G verifies,

$$\nabla_3(\operatorname{div} G) + \operatorname{tr}\underline{\chi}\operatorname{div} G = \operatorname{div} (e^{-f}\nabla f) + \operatorname{Err}_1$$
(30)

where,

$$Err_{1} = e^{-f}\nabla(\log\Omega) \cdot \nabla f - 2\underline{\hat{\chi}} \cdot \nabla G$$

$$- \nabla tr\underline{\chi} \cdot G + \left(tr\underline{\chi}\zeta - 2\underline{\hat{\chi}}\zeta - 2\underline{\hat{\chi}} \cdot \nabla(\log\Omega) + 2\nabla\underline{\omega} + 2\underline{\omega}\nabla\log\Omega\right) \cdot G$$

Also,

$$\nabla_3 f = 0 \tag{31}$$

$$\nabla_3(\nabla f) + \frac{1}{2} tr \underline{\chi} \nabla f = -\underline{\hat{\chi}} \nabla f \qquad (32)$$

$$\nabla_3[e^f div \ (e^{-f} \nabla f)] + tr \underline{\chi}[e^f div \ (e^{-f} \nabla f)] = Err_2$$
(33)

with error term,

$$Err_2 = -2\underline{\hat{\chi}} \cdot \left(\nabla^2 f - \nabla f \nabla f\right) - \nabla tr\underline{\chi} \cdot \nabla f + \left(tr\underline{\chi}\eta - 2\underline{\hat{\chi}}\zeta - 2\underline{\hat{\chi}} \cdot \nabla(\log\Omega)\right) \cdot \nabla f$$

3.6. Additional assumptions. To proceed we need to make stronger assumptions than those of section 2.2. More precisely, we need, in addition MA1 -MA3 the following,

MA2-S. The Ricci coefficients $\eta, \eta, \nabla \log \Omega$ verify the stronger assumptions,

$$|\eta|, |\eta| = O(\delta^c)$$

MA3-S For a fixed c > 0,

$$\nabla \eta|, |\nabla \underline{\eta}| = O(\delta^{-1/2+c}), \qquad |\nabla \underline{\chi}|, |\underline{\beta}| = O(\delta^c)$$

As a corollary of proposition 3.5 and these assumptions we deduce first,

$$\operatorname{tr}\chi' = \operatorname{tr}\chi - 2e^{f}\operatorname{div}(G) + \frac{2}{r}|F|^{2} + |F|^{2}O(\delta^{c})$$
 (34)

From the equation (32) $\nabla_3(\nabla f) + \frac{1}{2} \text{tr} \underline{\chi} \nabla f = -\underline{\hat{\chi}} \nabla f$ we deduce,

$$\nabla_u(r|\nabla f|) = O(\delta^{1/2}) \, r|\nabla f|$$

Therefore,

$$r|\nabla f| = r_0 |\nabla f_0| (1 + O(\delta^{1/2}))$$
(35)

We can also deduce in the same manner an estimate for $r^2 |\nabla^2 f|$. Indeed, differentiating (32) and commuting ∇ with ∇_3 , according to lemma 2.1 we deduce,

$$\nabla_3(\nabla^2 f) + \operatorname{tr} \underline{\chi} \nabla^2 f = -\underline{\hat{\chi}} \nabla^2 f + O(\delta^c)(1 + \frac{1}{r}) |\nabla f|$$

Note that the $\frac{1}{r}$ term is due to the contribution of the term $\operatorname{tr} \underline{\chi} \eta \cdot \nabla f$ which appear in the commutation lemma. Hence, since $r \leq r_0 \leq r$ we deduce using (35),

$$\begin{aligned} \nabla_u (r^2 |\nabla^2 f)| &= O(\delta^{1/2}) r^2 |\nabla^2 f| + O(\delta^c) (1 + \frac{1}{r}) r^2 |\nabla f| \\ &= O(\delta^{1/2}) r^2 |\nabla^2 f| + O(r\delta^c) r_0 |\nabla f_0| \end{aligned}$$

and we infer that,

$$r^{2}|\nabla^{2}f| \lesssim C(r_{0}^{2}|\nabla^{2}f_{0}| + O(\delta^{c})r_{0}|\nabla f_{0}|)$$

$$(36)$$

Proceeding in the same manner with (33) we derive, for $H = e^f \text{div} (e^{-f} \nabla f)$

$$\nabla_3 H + \operatorname{tr} \underline{\chi} H = O(\delta^{1/2}) \left(|\nabla^2 f| + |\nabla f|^2 \right) + O(\delta^c) (1 + \frac{1}{r}) |\nabla f|$$

