

Rigid Multiview Varieties

Joe Kileel

University of California, Berkeley

January 9, 2016

Nonlinear Algebra

JMM, Seattle

arXiv:1509.03257



Michael Joswig



Bernd Sturmfels



André Wagner

Algebraic vision

Multiview geometry studies 3D scene reconstruction from images. Foundations in projective geometry. *Algebraic vision* bridges to algebraic geometry (combinatorial, computational, numerical, ...).



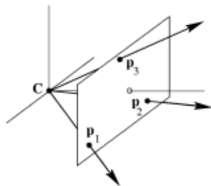
Oct 8–9, 2015, Berlin



May 2–6, 2016, San Jose

What is a camera?

A **camera** is a full rank 3×4 real matrix A .
Determines a projection $\mathbb{P}^3 \dashrightarrow \mathbb{P}^2$; $X \mapsto AX$



thought of as taking a picture.

A choice of point $C \in \mathbb{P}^3$ (center), plane $\pi \subset \mathbb{P}^3$ (viewing plane),
and coordinates on π gives a camera.

Multiview variety

Given n cameras $A = (A_1, \dots, A_n)$ in generic position, their **multiview variety** V_A is the closure of the image of the rational map:

$$\begin{array}{ccc} \mathbb{P}^3 & \dashrightarrow & \mathbb{P}^2 \times \mathbb{P}^2 \times \dots \times \mathbb{P}^2 \\ X & \mapsto & (A_1 X, A_2 X, \dots, A_n X). \end{array}$$

Given n cameras $A = (A_1, \dots, A_n)$ in generic position, their **multiview variety** V_A is the closure of the image of the rational map:

$$\begin{array}{ccc} \mathbb{P}^3 & \dashrightarrow & \mathbb{P}^2 \times \mathbb{P}^2 \times \dots \times \mathbb{P}^2 \\ X & \mapsto & (A_1 X, A_2 X, \dots, A_n X). \end{array}$$

- Space of n consistent views of one world point.

Given n cameras $A = (A_1, \dots, A_n)$ in generic position, their **multiview variety** V_A is the closure of the image of the rational map:

$$\begin{array}{ccc} \mathbb{P}^3 & \dashrightarrow & \mathbb{P}^2 \times \mathbb{P}^2 \times \dots \times \mathbb{P}^2 \\ X & \mapsto & (A_1 X, A_2 X, \dots, A_n X). \end{array}$$

- Space of n consistent views of one world point.
- Irreducible threefold isomorphic to \mathbb{P}^3 blown-up at n points.

Multiview variety

Given n cameras $A = (A_1, \dots, A_n)$ in generic position, their **multiview variety** V_A is the closure of the image of the rational map:

$$\begin{array}{ccc} \mathbb{P}^3 & \dashrightarrow & \mathbb{P}^2 \times \mathbb{P}^2 \times \dots \times \mathbb{P}^2 \\ X & \mapsto & (A_1 X, A_2 X, \dots, A_n X). \end{array}$$

- Space of n consistent views of one world point.
- Irreducible threefold isomorphic to \mathbb{P}^3 blown-up at n points.
- Prime ideal $I_A \subset \mathbb{R}[u_{i0}, u_{i1}, u_{i2} : i = 1, \dots, n]$ is \mathbb{Z}^n -multihomogeneous.

Equations

For which u_j and u_k , does:

$$\begin{cases} A_j X = \lambda_j u_j \\ A_k X = \lambda_k u_k \end{cases}$$

have a nonzero solution in X, λ_j, λ_k ? Rewrite as:

$$B^{jk} \begin{bmatrix} X \\ -\lambda_j \\ -\lambda_k \end{bmatrix} = 0 \quad \text{where} \quad B^{jk} := \begin{bmatrix} A_j & u_j & 0 \\ A_k & 0 & u_k \end{bmatrix}_{6 \times 6}$$