We deduce,

$$\nabla_u(r^2 H) = O(\delta^{1/2})r^2 |\nabla^2 f| + O(\delta^c)r |\nabla f|$$

= $O(\delta^c) [r_0^2 |\nabla^2 f_0| + r_0 |\nabla f_0|]$

Hence,

$$r^{2}H = r_{0}^{2}H_{0} + O(\delta^{c}) \left[r_{0}^{2} |\nabla^{2}f_{0}| + r_{0} |\nabla f_{0}| \right]$$

or,

$$r^{2} \operatorname{div} (e^{-f}) \nabla f = -r_{0}^{2} \Delta(e^{-f_{0}}) + O(\delta^{c}) \left[r_{0}^{2} |\nabla^{2} f_{0}| + r_{0} |\nabla f_{0}| \right] e^{-f_{0}}$$
(37)

Now, from equation (38),

$$\nabla_3|F| + \frac{1}{2} \operatorname{tr} \underline{\chi}|F| = |\nabla f| + O(\delta^{1/2})F$$

we deduce,

$$\nabla_u(r|F|) = O(\delta^{1/2})r|F| + r|\nabla f| = O(\delta^{1/2})r|F| + r_0|\nabla f_0|(1 + O(\delta^c))$$

and therefore, since $F_0 = e^{-f_0} |\nabla v_0| = 0$,

$$r|F| = ur_0 |\nabla f_0| \left(1 + O(\delta^c)\right) \tag{38}$$

with C > 0 independent of δ or f_0 .

We next calculate ∇F . Using the commutation lemma 2.1 we deduce,

$$\nabla_3 |\nabla F| + \operatorname{tr} \underline{\chi} |\nabla F| \leq |\nabla^2 f| + O(\delta^{1/2}) |\nabla F| + O(\delta^c) |F|$$

Thus, according to (36)

$$\begin{aligned} \nabla_u(r^2 |\nabla F|) &\leq r^2 |\nabla^2 f| + O(\delta^{1/2}) r^2 |\nabla F| + O(\delta^c) r^2 |F| \\ &\leq O(\delta^{1/2}) r^2 |\nabla F| + C(r_0^2 |\nabla^2 f_0| + O(\delta^c) r_0 |\nabla f_0|) + O(\delta^c) r r_0 |\nabla f_0| \end{aligned}$$

We deduce,

$$r^{2}|\nabla F| \leq C\left(r_{0}^{2}|\nabla^{2}f_{0}| + O(\delta^{c})r_{0}|\nabla f_{0}|\right)$$

$$(39)$$

Since $G = e^{-f}F$ we also deduce,

$$r^{2}|\nabla G| \leq C(r_{0}^{2}|\nabla^{2}f_{0}| + O(\delta^{c})r_{0}|\nabla f_{0}|)e^{-f_{0}}$$
(40)

Next we calculate div G from (30) which we write in the form,

$$\nabla_3(\operatorname{div} G) + \operatorname{tr}\underline{\chi}\operatorname{div} G = \operatorname{div} (e^{-f}\nabla f) + O(\delta^c)I_0e^{-f_0}$$
$$I_0 := \left(r_0^2|\nabla^2 f_0| + O(\delta^c)r_0|\nabla f_0|\right).$$

Hence, making use of (37)

$$\begin{aligned} \nabla_u(r^2 \text{div} \ G) &= r^2 \text{div} \ (e^{-f} \nabla f) + O(\delta^c) r^2 I_0 e^{-f_0} \\ &= -r_0^2 \Delta(e^{-f_0}) + O(\delta^c) I_0 + O(\delta^c) r^2 I_0 e^{-f_0} \end{aligned}$$

Therefore,

$$r^{2} \text{div } G = -ur_{0}^{2}\Delta(e^{-f_{0}}) + O(\delta^{c})I_{0}$$
(41)

Finally, going back to (34), and formula (38) for |F|,

$$\operatorname{tr}\chi' = \operatorname{tr}\chi - 2e^{f}\operatorname{div}(G) + \frac{2}{r}|F|^{2} + |F|^{2}O(\delta^{c})$$

$$= \operatorname{tr}\chi + 2ur^{-2}r_{0}^{2}e^{f_{0}}\Delta(e^{-f_{0}}) + O(r^{-2}\delta^{c})I_{0} + \frac{2}{r^{3}}u^{2}r_{0}^{2}|\nabla f_{0}|^{2}(1 + O(\delta^{c}))$$

$$= \operatorname{tr}\chi + 2ur^{-2}r_{0}^{2}(-\Delta f_{0} + |\nabla f_{0}|^{2}) + \frac{2}{r^{3}}u^{2}r_{0}^{2}|\nabla f_{0}|^{2}(1 + O(\delta^{c})) + O(r^{-2}\delta^{c})I_{0}$$

$$= \operatorname{tr}\chi + \frac{2ur_{0}^{2}}{r^{2}}\left(-\Delta f_{0} + \left[1 + u/r\left(1 + O(\delta^{c})\right]|\nabla f_{0}|^{2}\right]\right) + O(r^{-2}\delta^{c})I_{0}$$

We summarize the result in the following proposition.

Proposition 3.7. Assume that MA1-MA3 and MA2-S, MA3-S are verified in the space-time region $\mathcal{D}(u_*, \delta)$ and f, v defined according to (20) The the expansion $tr\chi'$ of the v foliation verifies, for all $0 \le u \le u_*$ and $0 \le \underline{u} \le \delta$, with $I_0 = (r_0^2 |\nabla^2 f_0| + O(\delta^c) r_0 |\nabla f_0|)$ verifies,

$$tr\chi' = tr\chi + \frac{2ur_0^2}{r^2} \left(-\Delta f_0 + \left[1 + u/r \left(1 + O(\delta^c) \right] |\nabla f_0|^2 \right] \right) + O(r^{-2}\delta^c) I_0$$
(42)

In particular, if $\delta > 0$ is sufficiently small,

$$tr\chi' \leq tr\chi + \frac{2ur_0^2}{r^2} \left[-\Delta f_0 + \left(1 + \frac{u}{r}\right) \right] |\nabla f_0|^2 + O(r^{-2}\delta^c) I_0$$
(43)

3.8. Main equation. We now combine the results of propositions 2.3 and 3.7. For simplicity we shall also assume that $r_0 = 1$. According to proposition 2.3 we have,

$$\operatorname{tr}\chi(u,\delta) = \frac{2}{r(u,\delta)} - \frac{1}{r^2(u,\delta)} \int_0^\delta |\hat{\chi}_0|^2(\underline{u}')d\underline{u}' + O(\delta^c)$$

Thus, inserting in (42)

$$\operatorname{tr}\chi'(u,\delta) \leq \frac{2}{r} + \frac{2u}{r^2} \left(-\Delta f_0 + \left[1 + u/r \left(1 + O(\delta^c) \right] |\nabla f_0|^2 \right] \right) - \frac{1}{r^2} M_0 + O(r^{-2}\delta^c) I_0$$

where $r = r(u, \delta)$ and

$$M_0 = \int_0^\delta |\hat{\chi}_0|^2(\underline{u}')d\underline{u}'.$$

Now, along a level surface³ $S_1 := \{v = 1\} \cap H_{\underline{u}}$ we can express both u and r as functions along S_0 which we denote by $U = U(f_0)$ and $R = R(f_0)$. In fact, since $v = ue^{f_0}$ we deduce $U = e^{-f_0}$. Moreover since according to (11) $\frac{dr}{du} = -1 + O(\delta^{1/2}r) = -1 + O(\delta^{1/2})$ we can write,

$$R = 1 - U + O(\delta^{1/2}) U$$

To have $\operatorname{tr} \chi'$ non-positive along S_{v_0} we need,

$$\frac{2}{R} + \frac{2U}{R^2} \left(-\Delta f_0 + \left[1 + U/R \left(1 + O(\delta^c) \right] |\nabla f_0|^2 \right] \right) \le \frac{1}{r^2} \left(M_0 - O(\delta^c) I_0 \right)$$

We deduce the following.