Equations

For which u_j and u_k , does:

$$\begin{cases} A_j X = \lambda_j u_j \\ A_k X = \lambda_k u_k \end{cases}$$

have a nonzero solution in X, λ_j, λ_k ? Rewrite as:

$$B^{jk} \begin{bmatrix} X \\ -\lambda_j \\ -\lambda_k \end{bmatrix} = 0 \quad \text{where} \quad B^{jk} := \begin{bmatrix} A_j & u_j & 0 \\ A_k & 0 & u_k \end{bmatrix}_{6 \times 6}$$

Theorem (Heyden-Aström 1997)

For $n \geq 4$, the $\binom{n}{2}$ bilinear forms $\det(B^{jk})$ where $1 \leq j < k \leq n$ cut out V_A set-theoretically.

Equations

For which u_j and u_k , does:

$$\begin{cases} A_j X = \lambda_j u_j \\ A_k X = \lambda_k u_k \end{cases}$$

have a nonzero solution in X, λ_j, λ_k ? Rewrite as:

$$B^{jk} \begin{bmatrix} X \\ -\lambda_j \\ -\lambda_k \end{bmatrix} = 0 \quad \text{where} \quad B^{jk} := \begin{bmatrix} A_j & u_j & 0 \\ A_k & 0 & u_k \end{bmatrix}_{6 \times 6}$$

Theorem (Heyden-Aström 1997)

For $n \geq 4$, the $\binom{n}{2}$ bilinear forms $\det(B^{jk})$ where $1 \leq j < k \leq n$ cut out V_A set-theoretically.

Theorem (Aholt-Sturmfels-Thomas 2013)

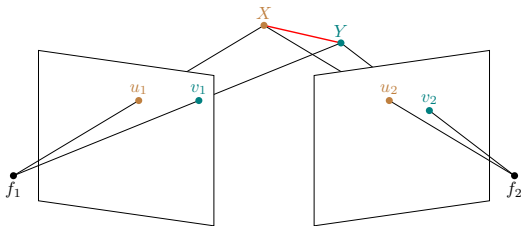
These $\binom{n}{2}$ bilinear forms and $\binom{n}{3}$ trilinear forms **minimally generate** I_A . Those and $\binom{n}{4}$ quadrilinear forms are a **universal Gröbner basis**.

Rigid multiview variety

Given n cameras $A = (A_1, \dots, A_n)$ in generic position, their **rigid multiview variety** W_A is the closure of the image of the rational map:

$$\begin{array}{ccc} V(Q) & \hookrightarrow & \mathbb{P}^3 \times \mathbb{P}^3 \quad \dashrightarrow & (\mathbb{P}^2)^n \times (\mathbb{P}^2)^n \\ (X, Y) & & \longmapsto & ((A_1 X, \dots, A_n X), (A_1 Y, \dots, A_n Y)), \end{array}$$

$$Q(X, Y) = (X_0 Y_3 - Y_0 X_3)^2 + (X_1 Y_3 - Y_1 X_3)^2 + (X_2 Y_3 - Y_2 X_3)^2 - X_3^2 Y_3^2.$$

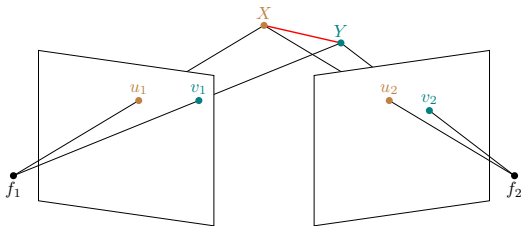


Rigid multiview variety

Given n cameras $A = (A_1, \dots, A_n)$ in generic position, their **rigid multiview variety** W_A is the closure of the image of the rational map:

$$\begin{array}{ccc} V(Q) & \hookrightarrow & \mathbb{P}^3 \times \mathbb{P}^3 \quad \dashrightarrow \quad (\mathbb{P}^2)^n \times (\mathbb{P}^2)^n \\ (X, Y) & \longmapsto & ((A_1 X, \dots, A_n X), (A_1 Y, \dots, A_n Y)), \end{array}$$