Corollary 3.9. A necessary condition for S_1 to be a trapped surface, is that,

$$-\Delta f_0 + \left[1 + U/R \left(1 + O(\delta^c)\right] |\nabla f_0|^2\right] + \frac{R}{U} \le \frac{1}{2U} \left(M_0 - O(\delta^c)I_0\right)$$
(44)

where,

$$U = e^{-f_0}, \qquad R = 1 - e^{-f_0} + O(\delta^{1/2}) e^{-f_0}$$

³with v the deformation function defined by (20)

Note that the inequality is only meaningful in the domain \mathcal{D} , i.e. for $U = e^{-f_0} \leq u_*$, or for δ sufficiently small,

$$R > 1 - u_* \tag{45}$$

We now re-express (44) with respect to $R = R(f_0)$. We have,

$$\nabla R = \frac{R}{df}(f_0)\nabla f_0$$

$$\Delta R = \frac{R}{df}(f_0)\Delta f_0 + \frac{d^2R}{d^2f}(f_0)|\nabla f_0|^2$$

On the other hand,

$$\frac{dR}{df}(f_0) = \frac{dr}{du} \cdot \frac{dU}{df} = -\nabla_u r \cdot e^{-f_0}$$
$$\frac{d^2R}{d^2f}(f_0) = \nabla_u^2 r \cdot e^{-f_0} + \nabla_u r e^{-f_0}$$

In view of formula (7) and the equation,

$$\nabla_3 \mathrm{tr}\underline{\chi} + \frac{1}{2} (\mathrm{tr}\underline{\chi})^2 = -2\underline{\omega} \mathrm{tr}\underline{\chi} - |\underline{\hat{\chi}}|^2$$

we deduce,

$$\nabla_{u}(r\nabla_{u}r) = \frac{1}{8\pi}\nabla_{u}\int_{S(u,\underline{u})}\Omega\mathrm{tr}\underline{\chi} = \frac{1}{8\pi}\int_{S(u,\underline{u})}\Omega\left(e_{3}(\Omega\mathrm{tr}\underline{\chi}) + \Omega\mathrm{tr}\underline{\chi}\mathrm{tr}\underline{\chi}\right)$$
$$= \frac{1}{16\pi}\int_{S(u,\underline{u})}\Omega^{2}\mathrm{tr}\underline{\chi}^{2} - \frac{1}{8\pi}\int_{S(u,\underline{u})}\Omega^{2}|\underline{\hat{\chi}}|^{2} = 1 + rO(\delta^{1/2})$$

Hence,

$$r\nabla_u^2 r + (\nabla_u r)^2 = \Omega^2 + rO(\delta^{1/2}) = 1 + O(\delta^{1/2})$$

from which we deduce,

$$r\nabla_u^2 r = O(\delta^{1/2}). \tag{46}$$

Hence,

$$\begin{aligned} |\nabla R|^2 &= |\nabla f_0|^2 e^{-2f_0} |\nabla_u r|^2 = |\nabla f_0|^2 e^{-2f_0} \left(1 + O(\delta^{1/2})\right) \\ \Delta R &= -\Delta f_0 e^{-f_0} \nabla_u r + \left(\nabla_u^2 r \cdot e^{-f_0} + \nabla_u r e^{-f_0}\right) |\nabla f_0|^2 \\ &= e^{-f_0} \Delta f_0 \left(1 + O(\delta^{1/2}) + (-1 + O(\delta^{1/2}) e^{-f_0} |\nabla f_0|^2 + R^{-1} e^{-f_0} |\nabla f_0|^2 O(\delta^{1/2}) \\ &= e^{-f_0} \left(\Delta f_0 - |\nabla f_0|^2\right) + O(\delta^{1/2}) \left(\Delta f_0 + (1 + R^{-1}) |\nabla f_0|^2\right) \end{aligned}$$

Thus,

$$\begin{aligned} |\nabla f_0|^2 &= e^{2f_0} |\nabla R|^2 + O(\delta^{1/2}) |\nabla f_0|^2 \\ \Delta f_0 &= e^{f_0} \Delta R + |\nabla f_0|^2 + O(\delta^{1/2}) (\Delta f_0 + (1 + R^{-1}) |\nabla f_0|^2) \\ &= e^{f_0} \Delta R + e^{-2f_0} |\nabla R|^2 + O(\delta^{1/2}) (\Delta f_0 + (1 + R^{-1}) |\nabla f_0|^2) \end{aligned}$$

Note that,

The left hand side of (44) becomes,

$$L = -\Delta f_0 + \left[1 + U/R \left(1 + O(\delta^c)\right)\right] |\nabla f_0|^2 + \frac{R}{U}$$

= $-e^{f_0} \Delta R - e^{-2f_0} |\nabla R|^2 + (1 + e^{-f_0} R^{-1}) e^{2f_0} |\nabla R|^2 + Re^{f_0}$
+ $O(\delta^c) R^{-1} e^{f_0} |\nabla R|^2 + O(\delta^{1/2}) \left(e^{f_0} \Delta R + e^{2f_0} |\nabla R|^2\right)$

Hence,

$$L = e^{f_0} \left[-\Delta R + R^{-1} |\nabla R|^2 (1 + O(\delta^c)) + R + O(\delta^{1/2}) (\Delta R + e^{f_0} |\nabla R|^2) \right]$$

The inequality (44) becomes,

$$-\Delta R + R^{-1} |\nabla R|^2 (1 + O(\delta^c)) + R + O(\delta^{1/2}) (\Delta R + e^{f_0} |\nabla R|^2 \le \frac{1}{2} (M_0 - O(\delta^c) I_0)$$

or,

$$-\Delta R + R^{-1} |\nabla R|^2 (1 + O(\delta^c)) + R \leq 2^{-1} M_0 + O(\delta^c) J$$

where J is a fixed smooth function depending only on $\nabla^2 R$ and ∇R . We deduce the following.

Proposition 3.10. A necessary condition such that S_1 is a trapped surface is that, for $\delta >$ sufficiently small there exists a smooth function R on $_0$ verifying $R > 1 - u_*$ and the differential inequality,

$$-\Delta R + (1 + O(\delta^c))R^{-1}|\nabla R|^2 + R \le 2^{-1}M_0 + O(\delta^c)J$$
(47)

To proceed we need to make the assumption $R \geq \delta^{-c/2}$. Hence, it suffices to prove the inequality:

$$-\Delta R + R^{-1} |\nabla R|^2 + R \le 2^{-1} M_0 + O(\delta^{c/2}) J$$

or, for δ sufficiently small,

$$-\Delta R + R^{-1} |\nabla R|^2 + R < 2^{-1} M_0.$$
(48)

In order that the initial surface, corresponding to R = 1, is not trapped we need $2^{-1}M_0 < 1$. We also note, by the maximum principle that,

$$\max R < 2^{-1} \max M_0$$

Thus,

$$1 - u_* < 2^{-1} \max_{S_0} M_0. \tag{49}$$

is a necessary condition for the formation of a trapped surface. Recall that u_* is the maximum of u for which our assumptions are satisfied in $\mathcal{D}(u, \delta)$. Is it sufficient?

Performing the transformation $R = e^{-\phi}$ we derive,

$$\Delta \phi + 1 < 2^{-1} M_0 e^{\phi}$$

4. Solutions to the deformation equation on a fixed sphere (S, γ) .

In this section we provide examples of solutions to our main deformation equation,

$$\Delta \phi + 1 < M e^{\phi} \tag{50}$$

on a smooth, compact, 2-dimensional Riemnannian manifold S, diffeomorphic to the standard sphere, with strictly positive Gaussian curvature K. We define r = r(S) such that $|S| = 4\pi r^2$ and define,

$$k_m = \min_{S} r^2 K, \qquad k_M = \max_{S} r^2 K$$

We consider geodesic balls $B(p, \epsilon) = B(p, \epsilon)$ for sufficiently small $\epsilon > 0$. We start by proving the following lemma.