$$Q(X, Y) = (X_0 Y_3 - Y_0 X_3)^2 + (X_1 Y_3 - Y_1 X_3)^2 + (X_2 Y_3 - Y_2 X_3)^2 - X_3^2 Y_3^2.$$



Irreducible 5-fold inside $V_A \times V_A$. Prime ideal J_A in

$\mathbb{R}[u_{i0}, u_{i1}, u_{i2}, v_{i0}, v_{i1}, v_{i2} : i = 1, \dots, n]$ is \mathbb{Z}^{2n} -multihomogeneous.

Equations

Write $Q(X, Y) = T(X, X, Y, Y)$, where $T(\bullet, \bullet, \bullet, \bullet)$ is a quadrilinear form.

Theorem (Joswig-K.-Sturmfels-Wagner 2015)

The octics coming from two pairs of cameras:

$$T(\tilde{\Lambda}_5 B_{i_1}^{j_1 k_1}(u), \tilde{\Lambda}_5 B_{i_2}^{j_1 k_1}(u), \tilde{\Lambda}_5 C_{i_3}^{j_2 k_2}(v), \tilde{\Lambda}_5 C_{i_4}^{j_2 k_2}(v))$$

*cut out W_A as a subvariety of $V_A \times V_A$ **set-theoretically**. For this, 16 suffice.*

Triangulation

From two views of one world point X , recover X by intersecting back-projected lines. Works unless X is collinear with centers.

From two views of one world point X , recover X by intersecting back-projected lines. Works unless X is collinear with centers.

For $1 \leq j < k \leq n$ and $1 \leq i \leq 6$, let:

- $B^{jk}(u) = \begin{bmatrix} A_j & u_j & 0 \\ A_k & 0 & u_k \end{bmatrix}_{6 \times 6}$

From two views of one world point X , recover X by intersecting back-projected lines. Works unless X is collinear with centers.

For $1 \leq j < k \leq n$ and $1 \leq i \leq 6$, let:

- $B^{jk}(u) = \begin{bmatrix} A_j & u_j & 0 \\ A_k & 0 & u_k \end{bmatrix}_{6 \times 6}$
- $B_i^{jk}(u)$ be the 5×6 matrix that is $B^{jk}(u)$ with its i^{th} row removed

From two views of one world point X , recover X by intersecting back-projected lines. Works unless X is collinear with centers.

For $1 \leq j < k \leq n$ and $1 \leq i \leq 6$, let:

- $B^{jk}(u) = \begin{bmatrix} A_j & u_j & 0 \\ A_k & 0 & u_k \end{bmatrix}_{6 \times 6}$
- $B_i^{jk}(u)$ be the 5×6 matrix that is $B^{jk}(u)$ with its i^{th} row removed
- $\wedge_5 B_i^{jk}(u)$ be the height 6 column of signed maximal minors of $B_i^{jk}(u)$

From two views of one world point X , recover X by intersecting back-projected lines. Works unless X is collinear with centers.

For $1 \leq j < k \leq n$ and $1 \leq i \leq 6$, let:

- $B^{jk}(u) = \begin{bmatrix} A_j & u_j & 0 \\ A_k & 0 & u_k \end{bmatrix}_{6 \times 6}$
- $B_i^{jk}(u)$ be the 5×6 matrix that is $B^{jk}(u)$ with its i^{th} row removed
- $\wedge_5 B_i^{jk}(u)$ be the height 6 column of signed maximal minors of $B_i^{jk}(u)$
- $\tilde{\wedge}_5 B_i^{jk}(u)$ be the height 4 column consisting of the top of $\wedge_5 B_i^{jk}(u)$

From two views of one world point X , recover X by intersecting back-projected lines. Works unless X is collinear with centers.