Lemma 4.1. Given a ball $B(p, \epsilon) \subset S$, there exists a function w_{ϵ} , smooth outside the point p, such that

$$\Delta w_{\epsilon} + K = 4\pi \delta_p \tag{51}$$

where δ_p is the Dirac measure at p. Moreover, if λ denotes the distance function from p,

$$w_{\epsilon} = \chi_{\epsilon} \log \lambda + v \tag{52}$$

with $v \in C^{1,1-}(S)$, v(p) = 0, smooth in $S \setminus \{p\}$ and χ_{ϵ} a smooth cutoff function,

$$\begin{cases} \chi_{\epsilon} = 1 & on \quad B(p,\epsilon) \\ \chi_{\epsilon} = 0 & on \quad B(p,2\epsilon) \end{cases}$$

Assuming the lemma true we consider the cut-off function

$$\begin{cases} \varphi_{\epsilon} = 0 \quad \text{on} \quad B(p, \epsilon/2) \\ \varphi_{\epsilon} = 1 \quad \text{on} \quad B_{\epsilon}(p) \end{cases}$$

and define $w'_{\epsilon} = \varphi_{\epsilon} w_{\epsilon}$. Note that w'_{ϵ} verifies the following properties:

$$w'_{\epsilon} = 0, \qquad \text{on} \qquad B(p, \epsilon/2)$$

$$w'_{\epsilon} = \log \epsilon + O(1), \qquad \text{on} \qquad S \setminus B(p, \epsilon/2)$$

$$\nabla^2 w'_{\epsilon} = O(\epsilon^{-2} \log \epsilon) \qquad \text{on} \qquad S \setminus B(p, \epsilon/2)$$

$$\Delta w'_{\epsilon} + K = 0 \qquad \text{on} \qquad S \setminus B(p, \epsilon)$$
(53)

Consider now the function $w_{\epsilon} = \Lambda w'_{\epsilon}$, for a fixed constant Λ and observe that, on $S \setminus B(p, \epsilon)$, we must have, $\Delta w_{\epsilon} + 1 = -\Lambda K + 1 < 0$ provided that $\Lambda > k_m^{-1}$. Thus, with a fixed choice of $\Lambda > k_m^{-1}$ we have,

$$w_{\epsilon} = 0, \qquad \text{on} \qquad B(p, \epsilon/2)$$

$$w_{\epsilon} = \Lambda \log \epsilon + O(1), \qquad \text{on} \qquad S \setminus B(p, \epsilon/2)$$

$$\nabla^{2}w_{\epsilon} = O(\epsilon^{-2}\log \epsilon) \qquad \text{on} \qquad S \setminus B(p, \epsilon/2)$$

$$\Delta w_{\epsilon} + 1 < 0 \qquad \text{on} \qquad S \setminus B(p, \epsilon)$$
(54)

It remains to check under what conditions for M, the function w_{ϵ} verifies (50). Clearly, on $S \setminus B(p, \epsilon)$, (50) is trivially verified in view of the fact that $M \geq 0$. Now let $M_{\epsilon} = \inf_{B(p,\epsilon)} M$. Thus, for some constant C,

$$Me^{w_{\epsilon}} \geq M_{\epsilon}e^{w_{\epsilon}} \geq C\epsilon^{\Lambda}M_{\epsilon},$$

$$\Delta w_{\epsilon} + 1 = O(\epsilon^{2}\log\epsilon)$$

Hence, to have (50) verified in $B(p, \epsilon)$ we need,

$$O(\epsilon^{-2}\log\epsilon) < M_{\epsilon}\epsilon^{\Lambda}$$

This proves the following.

Proposition 4.2. Let $M_{\epsilon} = \min_{B(p,\epsilon)} M$ and let $\Lambda > (\min_S K)^{-1}$. Assume that, for some universal constant C > 0,

$$M_{\epsilon} > C \epsilon^{-2-\Lambda} \log \epsilon \tag{55}$$

Then, for sufficiently small $\epsilon > 0$, there exists a function ϕ_{ϵ} verifying the inequality (50) and such that

$$\min \phi_{\epsilon} > \log \epsilon + O(1) \tag{56}$$

$$|\nabla \phi_{\epsilon}| = O(\epsilon^{-1} \log \epsilon), \quad |\nabla^2 \phi_{\epsilon}| = O(\epsilon^{-2} \log \epsilon).$$
(57)

In remains to prove lemma 4.1. This is a standard argument, see for example chapter 2 in [?], which we sketch below.

Let λ be the geodesic distance function from p. In a neighborhood of p we can write,

$$ds^2 = d\lambda^2 + a^2(\lambda, \theta)d\theta^2, \qquad a(0) = 0, \frac{da}{d\lambda}(0) = 1.$$

Let h be the geodesic curvature of the level curves of λ , i.e. denoting, $e = \gamma(\partial_{\theta}, \partial_{\theta})^{-1/2} \partial_{\theta}$ the unit tangent vector to these curves,

$$h = \gamma(\nabla_e \partial_\lambda, e) = a^{-1} \partial_\lambda a$$

h verifies the second variation formula,

$$\partial_{\lambda}h = -h^2 - K$$

or,

 $\partial_{\lambda}^2 a + Ka = 0. \tag{58}$

Since $a(0) = 0, \frac{da}{d\lambda}(0) = 1$ we deduce from (58) that $\partial_{\lambda}^2 a(0) = 0$. Consequently,

$$a(\lambda) = \lambda + O(\lambda^3), \qquad \partial_{\lambda} a(\lambda) = 1 + O(\lambda^2), \quad h(\lambda) = \lambda^{-1} + O(\lambda)$$

Now,

$$\Delta \log \lambda = \lambda^{-1}h - \lambda^{-2} = O(1)$$

Thus, for $\delta < \epsilon$ converging to 0,

$$\int_{S \setminus B(p,\delta)} \Delta(\chi_{\epsilon} \log \lambda) dv_{\gamma} = -2\pi + O(\delta)^2$$

Hence, passing to the limit,

$$\int_{S} \Delta(\chi_{\epsilon} \log \lambda) dv_{\gamma} = -2\pi$$

Note also that,

$$\int_{S} \chi \Delta(\chi_{\epsilon} \log \lambda) dv_{\gamma} = -2\pi \chi(p)$$
(59)

for any smooth test function χ supported in $B(p, \epsilon)$.

We now solve the equation,

$$\Delta_S v = f. \tag{60}$$

where, f is the bounded function

$$\begin{cases} f = K + 2\Delta(\chi_{\epsilon} \log \lambda) & \text{on } S \setminus \{p\} \\ f = 0 & \text{at } p \end{cases}$$

Note that (60) admits a $C^{1,1}$ solution in view of the fact that $f \in L^{\infty}(S)$ and,

$$\int_{S} f dv_{\gamma} = \int_{S} K dv_{\gamma} + 2 \int_{S} \Delta(\chi_{\epsilon} \log \lambda) dv_{\gamma} = 4\pi - 4\pi = 0.$$

We can also normalized v such v(p) = 0. We now define,

$$w_{\epsilon} = 2\chi_{\epsilon}\log\lambda - v$$

and note that,

$$\Delta w_{\epsilon} + K = 0, \quad \text{on } S \setminus \{p\}$$

Moreover, in view of (59),

$$\Delta w_{\epsilon} + K = -4\pi\delta$$

as desired.

Remark 4.3. Note that the proof of the proposition only requires the existence of a smooth function w on S which verifies $\Delta w + 1 < 0$ in the complement of a closed domain D for which $\inf_D M : M_D > 0$. Indeed if such a function exists we can produce a solution to our inequality simply by taking $\phi = -\log s + w$ for a sufficiently small constant s > 0. Indeed, with such a choice (50) is automatically satisfied in the complement of D. In D, $\Delta \phi = \Delta w$, $e^{\phi} = s^{-1}e^{w}$ and therefore we need $\max_D \left[e^{-w}(\Delta w + 1)\right] < s^{-1}M_D$. Finally we note that such solutions can easily be constructed for balls $B(p, \delta)$ with $\delta < i_p$, the radius of injectivity of S at p.

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