For $1 \leq j < k \leq n$ and $1 \leq i \leq 6$, let:

- $B^{jk}(u) = \begin{bmatrix} A_j & u_j & 0 \\ A_k & 0 & u_k \end{bmatrix}_{6 \times 6}$
- $B_i^{jk}(u)$ be the 5×6 matrix that is $B^{jk}(u)$ with its i^{th} row removed
- $\wedge_5 B_i^{jk}(u)$ be the height 6 column of signed maximal minors of $B_i^{jk}(u)$
- $\tilde{\wedge}_5 B_i^{jk}(u)$ be the height 4 column consisting of the top of $\wedge_5 B_i^{jk}(u)$
- $C^{jk}(v)$, $C_i^{jk}(v)$, $\wedge_5 C_i^{jk}(v)$ and $\tilde{\wedge}_5 C_i^{jk}(v)$ be the analogs with v .

Equations

Write $Q(X, Y) = T(X, X, Y, Y)$, where $T(\bullet, \bullet, \bullet, \bullet)$ is a quadrilinear form.

Theorem (Joswig-K.-Sturmfels-Wagner 2015)

The octics coming from two pairs of cameras:

$$T(\tilde{\Lambda}_5 B_{i_1}^{j_1 k_1}(u), \tilde{\Lambda}_5 B_{i_2}^{j_1 k_1}(u), \tilde{\Lambda}_5 C_{i_3}^{j_2 k_2}(v), \tilde{\Lambda}_5 C_{i_4}^{j_2 k_2}(v))$$

*cut out W_A as a subvariety of $V_A \times V_A$ **set-theoretically**. For this, 16 suffice.*

Equations

Write $Q(X, Y) = T(X, X, Y, Y)$, where $T(\bullet, \bullet, \bullet, \bullet)$ is a quadrilinear form.

Theorem (Joswig-K.-Sturmfels-Wagner 2015)

The octics coming from two pairs of cameras:

$$T(\tilde{\lambda}_5 B_{i_1}^{j_1 k_1}(u), \tilde{\lambda}_5 B_{i_2}^{j_1 k_1}(u), \tilde{\lambda}_5 C_{i_3}^{j_2 k_2}(v), \tilde{\lambda}_5 C_{i_4}^{j_2 k_2}(v))$$

*cut out W_A as a subvariety of $V_A \times V_A$ **set-theoretically**. For this, 16 suffice.*

Sketch.

These octics vanish on W_A . Conversely:

Equations

Write $Q(X, Y) = T(X, X, Y, Y)$, where $T(\bullet, \bullet, \bullet, \bullet)$ is a quadrilinear form.

Theorem (Joswig-K.-Sturmfels-Wagner 2015)

The octics coming from two pairs of cameras:

$$T(\tilde{\Lambda}_5 B_{i_1}^{j_1 k_1}(u), \tilde{\Lambda}_5 B_{i_2}^{j_1 k_1}(u), \tilde{\Lambda}_5 C_{i_3}^{j_2 k_2}(v), \tilde{\Lambda}_5 C_{i_4}^{j_2 k_2}(v))$$

*cut out W_A as a subvariety of $V_A \times V_A$ **set-theoretically**. For this, 16 suffice.*

Sketch.

These octics vanish on W_A . Conversely:

- For $n \geq 3$, show one of $B_1^{12}, B_2^{12}, B_1^{13}, B_2^{13}$ has rank 5, similarly with C .

Write $Q(X, Y) = T(X, X, Y, Y)$, where $T(\bullet, \bullet, \bullet, \bullet)$ is a quadrilinear form.

Theorem (Joswig-K.-Sturmfels-Wagner 2015)

The octics coming from two pairs of cameras:

$$T(\tilde{\Lambda}_5 B_{i_1}^{j_1 k_1}(u), \tilde{\Lambda}_5 B_{i_2}^{j_1 k_1}(u), \tilde{\Lambda}_5 C_{i_3}^{j_2 k_2}(v), \tilde{\Lambda}_5 C_{i_4}^{j_2 k_2}(v))$$

*cut out W_A as a subvariety of $V_A \times V_A$ **set-theoretically**. For this, 16 suffice.*

Sketch.

These octics vanish on W_A . Conversely:

- For $n \geq 3$, show one of $B_1^{12}, B_2^{12}, B_1^{13}, B_2^{13}$ has rank 5, similarly with C .
- For $n = 2$, need special geometric argument because of world points collinear with centers. □

Conjecture (Joswig-K.-Sturmfels-Wagner 2015)

J_A is **minimally generated** by $\frac{4}{9}n^6 - \frac{2}{3}n^5 + \frac{1}{36}n^4 + \frac{1}{2}n^3 + \frac{1}{36}n^2 - \frac{1}{3}n$ polynomials, coming from two triples of cameras, and their number per symmetry class of degrees is:

$$(110..000..) : 1 \cdot 2 \binom{n}{2}$$

$$(220..220..) : 9 \cdot \binom{n}{2}^2$$

$$(111..000..) : 1 \cdot 2 \binom{n}{3}$$

$$(220..211..) : 3 \cdot 2n \binom{n}{2} \binom{n-1}{2}$$

$$(220..111..) : 3 \cdot 2 \binom{n}{2} \binom{n}{3}$$

$$(211..211..) : 1 \cdot n^2 \binom{n-1}{2}^2$$

$$(211..111..) : 1 \cdot 2n \binom{n-1}{2} \binom{n}{3}$$

$$(111..111..) : 1 \cdot \binom{n}{3}^2$$

Conjecture (Joswig-K.-Sturmfels-Wagner 2015)

J_A is **minimally generated** by $\frac{4}{9}n^6 - \frac{2}{3}n^5 + \frac{1}{36}n^4 + \frac{1}{2}n^3 + \frac{1}{36}n^2 - \frac{1}{3}n$ polynomials, coming from two triples of cameras, and their number per symmetry class of degrees is:

$$(110..000..) : 1 \cdot 2 \binom{n}{2}$$

$$(220..220..) : 9 \cdot \binom{n}{2}^2$$

$$(111..000..) : 1 \cdot 2 \binom{n}{3}$$

$$(220..211..) : 3 \cdot 2n \binom{n}{2} \binom{n-1}{2}$$

$$(220..111..) : 3 \cdot 2 \binom{n}{2} \binom{n}{3}$$

$$(211..211..) : 1 \cdot n^2 \binom{n-1}{2}^2$$

$$(211..111..) : 1 \cdot 2n \binom{n-1}{2} \binom{n}{3}$$

$$(111..111..) : 1 \cdot \binom{n}{3}^2$$

Computational proof.

Up to $n = 5$, when there are 4940 minimal generators. □

Generalizations

- Images of four coplanar world points.
- Images of rigid world triangles.
- Proposed approach to images of unlabeled world points.

References

- [1] C. Aholt, B. Sturmfels and R. Thomas: *A Hilbert scheme in computer vision*, Canadian Journal of Mathematics **65** (2013) 961–988.
- [2] D. Grayson and M. Stillman: *Macaulay2, a software system for research in algebraic geometry*, available at www.math.uiuc.edu/Macaulay2/.
- [3] R. Hartley and A. Zisserman: *Multiple View Geometry in Computer Vision*, Cambridge University Press, 2003.
- [4] A. Heyden and K. Åström: *Algebraic properties of multilinear constraints*, Mathematical Methods in the Applied Sciences **20** (1997) 1135–1162.
- [5] M. Joswig, J. Kileel, B. Sturmfels and A. Wagner: *Rigid Multiview Varieties*, arXiv:1509.032571.
- [6] B. Li: *Images of rational maps of projective spaces*, arXiv:1310.8453.
- [7] E. Miller and B. Sturmfels: *Combinatorial Commutative Algebra*, Graduate Texts in Mathematics, Springer Verlag, New York, 2004.

Thank you!